### **ASSIGNMENT 4**

### Ultrasonic sensor simulation in Wokwi

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### **Question:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

#### Code:

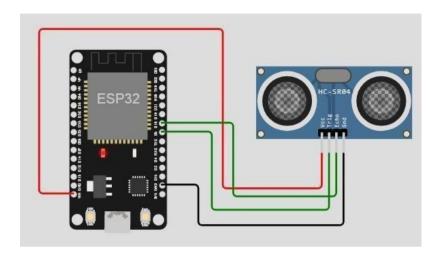
```
char subscribetopic[] = "iot-
2/cmd/test/fmt/String"; char authMethod[] = "use-
token-auth":
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback
,wifiClient); const int trigPin = 5;
const int echoPin =
18; #define SOUND SPEED
0.034long duration;
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin,
OUTPUT);
pinMode(echoPin,
INPUT); wificonnect();
mqttconnect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin,
HIGH); distance = duration *
SOUND SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
```

```
if(distance<100)</pre>
Serial.println("ALERT!!"
); delay(1000);
  PublishData(distanc
  e); delay(1000);
  if (!client.loop())
  {mqttconnect();
  delay(1000);
  void PublishData(float
  dist) {mqttconnect();
  String payload =
  "{\"Distance\":";payload +=
  dist;
  payload += ",\"ALERT!!\":""\"Distance less than
  100cms\""; payload += "}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c str())) {
  Serial.println("Publish ok");
  } else {
  Serial.println("Publish failed");
  }
  void mqttconnect() {
  if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
  while (!!!client.connect(clientId, authMethod, token)) {
```

```
Serial.print(".
   "); delay(500);
initManagedDevice();
Serial.println();
void wificonnect()
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() !=WL_CONNECTED) { delay(500);
Serial.print(".");
Serial.println(""); Serial.println("WiFi
connected"); Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe tocmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
   //Serial.print((char)payload[i
```

```
]);data3 += (char)payload[i];
Serial.println("data: "+
data3);data3="";
Diagram.json:
  "version": 1,
 "author":
 "sweetysharon",
 "editor": "wokwi",
 "parts": [
   { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
   { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
  "connections": [
   [ "esp:TX0", "$serialMonitor:RX", "", [] ],
   [ "esp:RX0", "$serialMonitor:TX", "",
   []],[
     "esp:VIN",
     "ultrasonic1:VCC",
     "red",
     [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
   [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
   [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
   [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
}
```

# **Circuit Diagram:**



# **Output:**

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.92
Distance (cm): 399.94
```

# **IBM cloud output:**

