Date	31 October 2022
Team ID	PNT2022TMID10531
Project Name	Signs with smart connectivity for Better road safety

# **Sprint 04**

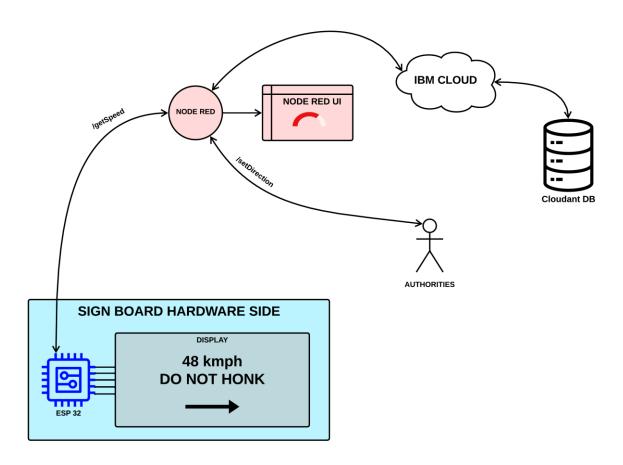
## **Signs with Smart Connectivity for Better Road Safety**

## **Team ID - PNT2022TMID10531**

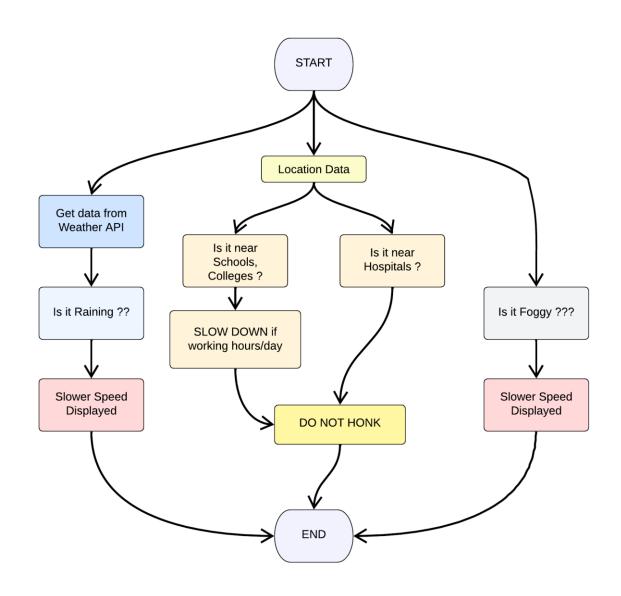
## **Sprint Goals:**

1. Hardware & Cloud integration

#### **Process Flow:**

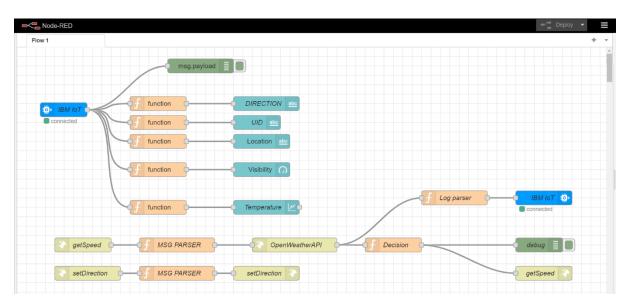


#### **Code Flow:**



#### Node RED:

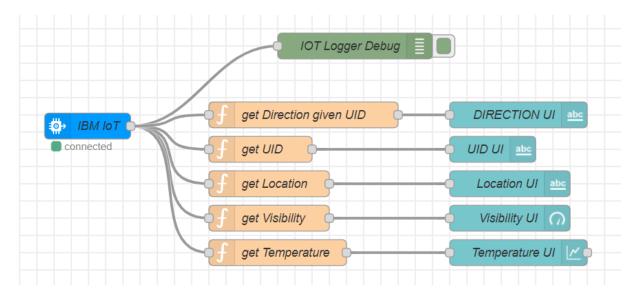
#### Node RED flow:



