Date	31 October 2022
Team ID	PNT2022TMID10531
Project Name	Signs with smart connectivity for Better road safety

# **Sprint 02**

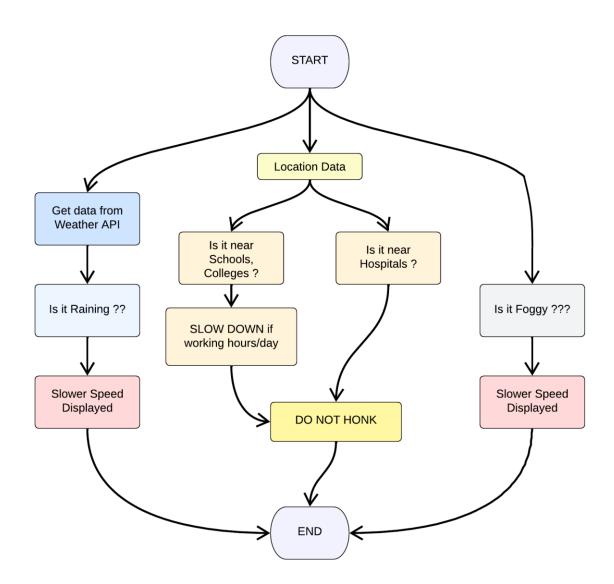
# **Signs with Smart Connectivity for Better Road Safety**

# **Team ID - PNT2022TMID10531**

# **Sprint Goals:**

1. Push data from local code to cloud

#### **Code Flow:**



## **Program Code:**

#### > weather.py

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code
import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
```

#### > publishData.py

This code pushes data to the cloud and logs data. IBM Cloud is configured such that the data is displayed in the following website: **CLICK TO OPEN NODE RED** 

#### **DASHBOARD**

```
# Python code
# IMPORT SECTION STARTS
import wiotp.sdk.device # python -m pip install wiotp
import time
# IMPORT SECTION ENDS
# -----
# API CONFIG SECTION STARTS
myConfig = {
    "identity" : {
       "orgId" : "epmoec",
"typeId" : "testDevice",
"deviceId" : "device0"
    "auth" : {
        "token" : "?-KDXUPMvDo TK2&b1"
    }
}
# API CONFIG SECTION ENDS
# -----
# FUNCTIONS SECTION STARTS
def myCommandCallback(cmd):
    print("recieved cmd : ",cmd)
def logData2Cloud(location,temperature,visibility):
    client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
    client.connect()
    client.publishEvent(eventId="status",msgFormat="json",data={
        "temperature" : temperature,
"visibility" : visibility,
"location" : location
    },qos=0,onPublish=None)
    client.commandCallback = myCommandCallback
    client.disconnect()
```

```
time.sleep(1)
# FUNCTIONS SECTION ENDS
```

#### > brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
from datetime import datetime as dt
from publishData import logData2Cloud as log2cloud
# IMPORT SECTION ENDS
# -----
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
   weatherData = weather.get(myLocation,APIKEY)
   log2cloud(myLocation,weatherData["temperature"],weatherData["visibility"])
   finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
   finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
    if(localityInfo["hospitalsNearby"]):
       # hospital zone
       doNotHonk = True
   else:
       if(localityInfo["schools"]["schoolZone"]==False):
           # neither school nor hospital zone
           doNotHonk = False
       else:
           # school zone
           now = [dt.now().hour,dt.now().minute]
           activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
           doNotHonk = activeTime[0][0] < = now[0] < = activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
    return({
        "speed" : finalSpeed,
        "doNotHonk" : doNotHonk
   })
# UTILITY LOGIC SECTION ENDS
```

#### > main.py

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
```

```
import brain
# IMPORT SECTION ENDS
# -----
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
   "schools" : {
       "schoolZone" : True,
       "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
       },
   "hospitalsNearby" : False,
   "usualSpeedLimit" : 40 # in km/hr
}
# USER INPUT SECTION ENDS
# -----
# MICRO-CONTROLLER CODE STARTS
while True :
   print(brain.processConditions(myLocation,APIKEY,localityInfo))
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR PLANNED SPRINT SCHEDULE
# MICRO-CONTROLLER CODE ENDS
```

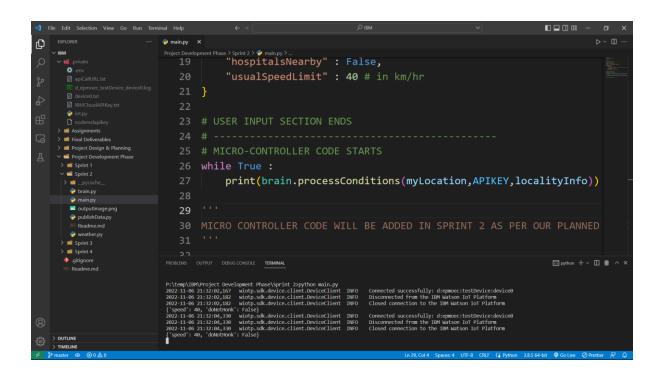
### **Output:**

#### LINK TO NODE RED DASHBOARD

```
# Code Output
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
                                                                      Connected
successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
                                                                      Closed
connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
                                                                      Connected
successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:35,631
                        wiotp.sdk.device.client.DeviceClient INFO
                                                                      Closed
connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
... repeats every 1 sec
```

## **Image:**





### **Thank You**