Assignment - 4

Assignment Date	20 October 2022
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Maximum Marks	2 Marks

Question :

Write a code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send “alert” to ibm cloud and display in device recent events.

Solution :

(Link >>>https://wokwi.com/projects/347296217300992594**)**

Code in Wokwi :

(sketch.ino)

```
#include<WiFi.h>//library for wifi
#include<PubSubClient.h>//library for MQtt


voidcallback(char* subscribetopic, byte* payload, unsignedintpayloadLength);


// credentials of IBM Accounts
#defineORG "lz4ll"//IBM Organition ID
#defineDEVICE_TYPE "KishorIoT"//Device type mentioned in ibm watson IOT Platform
#defineDEVICE_ID "22022002"//Device ID mentioned in ibm watson IOT Platform
#defineTOKEN "98765432"//Token
Stringdata3;


// Customise the above values
charserver[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
charpublishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and format in which data to be send
charsubscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type
AND COMMAND IS TEST OF FORMAT STRING
charauthMethod[] = "use-token-auth";// authentication method
chartoken[] = TOKEN;
charclientId[] = "d:"ORG ":"DEVICE_TYPE ":"DEVICE_ID;// client id


WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined
client id by passing parameter like server id,portand wificredential
constinttrigpin = 5;
constintechopin = 18;
```

```
constintledpin = 2;

longduration ;
floatdistance;
#definesound_speed 0.034
voidsetup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, OUTPUT);
  pinMode(ledpin, OUTPUT);
  wificonnect();
  mqttconnect();
}


voidloop()
{
  digitalWrite(trigpin, LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin, LOW);
  duration= pulseIn(echopin,HIGH);
  distance = duration * sound_speed /2;
  if(distance<=100)
  {
    PublishData(distance);
    delay(1000);
    if(!client.loop())
    {
      mqttconnect();
    }
    digitalWrite(ledpin, HIGH);
    Serial.println("Alert !!");
    Serial.println(distance);
  }
  else
  {
    digitalWrite(ledpin, LOW);
  }
  delay(10); // this speeds up the simulation
}


// Retrieving to Cloud


voidPublishData(floatdistance)
{
  mqttconnect();// Function call for connecting to ibm
  // creating the String in in form JSon to update the data to ibm cloud
  Stringpayload = "{\"Alert !! \": ";
  payload += distance;
  payload += "}";
  Serial.print("Sending payload : ");
  Serial.println(payload);
```

```
  if(client.publish(publishTopic, (char*) payload.c_str()))
  {
    Serial.println("Publish ok");// If it sucessfully upload data on the cloud then
it will print publish ok in Serial monitor or else it will print publish failed
  }
  else
  {
    Serial.println("Publish failed");
  }
}


voidmqttconnect()
{
  if(!client.connected())
  {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while(!!!client.connect(clientId, authMethod, token))
    {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}


voidwificonnect() // Function defination for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);// Passing the wifi credentials to establish the
connection
  while(WiFi.status() != WL_CONNECTED)
  {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}


voidinitManagedDevice()
{
  if(client.subscribe(subscribetopic))
  {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  }
  else
  {
```

```
    Serial.println("subscribe to cmd FAILED");
  }
}


voidcallback(char* subscribetopic, byte* payload, unsignedintpayloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for(inti = 0; i < payloadLength; i++)
  {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
  if(data3=="lighton")
  {
      Serial.println(data3);
  }
  else
  {
      Serial.println(data3);
  }
data3="";
}
```

(diagram.json)

```
{
  "version": 1,
  "author": "044 M. kishor",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 35.33, "left": -109.33,
"attrs": {} },
    {
      "type": "wokwi-hc-sr04",
      "id": "ultrasonic1",
      "top": -61.7,
      "left": 78.5,
      "attrs": { "distance": "164"}
    },
    {
      "type": "wokwi-led",
      "id": "led1",
      "top": 134.3,
      "left": 195.16,
      "attrs": { "color": "red"}
    },
    {
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 214.96,
      "left": 65.17,
      "attrs": { "value": "1000"}
    }
```