There are 3 flows in the above Node RED flow. They are

- 1. Node RED UI flow
- 2. /getSpeed API flow
- 3. /setDirection API flow

#### 1. Node RED UI flow:



- 1. "IBM IOT" node connects the backend to Node RED UI
- 2. The function nodes such as "get Direction given UID", "get UID", "get Location", "get Visibility" & "get Temperature" extract the respective data

out and provides them to the UI nodes "Direction UI", "UID UI", "Location UI", "Visibility UI" & "Temperature UI".

```
// get Direction given UID
msg.payload = global.get(String(msg.payload.uid));
return msg;

// get UID
msg.payload = msg.payload.uid;
return msg;

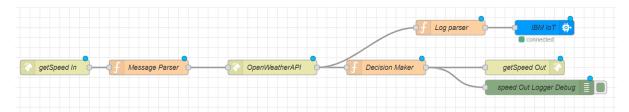
// get Location
msg.payload = msg.payload.location;
return msg;

// get Visibility
msg.payload = msg.payload.visibility;
return msg;

// get Temperature
msg.payload = msg.payload.temperature;
return msg;
```

3. "IOT Logger Debug" node logs the data at debugger.

#### 2. /getSpeed API flow:



- 1. "getSpeed In" node is an http end point. It accepts parameters like microcontroller UID, location, school & hospital zones info.
- 2. "Message Parser" node parses the data and passes on only required information to the next node

```
global.set("data",msg.payload);
msg.payload.q = msg.payload.location;
msg.payload.appid = "bf4a8d480ee05c00952bf65b78ae826b";
return msg;
```

- 3. "OpenWeatherAPI" node is a http request node which calls the OpenWeather API and send the data to the next node.
- 4. "Log Parser" node extracts specific parameters from the weather data and and sends it to the next node

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");

var suggestedSpeedPercentage = 100;

var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    location : localityObj.location,
    visibility : weatherObj.visibility/100,
    uid : localityObj.uid,
    direction : global.get("direction")
};

msg.payload = preciseObject;

return msg;
```

- "IBM IoT" node here (IBM IoT OUT)connects the "IBM IoT" node (IBM IoT IN) metioned in the Node RED UI flow which enables UI updation and logging.
- 6. "Decision Maker" node processes the weather data and other information from the micro controller to form the string that is to be displayed at the Sign Board

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");
var suggestedSpeedPercentage = 100;
var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    weather : weatherObj.weather.map(x=>x.id).filter(code => code<700),</pre>
    visibility : weatherObj.visibility/100
};
if(preciseObject.visibility<=40)</pre>
    suggestedSpeedPercentage -=30
switch(String(preciseObject.weather)[-1]) // https://openweathermap.org/weather-
conditions refer weather codes meaning here
{
    case "0" : suggestedSpeedPercentage -=10;break;
    case "1" : suggestedSpeedPercentage -=20;break;
    case "2" : suggestedSpeedPercentage -=30;break;
}
msg.payload = preciseObject;
var doNotHonk = 0;
if(localityObj.hospitalZone=="1"||localityObj.schoolZone=="1")
    doNotHonk = 1;
var returnObject = {
    suggestedSpeed : localityObj.usualSpeedLimit*(suggestedSpeedPercentage/100),
    doNotHonk : doNotHonk
}
```

```
msg.payload = String(returnObject.suggestedSpeed) + " kmph \n\n" +
(returnObject.doNotHonk==1?"Do Not Honk":"") + "$" +
global.get(String(localityObj.uid));
return msg;
```

- 7. "getSpeed Out" node returns a http response for the request at node "getSpeed In".
- 8. "speed Out Logger Debug" logs the data for debugging.

#### 3. /setDirection API flow:



- 1. "setDirection In" node is an http end point. It accepts parameters like microcontroller UID & direction.
- 2. "**set Direction Function**" node sets the direction for the given UID.

global.set(String(msg.payload.uid),msg.payload.dir);
return msg;

3. "setDirection Out" node returns a http response for the request at node "setDirection In".

