

ASSIGNMENT

INDUSTRY – SPECIFIC INTELLIGENT FIRE MANAGEMENT SYSTEM

TEAM MEMBERS

19C011 – BHAGYALAKSHMI T

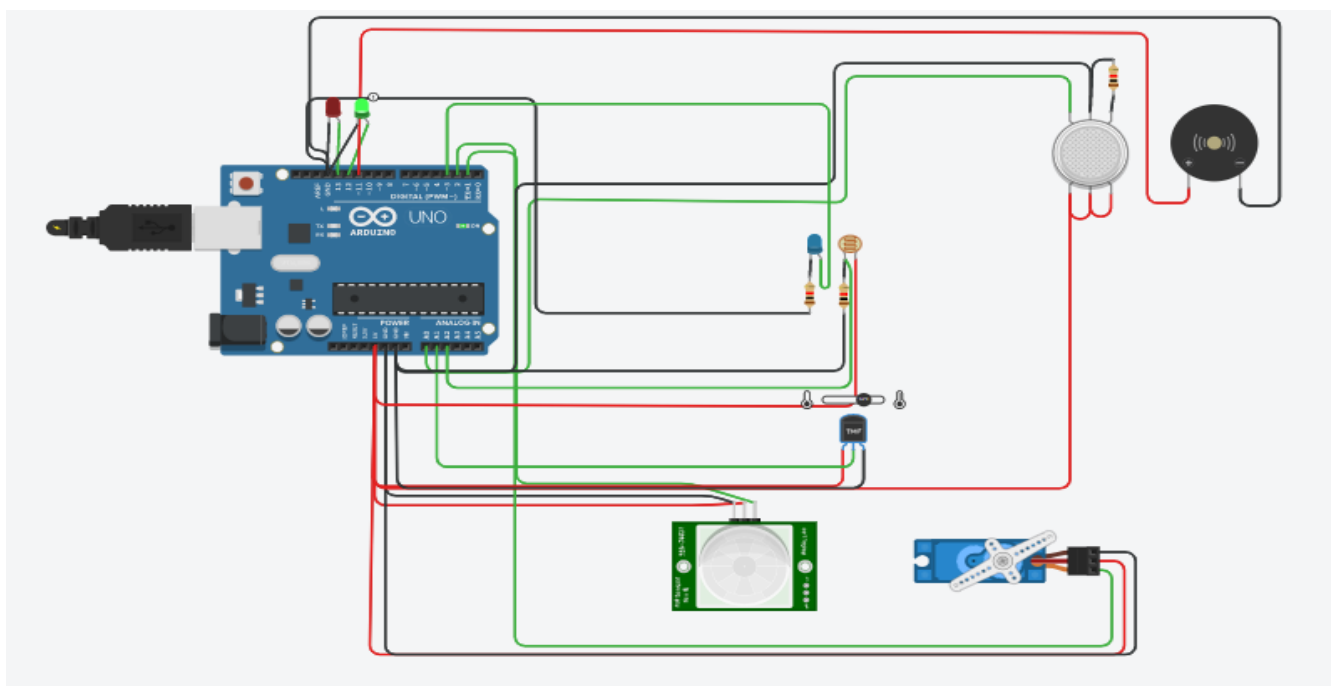
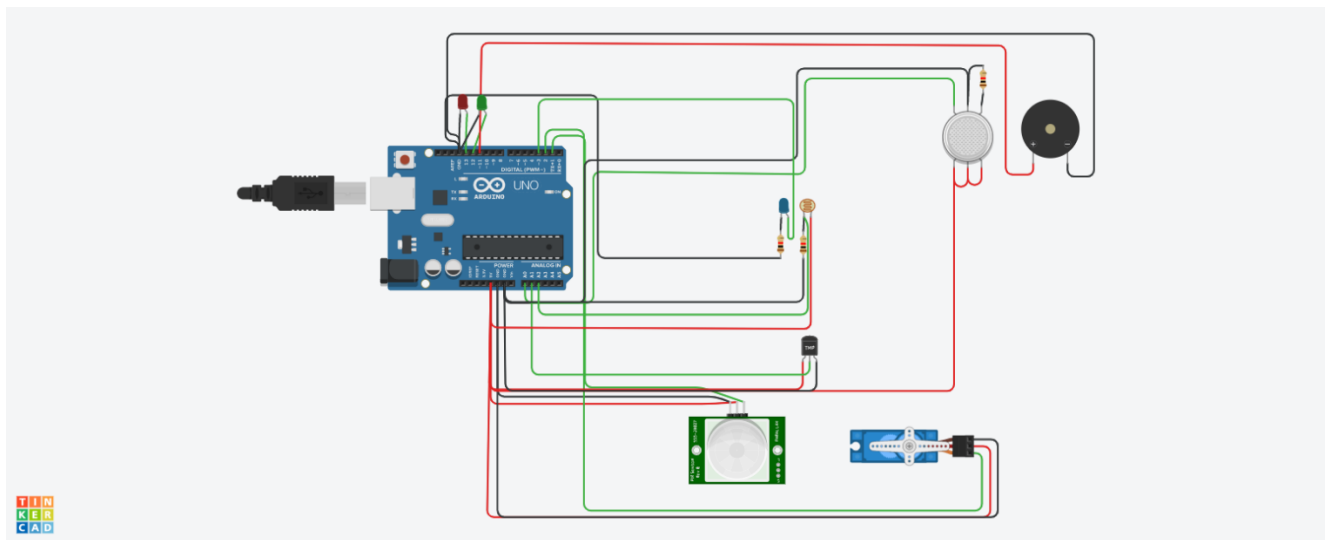
19C036 – HARSINI A M

