## Assignment - 4

Assignment Date	23 <sup>th</sup> October 2022
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Maximum Marks	2 Marks

## **Question-1:**

Write a code connection in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send "alert" to ibm cloud and display in device recent events.

## **Solution:**

```
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE TYPE "nodeMcu"
#define DEVICE ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
```

```
void loop() {
 bool is Nearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop())
  {mqttConnect();
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL CONNECTED)
  {delay(500);
  Serial.print(".");
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token))
  { Serial.print(".");
   delay(500);
  initManagedDevice();
  Serial.println();
void initManagedDevice()
 { if (client.subscribe(topic))
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
```

```
dist=duration*speed/2;
if(dist<100){
 String payload = "{\"Normal Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str()))
  {Serial.println("Publish OK");
 if(dist>101 && dist<111){
 String payload = "{\"Alert distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if(client.publish(publishTopic, (char*) payload.c_str()))
  { Serial.println("Warning crosses 110cm -- it automaticaly of the
  loop");digitalWrite(led,HIGH);
 }else {
  Serial.println("Publish FAILED");
}
void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength;
i++){dist += (char)payload[i];
Serial.println("data:"+ data3);
if(data3=="lighton"){ Serial.
println(data3);
digitalWrite(led,HIGH);
 data3="";
```

## Output:

```
#include <NiFi.h>
#include <PubSubClient.h>
#include <PubSubClient.h>
#include <PubSubClient.h>
#include <PubSubClient.h>
#include <PubSubClient.h>
#include <PubSubClient.h>
#include <PubSubClient.form.h
#include <PubSubClient.h
#include <Pu
```

```
Connecting to ...
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

