

**Project Development Phase**  
**Project Development Delivery of Sprint 1**

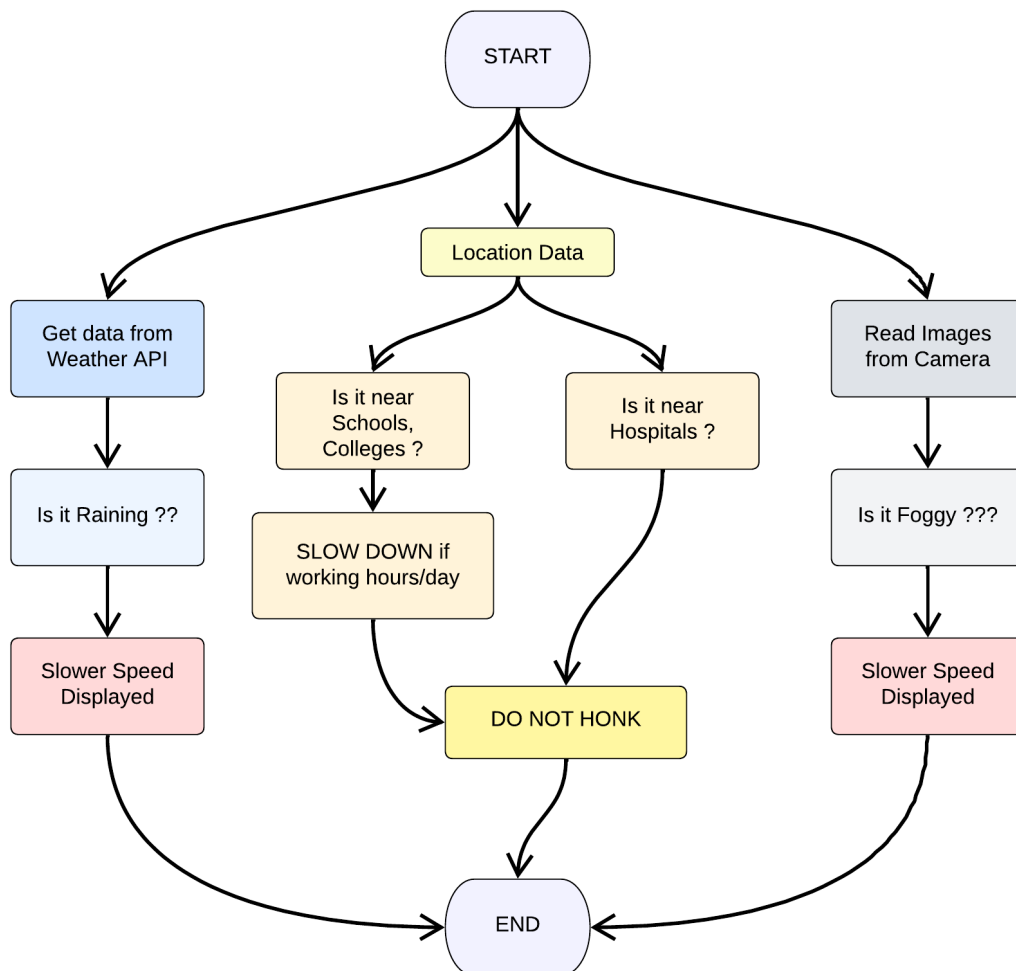
Date	07 September 2022
Team ID	PNT2022TMIDI3488
Project Name	Project - Signs with smart connectivity for Better road safety
Maximum Marks	4 Marks

**Signs with smart connectivity for Better road safety**

**Sprint Goals :**

1. Create and initialize accounts in various public APIs like OpenWeather API
2. Write a Python program that outputs results given the inputs like weather and location.

**Code Flow :**



**Program Code :**

**weather.py**

```

# Python code
import requests as reqs
def get(myLocation, APIKEY):
    apiURL = f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
        "temperature" : responseJSON['main']['temp'] - 273.15,
        "weather" : [responseJSON['weather'][_]['main'].lower()
            for _ in range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in percentage where 10km is
            100% and 0km is 0%
    }
    if("rain" in responseJSON):
        returnObject["rain"] = [responseJSON["rain"][key] for key in responseJSON["rain"]]
    return(returnObject)

```

### **brain.py**

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```

# Python code
# IMPORT SECTION STARTS
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
# -----
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation, APIKEY, localityInfo):
    weatherData = weather.get(myLocation, APIKEY)
    finalSpeed = localityInfo["usualSpeedLimit"]
    if "rain" not in weatherData else localityInfo["usualSpeedLimit"]/2
    finalSpeed = finalSpeed if weatherData["visibility"] > 35 else finalSpeed/2
    if (localityInfo["hospitalsNearby"]):
        # hospital zone
        doNotHonk = True
    else:
        if (localityInfo["schools"]["schoolZone"] == False):
            # neither school nor hospital zone
            doNotHonk = False
        else:

```

