

ASSIGNMENT-1

Smart Home automation using IOT

Assignment Date	15 September 2022
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Maximum Marks	2 Marks

Code:

```
#include<Servo.h>

const int pingPin = 7;

int servoPin = 8;

Servo servo1;

void setup() {
  // initialize serial communication:
  Serial.begin(9600);

  servo1.attach(servoPin);

  pinMode(2,INPUT);
  pinMode(4,OUTPUT);
  pinMode(11,OUTPUT);
  pinMode(12,OUTPUT);
  pinMode(13,OUTPUT);
  pinMode(A0,INPUT);
  digitalWrite(2,LOW);
  digitalWrite(11,HIGH);
}

void loop() {
  long duration, inches, cm;

  pinMode(pingPin, OUTPUT);
  digitalWrite(pingPin, LOW);
```

```
delayMicroseconds(2);
digitalWrite(pingPin, HIGH);
delayMicroseconds(5);
digitalWrite(pingPin, LOW);
// The same pin is used to read the signal from the PING))) a HIGH pulse
// whose duration is the time (in microseconds) from the sending of the ping
// to the reception of its echo off of an object.
pinMode(pingPin, INPUT);
duration = pulseIn(pingPin, HIGH);
// convert the time into a distance
inches = microsecondsToInches(duration);
cm = microsecondsToCentimeters(duration);
//Serial.print(inches);
//Serial.print("in, ");
//Serial.print(cm);
//Serial.print("cm");
//Serial.println();
//delay(100);
servo1.write(0);
if(cm < 40)
{
servo1.write(90);
delay(2000);
}
else
{
servo1.write(0);
}
```

```
// PIR with LED starts
int pir = digitalRead(2);
if(pir == HIGH)
{
    digitalWrite(4,HIGH);
    delay(1000);
}
else if(pir == LOW)
{
    digitalWrite(4,LOW);
}

//temp with fan
float value=analogRead(A0);
float temperature=value*0.48;
Serial.println("temperature");
Serial.println(temperature);
if(temperature > 20)
{
    digitalWrite(12,HIGH);
    digitalWrite(13,LOW);
}
else
{
    digitalWrite(12,LOW);
    digitalWrite(13,LOW);
}
}

long microsecondsToInches(long microseconds) {
```

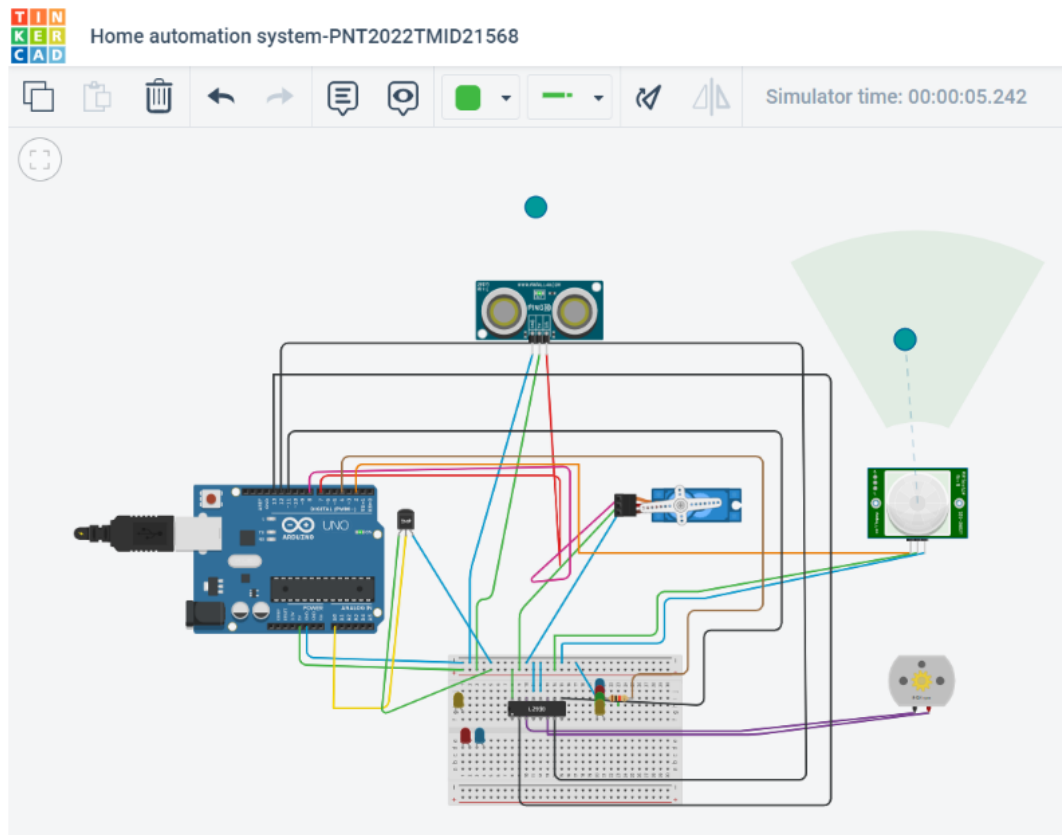
```

return microseconds / 74 / 2;
}

long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
}

```

Screenshot:



Demo Link:

<https://drive.google.com/drive/folders/1bgoweJSot9QGMMDvvVlm9jXsCRfFolZ>