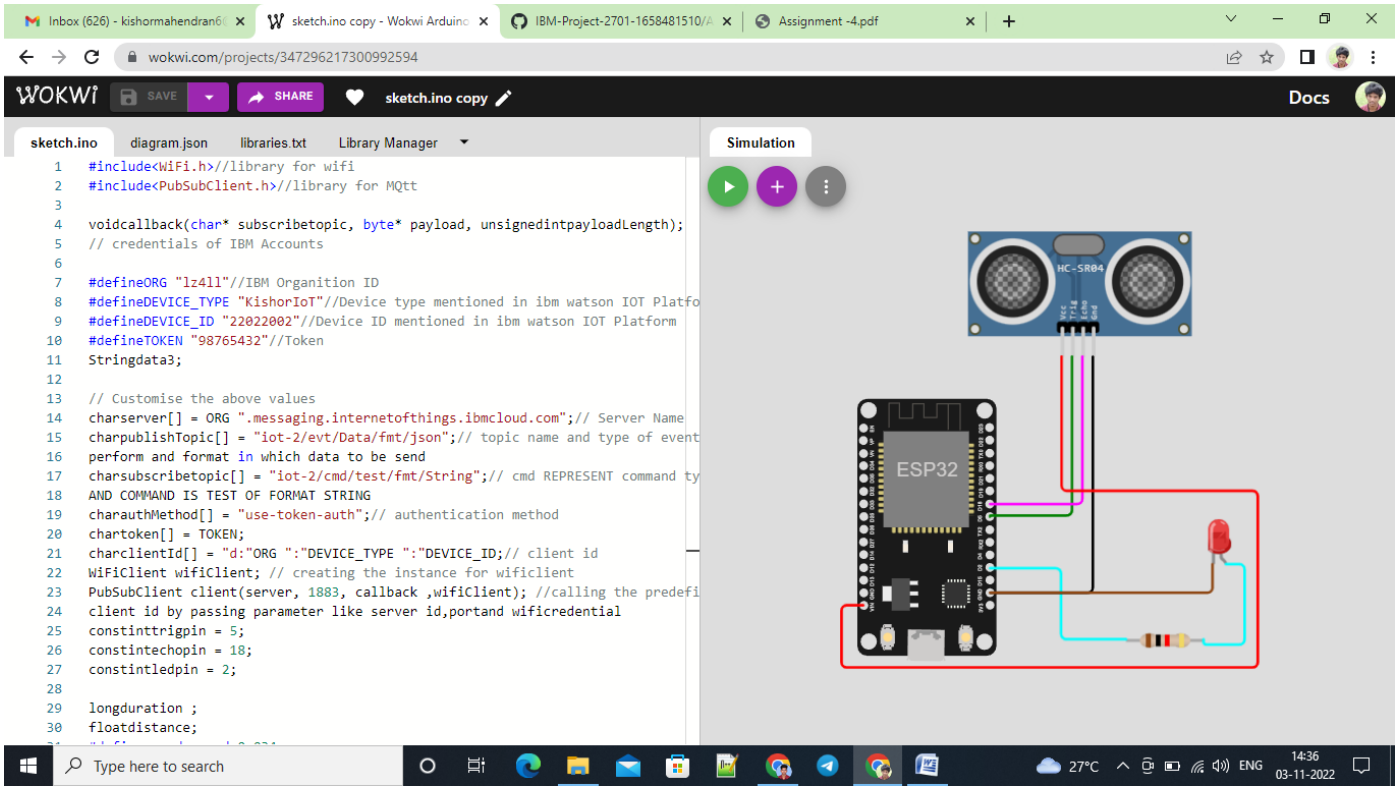
```
  ],
  "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
    [ "led1:A", "r1:2", "red", [ "v49.07", "h-96.19"] ],
    [ "r1:1", "esp:D2", "red", [ "v1.41", "h-48", "v-59.64"] ],
    [ "led1:C", "esp:GND.1", "black", [ "v31.74", "h-36.99", "v-23.71"] ],
    [
      "ultrasonic1:VCC",
      "esp:VIN",
      "red",
      [ "v28.57", "h-132.45", "v-48", "h-152", "v182", "h29.84"]
    ],
    [ "esp:D5", "ultrasonic1:TRIG", "blue", [ "h0"] ],
    [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h0"] ],
    [ "ultrasonic1:GND", "esp:GND.1", "black", [ "v0"] ]
  ]
}
```

