PROJECT DEVELOPMENT PHASE

CODING

Date	14 November 2022
Team ID	PNT2022TMID33136
Project Name	Virtual Eye – Life Guard For Swimming Pools To
	Detect Active Drowning
Max Marks	2 Marks

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APP.PY:
# import necessary packages
import cylib as cy
from cvlib.object_detection import draw_bbox
import cv2
import time
import numpy as np
import math
import argparse
def getFaceBox(net, frame,conf_threshold = 0.75):
frameOpencvDnn = frame.copy()
frameHeight = frameOpencvDnn.shape[0]
frameWidth = frameOpencvDnn.shape[1]
blob = cv2.dnn.blobFromImage(frameOpencvDnn,1.0,(300,300),[104, 117, 123], True,
False)
net.setInput(blob)
detections = net.forward()
bboxes = []
for i in range(detections.shape[2]):
confidence = detections[0,0,i,2]
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if confidence > conf_threshold:
x1 = int(detections[0,0,i,3]* frameWidth)
y1 = int(detections[0,0,i,4]* frameHeight)
x2 = int(detections[0,0,i,5]* frameWidth)
y2 = int(detections[0,0,i,6]* frameHeight)
bboxes.append([x1,y1,x2,y2])
cv2.rectangle(frameOpencvDnn,(x1,y1),(x2,y2),(0,255,0),int(round(frameHeight/150)),8)
return frameOpencvDnn, bboxes
faceProto = "opencv_face_detector.pbtxt"
faceModel = "opencv_face_detector_uint8.pb"
ageProto = "age_deploy.prototxt"
ageModel = "age_net.caffemodel"
genderProto = "gender_deploy.prototxt"
genderModel = "gender_net.caffemodel"
MODEL_MEAN_VALUES = (78.4263377603, 87.7689143744, 114.895847746)
ageList = ['(0-2)', '(4-6)', '(8-12)', '(15-20)', '(21-24)', '(25-32)', '(38-43)', '(48-53)', '(60-100)']
genderList = ['Male', 'Female']
#load the network
ageNet = cv2.dnn.readNet(ageModel,ageProto)
genderNet = cv2.dnn.readNet(genderModel, genderProto)
faceNet = cv2.dnn.readNet(faceModel, faceProto)
# open webcam
webcam = cv2.VideoCapture(0)
padding = 20
if not webcam.isOpened():
print("Could not open webcam")
exit()
t0 = time.time() #gives time in seconds after 1970
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#print('t0=',t0)
#variable dcount stands for how many seconds the person has been standing still for
centre0 = np.zeros(2)
isDrowning = False
#this loop happens approximately every 1 second, so if a person doesn't move,
#or moves very little for 10seconds, we can say they are drowning
# loop through frames
while webcam.isOpened():
# read frame from webcam
status, frame = webcam.read()
if not status:
break
\#small\_frame = cv2.resize(frame,(0,0),fx = 0.5,fy = 0.5)
# apply object detection
bbox, label, conf = cv.detect_common_objects(frame, confidence=0.25,
model='yolov3-tiny')
print(bbox, label, conf)
if(len(bbox)>0):
bbox0 = bbox[0]
#centre = np.zeros(s)
centre = [0,0]
#for i in range(0, len(bbox)):
#centre[i] =[(bbox[i][0]+bbox[i][2])/2,(bbox[i][1]+bbox[i][3])/2]
centre = [(bbox0[0]+bbox0[2])/2,(bbox0[1]+bbox0[3])/2]
#make vertical and horizontal movement variables
hmov = abs(centre[0]-centre0[0])
vmov = abs(centre[1]-centre0[1])
#there is still need to tweek the threshold
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#this threshold is for checking how much the centre has moved
x=time.time()
threshold = 10
#print("hmov=",hmov)
if(hmov>threshold or vmov>threshold):
print(x-t0, 'sif')
t0 = time.time()
isDrowning = False
else:
print(x-t0, 'selse')
if((time.time() - t0) > 10):
isDrowning = True
small\_frame = cv2.resize(frame,(0,0),fx = 0.5,fy = 0.5)
frameFace ,bboxes = getFaceBox(faceNet,small_frame)
if not bboxes:
print("No face Detected, Checking next frame")
continue
for bbox in bboxes:
face = small_frame[max(0,bbox[1]-
padding):min(bbox[3]+padding,frame.shape[0]-1),
max(0,bbox[0]-padding):min(bbox[2]+padding, frame.shape[1]-1)]
blob = cv2.dnn.blobFromImage(face, 1.0, (227, 227),
MODEL_MEAN_VALUES, swapRB=False)
genderNet.setInput(blob)
genderPreds = genderNet.forward()
gender = genderList[genderPreds[0].argmax()]
print("Gender: {}, conf = {:.3f}".format(gender, genderPreds[0].max()))
ageNet.setInput(blob)
agePreds = ageNet.forward()
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age = ageList[agePreds[0].argmax()]
print("Age Output : {}".format(agePreds))
print("Age : {}, conf = {:.3f}".format(age, agePreds[0].max()))
label = "{},{}".format(gender, age)
cv2.putText(frameFace, label, (bbox[0], bbox[1]-10),
cv2.FONT_HERSHEY_SIMPLEX, 0.8, (0, 255, 255), 2, cv2.LINE_AA)
cv2.imshow("Age Gender Demo", frameFace)
print("time : {:.3f}".format(time.time() - t0))
#print("Entered in to true")
#print('bounding box: ', bbox, 'label: ' label ,'confidence: ' conf[0], 'centre: ', centre)
#print(bbox,label ,conf, centre)
print('bbox: ', bbox, 'centre:', centre, 'centre0:', centre0)
print('Is he/she drowning: ', isDrowning)
#print('End of the program')
centre0 = centre
# draw bounding box over detected objects
# draw bounding box over detected objects
out = draw_bbox(frame, bbox, label, conf, write_conf=True)
# display output
cv2.imshow("Real-time object detection", out)
# press "Q" to stop
if cv2.waitKey(1) \& 0xFF == ord('q'):
break
# release resources
webcam.release()
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cv2.destroyAllWindows()