Click on this link to change direction to Straight

**Click on this link to change direction to Left** 

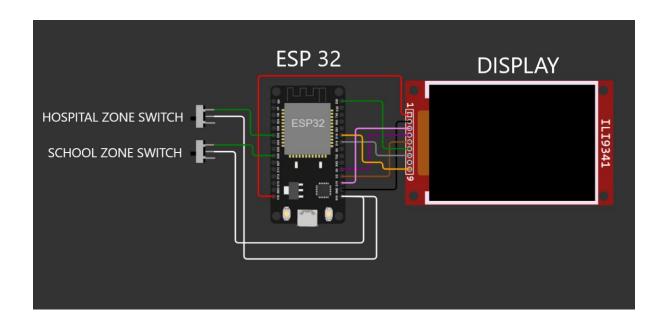
Click on this link to change direction to Right

#### **Wokwi Circuit:**

**Wokwi Code** 

**Wokwi Link** 

**Circuit Diagram:** 



#### **ESP 32 CODE:**

```
#include <WiFi.h>
#include <HTTPClient.h>
#include <Adafruit_GFX.h>
#include <Adafruit_ILI9341.h>
#include <string.h>
const char* ssid = "Wokwi-GUEST";
const char* password = "";
#define TFT DC 2
#define TFT CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);
String myLocation = "Chennai, IN";
String usualSpeedLimit = "70"; // kmph
int schoolZone = 32;
int hospitalZone = 26;
int uid = 2504; // ID Unique to this Micro Contoller
String getString(char x)
    String s(1, x);
    return s;
String stringSplitter1(String fullString,char delimiter='$')
    String returnString = "";
    for(int i = 0; i<fullString.length();i++) {</pre>
        char c = fullString[i];
        if(delimiter==c)
            break;
        returnString+=String(c);
    return(returnString);
```

```
}
String stringSplitter2(String fullString,char delimiter='$')
    String returnString = "";
    bool flag = false;
    for(int i = 0; i<fullString.length();i++) {</pre>
        char c = fullString[i];
        if(flag)
            returnString+=String(c);
        if(delimiter==c)
            flag = true;
    }
    return(returnString);
}
void rightArrow()
  int refX = 50;
  int refY = tft.getCursorY() + 40;
 tft.fillRect(refX,refY,100,20,ILI9341 RED);
 tft.fillTriangle(refX+100,refY-
30, refX+100, refY+50, refX+40+100, refY+10, ILI9341 RED);
}
void leftArrow()
  int refX = 50;
  int refY = tft.getCursorY() + 40;
 tft.fillRect(refX+40,refY,100,20,ILI9341_RED);
 tft.fillTriangle(refX+40,refY-30,refX+40,refY+50,refX,refY+10,ILI9341_RED);
}
void upArrow()
  int refX = 125;
 int refY = tft.getCursorY() + 30;
 tft.fillTriangle(refX-40,refY+40,refX+40,refY,refX,refY,ILI9341_RED);
  tft.fillRect(refX-15,refY+40,30,20,ILI9341 RED);
String APICall() {
 HTTPClient http;
 String url = "https://node-red-grseb-2022-11-05-test.eu-
gb.mybluemix.net/getSpeed?";
 url += "location="+myLocation+"&";
 url += "schoolZone="+(String)digitalRead(schoolZone)+(String)"&";
 url += "hospitalZone="+(String)digitalRead(hospitalZone)+(String)"&";
 url += "usualSpeedLimit="+(String)usualSpeedLimit+(String)"&";
 url += "uid="+(String)uid;
 http.begin(url.c_str());
  int httpResponseCode = http.GET();
  if (httpResponseCode>0) {
    String payload = http.getString();
```