(libraries.txt)

```
# Wokwi Library List
# See https://docs.wokwi.com/guides/libraries

PubSubClient
```

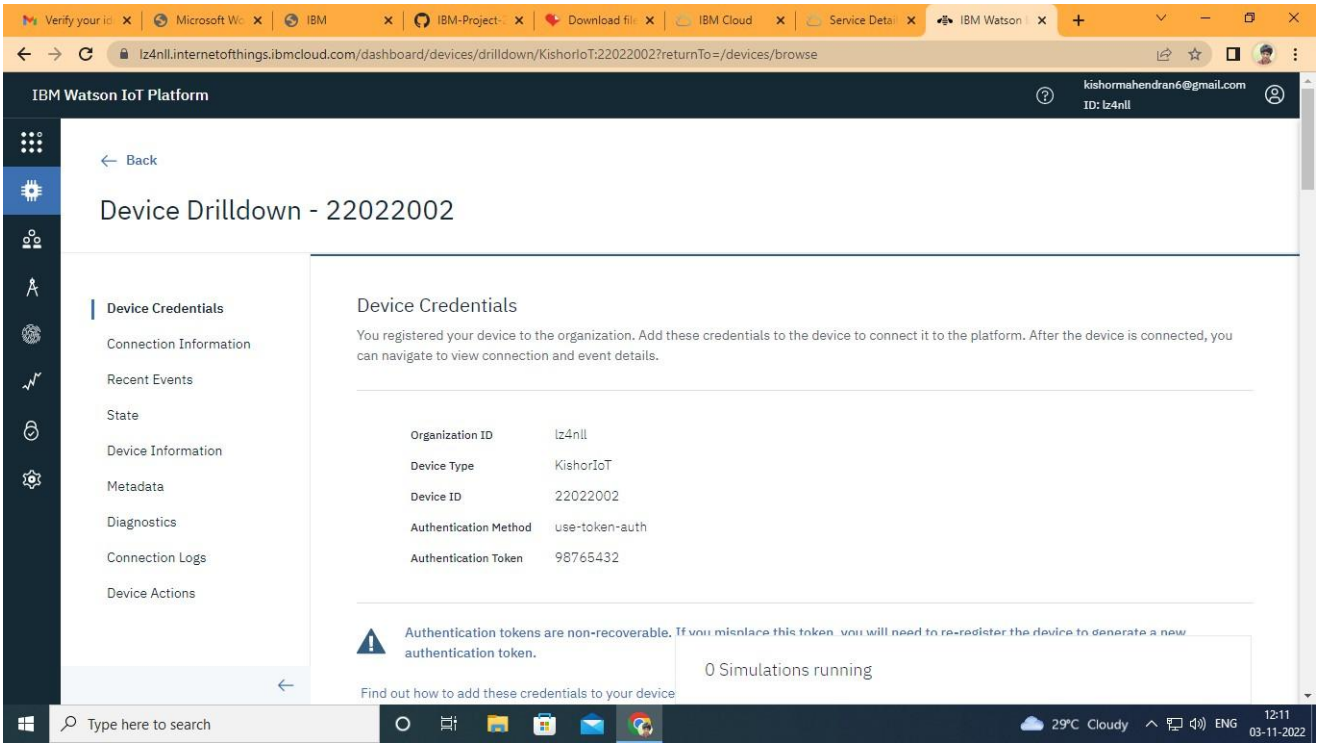
<u>Wokwi Sketch and Simulation</u> :

