Assignment 4

WOKWI PROGRAM

Date	01 November 2022
Team ID	PNT2022TMID28453
Project Name	Smart Waste Management System For Metropolitan Cities

PROGRAM

Smart Waste Management System for Metropolitan Cities ASSIGNMENT 4:

Write code and connections in wokwi for ultrasonic sensors.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

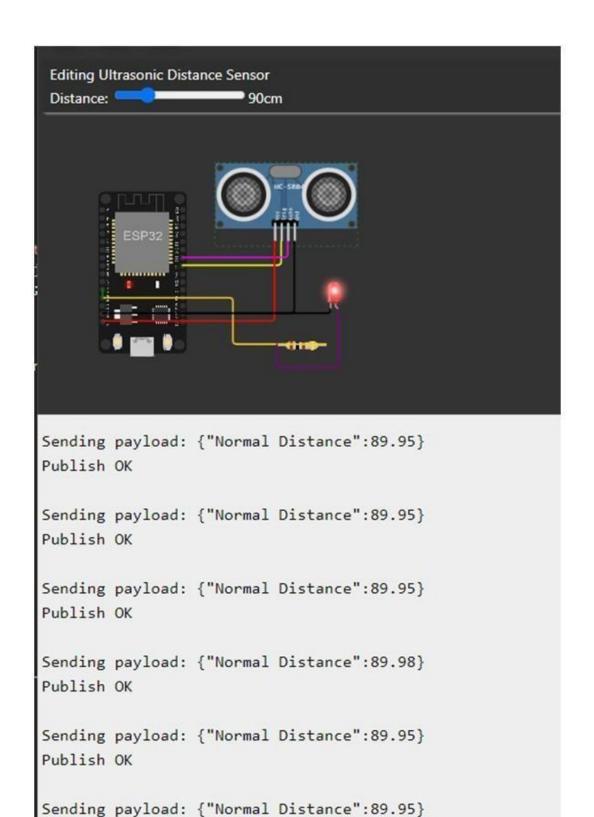
Upload document with wokwi share link and images of ibm cloud

CODE:

```
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
```

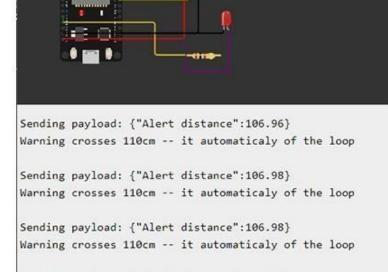
```
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
    Serial.print(".");
    delay(500);
  initManagedDevice();
  Serial.println();
void initManagedDevice() {
 if (client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Normal Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload,
    Serial.println("Publish OK");
  if(dist>101 && dist<111){
  String payload = "{\"Alert distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
   if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Warning crosses 110cm -- it automatically of the loop");
    digitalWrite(led,HIGH);
  }else {
    Serial.println("Publish FAILED");
 }
 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
 Serial.print("callback invoked for topic:");
 Serial.println(subscribeTopic);
 for(int i=0; i<payloadLength; i++){</pre>
  dist += (char)payload[i];
 Serial.println("data:"+ data3);
 if(data3=="lighton"){
  Serial.println(data3);
  digitalWrite(led,HIGH);
 data3="";
```





1) when distance under 100 cm it wil show normal distance





Sending payload: {"Alert distance":106.98} Warning crosses 110cm -- it automaticaly of the loop

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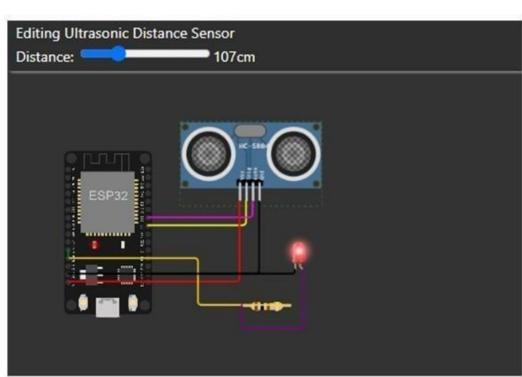
IBM CLOUD OUPUT



