IBM ASSIGNMENT- 4

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Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send an "Alert" to ibm cloud and display in device recent events.

Solution:

```
//Pins
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range
find Pin Mode(TRIG_PIN, OUTPUT); digital
Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the
duration of //pulses coming back from the
distance sensor pinMode(ECHO_PIN, INPUT);
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
void loop() {
unsigned long t1;
unsigned long t2;
unsigned long
pulse_width; float
cm; float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while
                    (digitalRead(
ECHO_PIN)==0;
// Measure how long the echo pin was held high (pulse
width) // Note: the micros() counter will overflow after-70
min t1= micros ();
```

```
while (digitalRead(ECHO_PIN) ==
1); t2= micros (); pulse_width =
t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
 // of sound in air at sea level (-
340m/s) cm=pulse_Width / 58;
inches = pulse_width/148.0;
// Print out results
(pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if (cm < 100)
   //while(true){
   Serial.println("Alert!!");
   //}
Serial.print("********************************);
//wait at least 1000ms before next measurement
```

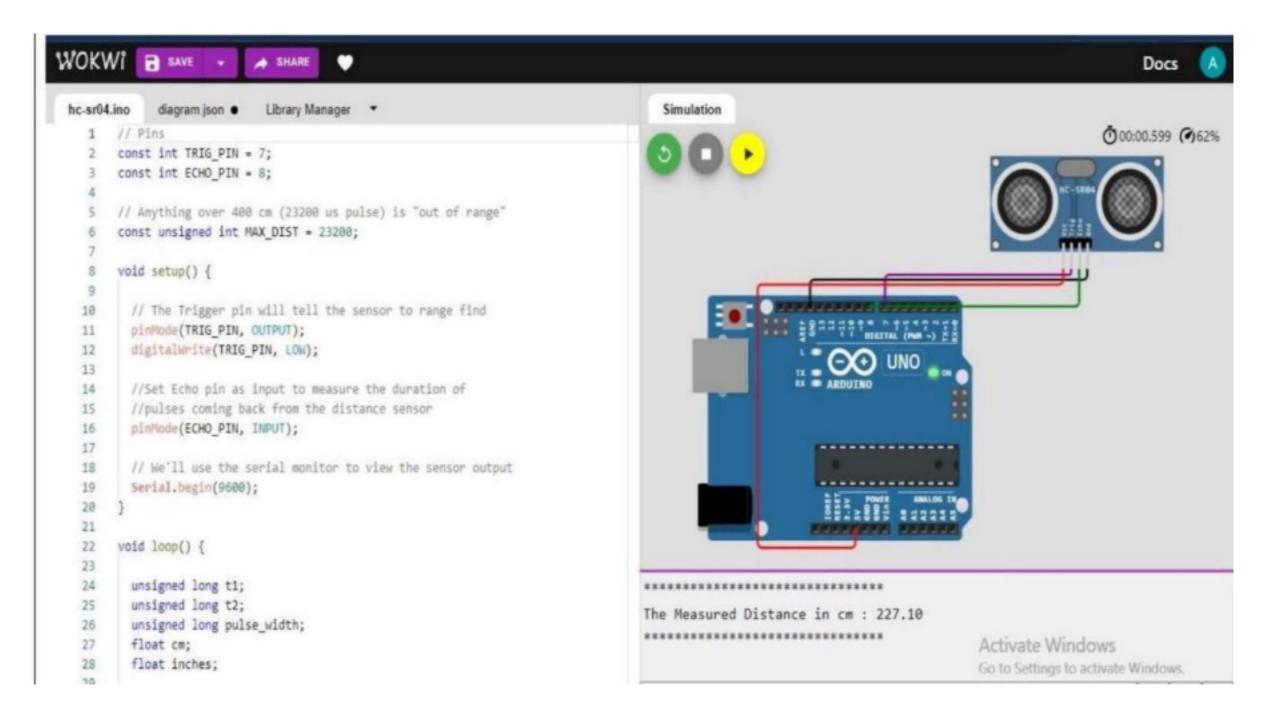
```
Delay(1000);
}
```

Output:

1.If the distance is less than 100 cms ,it alerts.

```
WOKWI - SAVE
                                                                                   Simulation
 hc-sr04.ino
            diagram.json ● Library Manager ▼
                                                                                                                                               ₫00:00.466 (*)58%
        // Pins
        const int TRIG_PIN = 7;
        const int ECHO_PIN = 8;
        // Anything over 400 cm (23200 us pulse) is "out of range"
                                                                                 Distance:
        const unsigned int MAX_DIST = 23200;
        void setup() {
         // The Trigger pin will tell the sensor to range find
   11
         pinMode(TRIG_PIN, OUTPUT);
         digitalWrite(TRIG_PIN, LOW);
         //Set Echo pin as input to measure the duration of
   15
         //pulses coming back from the distance sensor
   16
         pinMode(ECHO_PIN, IMPUT);
   17
   18
         // We'll use the serial monitor to view the sensor output
   19
         Serial.begin(9600);
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   20
   21
   22
        void loop() {
   23
   24
         unsigned long t1;
                                                                                ***********
         unsigned long t2;
   25
          unsigned long pulse_width;
                                                                                The Measured Distance in cm : 84.14
   26
   27
         float cm;
```

2.If the distance is more than 100 cms, it won't alert



3. Simulation and code execution