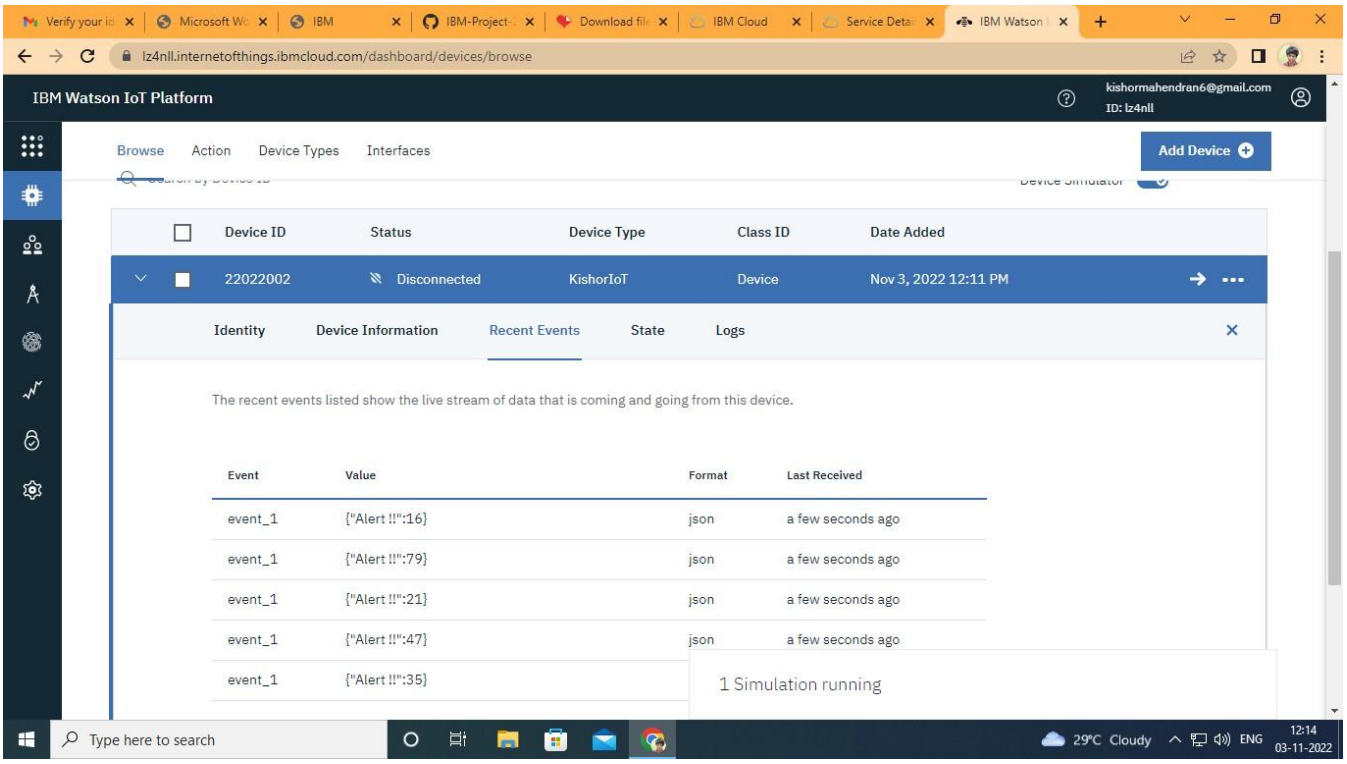


```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

Add a new device in IBM Cloud & Output in IBM Cloud (Watson Platform) :





Conclusion :

Whenever the distance is less than 100 cms send an "Alert" to the IBM cloud and display in the device **Recent Events**.