Publish OK

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	["Normal Distance":89.95]	json	a few seconds ago
Data	["Normal Distance":89.95]	json	a few seconds ago
Data.	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89,95}	json	a few seconds ago
Data	["Normal Distance":89.95]	json	a few seconds ago



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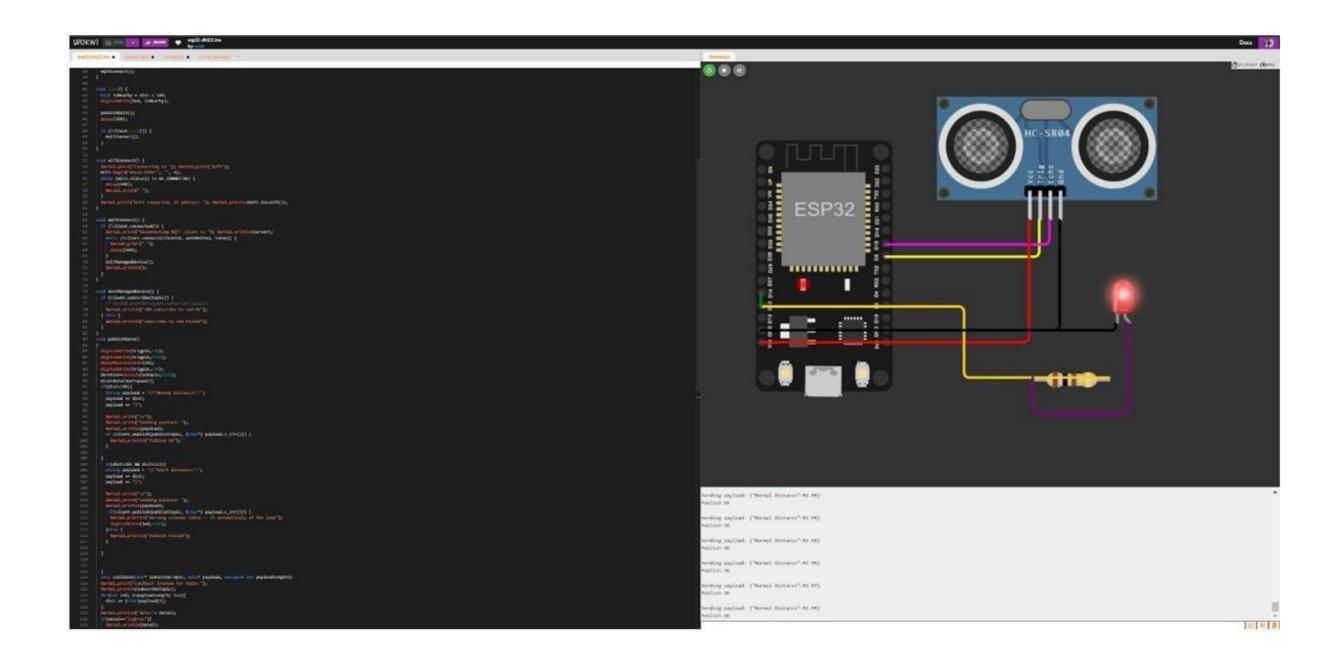
2) when distance cross 100 cm it wil show ALERT with warning message distance

when it cross above 110 cm it totaly move to iff state once it reduce to 110 it on again

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	["Alert distance":107.03]	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	["Alert distance":106.98]	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago



Connection Information

Basic connection information about this device.

Assignment4 Device ID nodeMcu **Device Type** 23 Oct 2022 07:20 Date Added

Disconnected

920219104302@sm Added By

Connection Status

Last Connected: 23 Oct 2022 16:57 Client Address: 145.40.94.93 Insecure

rnz.com

Duration: 3 minutes Data Transferred: 14.4 KB

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago

WORK FLOW LIKE IN description