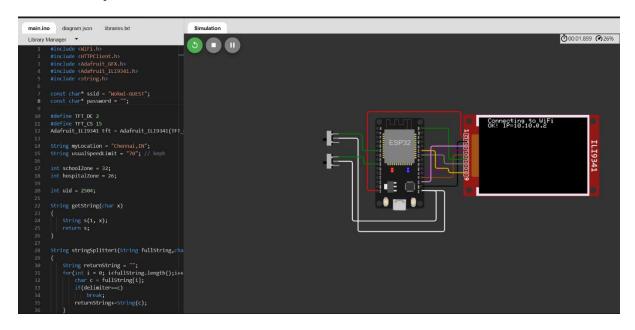
```
http.end();
    return(payload);
  }
 else {
    Serial.print("Error code: ");
    Serial.println(httpResponseCode);
 http.end();
}
void myPrint(String contents) {
 tft.fillScreen(ILI9341_BLACK);
 tft.setCursor(0, 20);
 tft.setTextSize(4);
  tft.setTextColor(ILI9341_RED);
  //tft.println(contents);
 tft.println(stringSplitter1(contents));
 String c2 = stringSplitter2(contents);
  if(c2=="s") // represents Straight
  {
    upArrow();
  if(c2=="l") // represents left
  {
   leftArrow();
  if(c2=="r") // represents right
    rightArrow();
  }
void setup() {
 WiFi.begin(ssid, password, 6);
 tft.begin();
 tft.setRotation(1);
 tft.setTextColor(ILI9341_WHITE);
 tft.setTextSize(2);
 tft.print("Connecting to WiFi");
 while (WiFi.status() != WL_CONNECTED) {
    delay(100);
    tft.print(".");
 tft.print("\nOK! IP=");
  tft.println(WiFi.localIP());
}
void loop() {
 myPrint(APICall());
  delay(100);
}
```

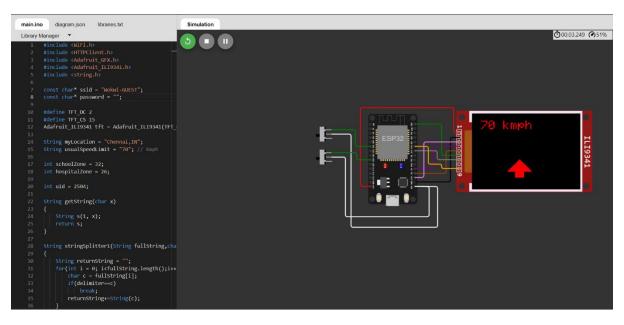
### **Output:**

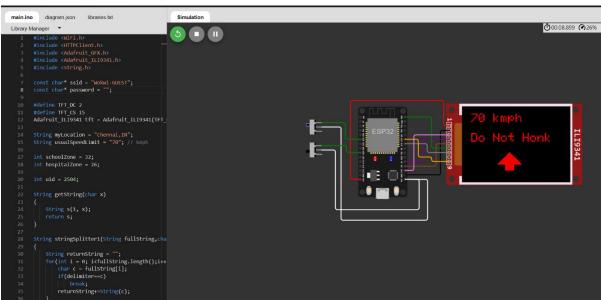
#### **Node RED Dashboard:**

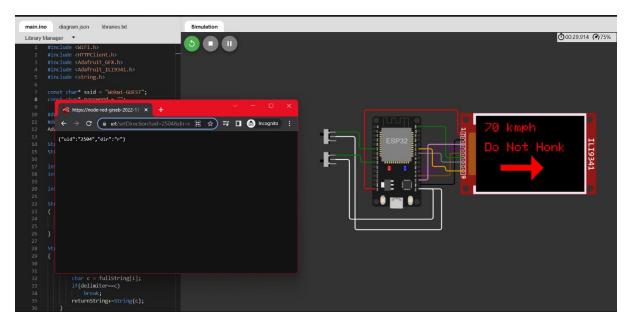


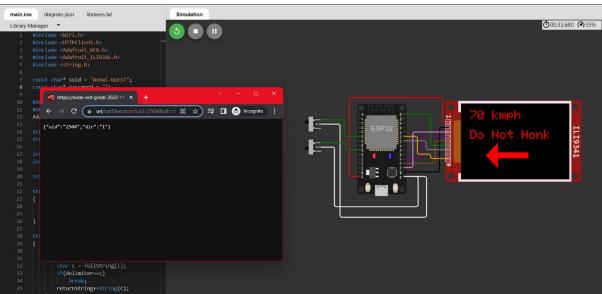
#### **Wokwi Output:**











**Thank You**