EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES

VIDEO ANALYSIS

OPEN CV FOR VIDEO PROCESSING

Date	08 NOVEMBER 2022
Team ID	PNT2022TMID30907
Project Name	Emerging Methods for Early Detection of Forest Fires

Importing The ImageDataGenerator Library import keras

from keras.preprocessing.image import ImageDataGenerator

Define the parameters/arguments for ImageDataGenerator class

train_datagen=ImageDataGenerator(rescale=1./255,shear_range=0.2,rot ati on_range=180,zoom_range=0.2, horizontal_flip=True) test_datagen=ImageDataGenerator(rescale=1./255)

Applying

ImageDataGenerator functionality to trainset

x_train=train_datagen.flow_from_directory(r'/content/drive/MyDrive/Colab Notebooks/
Dataset/trainset',target_size=(128,128),batch_size=32,class_mode='binary')

Found 117 images belonging to 2 classes.

Applying ImageDataGenerator functionality to testset

x_test=test_datagen.flow_from_directory(r'/content/drive/MyDrive / Colab Notebooks/ Dataset/testset',target_size=(128,128),batch_size=32, class_mode='binary')

Found 117 images belonging to 2 classes.

Import model building libraries

#To define Linear initialisation import Sequential
from keras.models import Sequential #To add layers
import Dense from keras.layers import Dense #To
create Convolution kernel import Convolution2D
from keras.layers import Convolution2D #import
Maxpooling layer from keras.layers import MaxPooling2D
#import flatten layer from
keras.layers import Flatten
import warnings
warnings.filterwarnings('ignore')

Initializing the model model=Sequential()

```
Add CNN Layer
model.add(Convolution2D(32,
(3,3),input_shape=(128,128,3),activation='relu'))
#add maxpooling layer
model.add(MaxPooling2D(pool_size=(2,2))) #add
flatten layer model.add(Flatten())
Add Hidden Layer
 #add hidden layer model.add(Dense(150,activation='relu'))
#add output layer model.add(Dense(1,activation='sigmoid')
Configure the learning process
model.compile(loss='binary_crossentropy',optimizer="adam",metrics=[
"ac curacy"])
Train the model
model.fit_generator(x_train,steps_per_epoch=4,epochs=10,validation_da
ta=x_test, validation_steps=4)
Epoch 1/10
4/4 [======] - 97s 7s/step - loss:
1.3060 - accuracy: 0.7775 - val_loss: 0.5513 -
val accuracy: 0.8512
Epoch 2/10
4/4 [======] - 26s 2s/step - loss:
0.3178 - accuracy: 0.8807 - val loss: 0.1299 -
val_accuracy: 0.9421
Epoch 3/10
4/4 [======] - 26s 2s/step - loss:
0.2226 - accuracy: 0.9106 - val loss: 0.1311 - val accuracy:
0.9421
```

```
Epoch 4/10
4/4 [======] - 31s 2s/step - loss:
0.1836 - accuracy: 0.9174 - val_loss: 0.1129 -
 val_accuracy: 0.9339
Epoch 5/10
4/4 [======] - 30s 2s/step - loss:
0.1675 - accuracy: 0.9243 - val loss: 0.0925 -
 val accuracy: 0.9669
Epoch 6/10
4/4 [=======] - 26s 2s/step - loss:
0.1884 - accuracy: 0.9289 - val_loss: 0.1287 -
 val_accuracy: 0.9339
Epoch 7/10
4/4 [=======] - 28s 2s/step - loss:
0.1724 - accuracy: 0.9335 - val_loss: 0.0926 -
 val accuracy: 0.9752
Epoch 8/10
4/4 [======] - 26s 2s/step - loss:
0.1510 - accuracy: 0.9404 - val_loss: 0.0757 -
 val_accuracy: 0.9752
Epoch 9/10
4/4 [=======] - 26s
 2s/step - loss:
  0.173 - 2 accuracy: 0.9174 - val_loss: 0.0537 - val_accuracy: 0.9835
Epoch 10/10
4/4 [=======] - 26s
2s/step - loss:
0.154 -accuracy: 0.9312 - val_loss: 0.0573 - val_accuracy: 0.9835
 <keras.callbacks.History at 0x7f05d66a9c90>
```

Save The Model

model.save("forestf1.h5") **Predictions**

```
#import load model
from keras.model from
 keras.models import
 load_model #import
 image class from keras
        tensorflow.keras.preprocessing
                                        import
 from
                                                 image
 #import numpy import numpy as np #import cv2 import
 cv2
           #load
                    the
                          saved model
                                            model
 load model("forest1.h5")
 img=image.load_img(r'/content/drive/MyDrive/Dataset/te
 st set/forest/ 0.48007200 1530881924 final forest.jpg')
 x=image.img_to_array(img)
                                           cv2.resize(x,
                                 res
 dsize=(128, 128), interpolation=cv2.INTER_CUBIC)
 #expand the image shape x=np.expand_di ms(res,axis=0)
 pred= model.predict(x)
 1/1 [======] - 0s
 126ms/step pred
 array([[0.]],
 dtype=float32) OpenCV
 For Video Processing
pip install twilio
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Requirement already satisfied: twilio in
/usr/local/lib/python3.7/dist-packages (7.15.1)
Requirement already satisfied: pytz in /usr/local/lib/python3.7/dist-
packages (from twilio) (2022.5)
Requirement already satisfied: requests>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from twilio) (2.23.0)
Requirement already satisfied: PyJWT<3.0.0,>=2.0.0 in
```

```
/usr/local/lib/python3.7/dist-packages (from twilio) (2.6.0) Requirement
already satisfied: urllib3!=1.25.0,!=1.25.1,<1.26,>=1.21.1 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0- >twilio)
(1.24.3)
Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)
(2022.9.24)
Requirement already satisfied: idna<3,>=2.5 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)
(2.10)
Requirement already satisfied: chardet<4,>=3.0.2 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio)
(3.0.4)
pip install playsound
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Requirement already satisfied: playsound in
/usr/local/lib/python3.7/dist-packages (1.3.0)
#import opency library import
cv2 #import
numpy import numpy
as np
#import image function from keras
from keras.preprocessing import
image #import load_model from
keras from keras.models import load_model
#import
client from twilio API from
twilio.rest import Client
#import playsound package from playsound import
playsound WARNING:playsound:playsound is
relying on another python subprocess. Please use
`pip install pygobject` if you want playsound to
```

run more efficiently. #load the saved model

model=load_model("forest1.h 5")
#define video
video=cv2.VideoCapture(0) #define
the features
name=['forest','with fire']