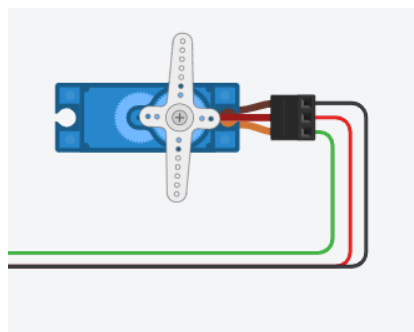
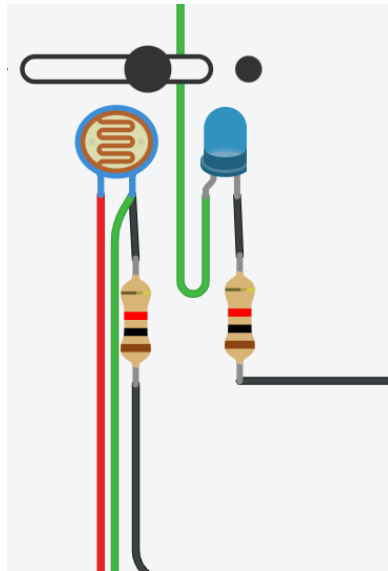
19C047 – LAKSHMI SREE S

19C052 – MADHUMITHA P R

SIMULATION OF SMART HOME AUTOMATION IN TINKERCAD:

WORKING SCREENSHOTS:





SERIAL MONITOR

```
Smoke sensor's value is :266
Raw reading - 153
The temperature reading of the room in Celcius is :24
The values of sensor are :
425
Smoke sensor's value is :266
Raw reading - 153
The temperature reading of the room in Celcius is :24
The values of sensor are :
425
Smoke sensor's value is :266
Raw reading - 153
The temperature reading of the room in Celcius is :24
The values of sensor are :
425
Smoke sensor's value is :266
Raw reading - 153
The temperature reading of the room in Celcius is :2
```

CODE:

//HOME AUTOMATION

/*

USE OF PIR SENSOR:

If motion is detected, servo motor(Indication door) would be opened)

USE OF SMOKE SENSOR:

If smoke value detected by sensor is greater than 200, buzzer would ring

USE OF TEMPERATURE SENSOR:

If temperature value read by sensor is greater than 40 degree celcius, buzzer would ring

USE OF Photoresistor:

Based on the light intensity read from sensor we can change the brigtness of the Blue LED

*/

```
#include<Servo.h>
```

```
int pos1;
```

```
Servo s;
```

```
int smokethres = 150;
```

```
int temp = 0;
```

```
int threshold = 550;
```

```
int sensor_value = 0;
```

```
int led = 0;
```

```
void setup()
```

```
{
```

```
  Serial.begin(9600);
```

```
  pinMode(1,INPUT);
```

```
  pinMode(A0,INPUT);
```

```
  pinMode(A1, INPUT);
```

```
  pinMode(A2, INPUT);
```

```
  pinMode(12,OUTPUT);
```

```
  pinMode(13,OUTPUT);
```

```
  pinMode(11,OUTPUT);
```

```
  pinMode(3,OUTPUT);
```

```
  s.attach(2);
```

```
}
```

```
void loop(){
```

```
  if(digitalRead(1)== HIGH)
```

```
  {
```

```
    digitalWrite(12,HIGH);
```

```

digitalWrite(13,LOW);
for(pos1 = 0; pos1 <= 90; pos1 += 1)
{
    s.write(pos1);
    delay(15);
}
delay(1000);

for(pos1 = 90; pos1>=0; pos1 -=1)
{
    s.write(pos1);
    delay(15);
}
}
else if(digitalRead(1)== LOW)
{
    digitalWrite(13,HIGH);
    digitalWrite(12,LOW);
}

int sensorvalue = analogRead(A0);
Serial.print("Smoke sensor's value is :");
Serial.println(sensorvalue);

if(sensorvalue < 200)
{
    digitalWrite(11,LOW);

}
else if(sensorvalue > 200)
{
    digitalWrite(11,HIGH);
}

temp = analogRead(A1);
Serial.print("Raw reading - ");
Serial.println(temp);
temp = -40 + 0.488155 * (analogRead(A1) - 20);
Serial.print("The temperature reading of the room in Celcius is :");
Serial.println(temp);

if(temp < 40)
{

```

```
    digitalWrite(11,LOW);  
  
    }  
    else if(temp > 40)  
    {  
        digitalWrite(11,HIGH);  
    }  
  
    //Photoresistor to LED mapping  
    sensor_value = analogRead(A2);  
    Serial.println("The values of sensor are :");  
    Serial.println(sensor_value);  
  
    led = map(sensor_value,0,1023,0,255);  
        delay(100);  
    if(sensor_value < threshold)  
    {  
        analogWrite(3,led);  
  
    }  
    else if(sensor_value > threshold)  
    {  
        analogWrite(3,LOW);  
  
    }  
}
```