```

# school zone
now= [dt.now().hour,dt.now().minute]
activeTime= [list(map(int,_split(":"))) for _ in localityInfo["schools"]["activeTime"]]
doNotHonk=activeTime[0][0]<=now[0]<=activeTime[1][0]
andactiveTime[0][1]<=now[1]<=activeTime[1][1]
return({
"speed" : finalSpeed,
"doNotHonk" : doNotHonk
})
# UTILITY LOGIC SECTION ENDS

```

### **main.py**

The code that runs in a forever loop in the microcontroller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```

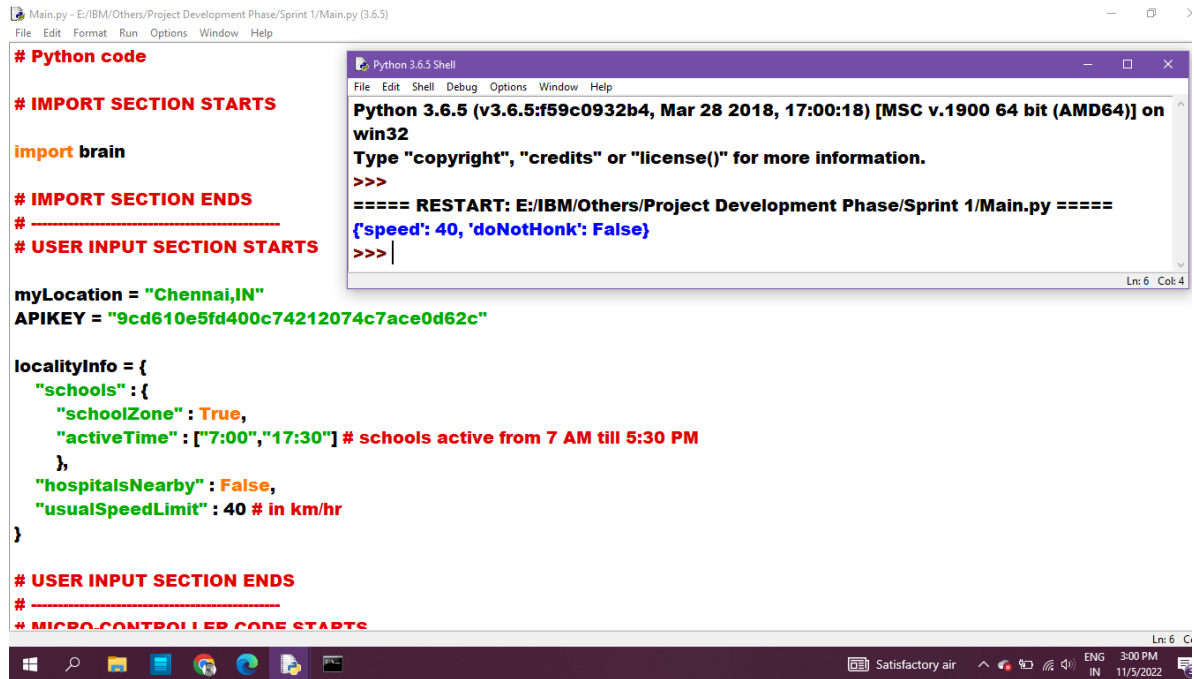
# Python code
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# -----
# USER INPUT SECTION STARTS
myLocation="Chennai,IN"
APIKEY="9cd610e5fd400c74212074c7ace0d62c"
localityInfo= {
"schools" : {
"schoolZone" : True,
"activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
},
"hospitalsNearby" : False,
"usualSpeedLimit" : 40# in km/hr
}
# USER INPUT SECTION ENDS
# -----
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
'''
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED
SPRINT SCHEDULE
'''
# MICRO-CONTROLLER CODE ENDS

```

## Output :

### # Code Output

```
{'speed': 40, 'doNotHonk': False}
```



The screenshot displays a Python IDE with a file named 'Main.py' open. The code in the editor includes comments for different sections: '# Python code', '# IMPORT SECTION STARTS', '# IMPORT SECTION ENDS', '# USER INPUT SECTION STARTS', and '# USER INPUT SECTION ENDS'. The code defines a variable 'myLocation' as 'Chennai,IN' and an 'APIKEY' as '9cd610e5fd400c74212074c7ace0d62c'. It also defines a dictionary 'localityInfo' with keys for 'schools', 'hospitalsNearby', and 'usualSpeedLimit'. The 'schools' key has a nested dictionary with 'schoolZone' set to True and 'activeTime' set to ['7:00', '17:30']. The 'hospitalsNearby' key is set to False, and the 'usualSpeedLimit' key is set to 40. The code is executed in a 'Python 3.6.5 Shell' window, which shows the output: '{'speed': 40, 'doNotHonk': False}'. The shell window also displays the Python version and the path to the script.

```
# Python code

# IMPORT SECTION STARTS

import brain

# IMPORT SECTION ENDS
# =====
# USER INPUT SECTION STARTS

myLocation = "Chennai,IN"
APIKEY = "9cd610e5fd400c74212074c7ace0d62c"

localityInfo = {
    "schools": {
        "schoolZone": True,
        "activeTime": ["7:00", "17:30"] # schools active from 7 AM till 5:30 PM
    },
    "hospitalsNearby": False,
    "usualSpeedLimit": 40 # in km/hr
}

# USER INPUT SECTION ENDS
# =====
# MICRO-CONTROLLER CODE STARTS
```

```
Python 3.6.5 (v3.6.5:f59c0932b4, Mar 28 2018, 17:00:18) [MSC v.1900 64 bit (AMD64)] on
win32
Type "copyright", "credits" or "license()" for more information.
>>>
===== RESTART: E:/IBM/Others/Project Development Phase/Sprint 1/Main.py =====
{'speed': 40, 'doNotHonk': False}
>>>
```