

## Sprint-01

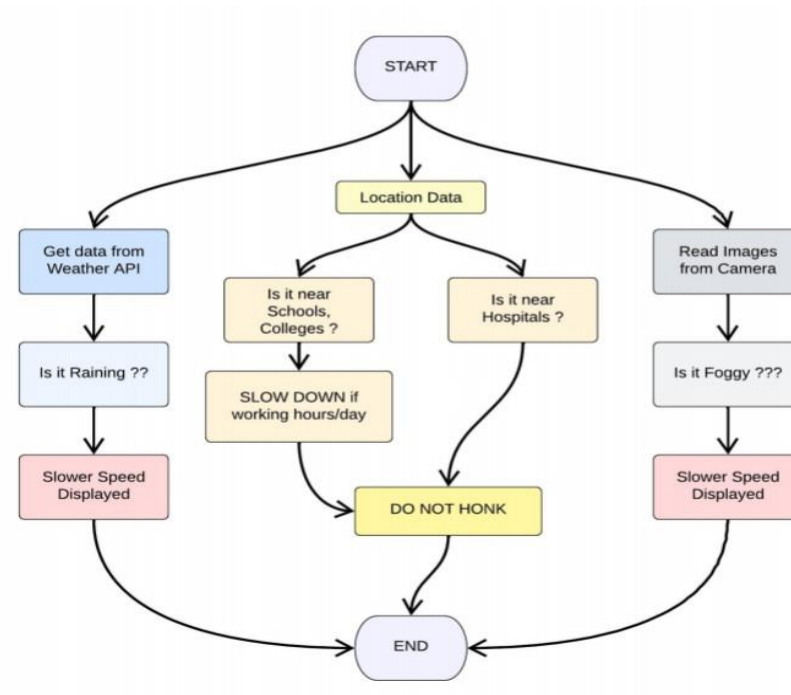
### Signs with Smart Connectivity for Better Road Safety

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#### ###SprintGoals:

1. Create and initialize accounts in various public APIs like Open Weather API.
2. Write a Python program that outputs results given the inputs like weather and location.

#### ###CodeFlow :



#### ### Program Code

:(./weather.py)

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
```python
```

```
#Pythoncode
```

```
import requests as reqs
```

```
def get(myLocation, APIKEY):
```

```
    apiURL =
```

```
    f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
```

```
    response = (reqs.get(apiURL)).json()
```

```
    returnObject = {
```

```
        "temperature": responseJSON['main']['temp'] -
```

```
        273.15, "weather": [responseJSON['weather'][_]['main'].lower() for
```

```
        _ in
```

```
        range(len(responseJSON['weather']))],
```

```
        "visibility": responseJSON['visibility']/100, # visibility in percentage where 10km is 100% and 0km is 0%
```

```
    }
```

```
    if ("rain" in responseJSON):
```

```
        returnObject["rain"] = [responseJSON["rain"][key] for key in
```

```
        responseJSON["rain"]]
    return(returnObject)
```

```
```
```

```
(./brain.py)
```

> This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
```python
```

```
#Pythoncode
```

```
#IMPORTSECTIONSTARTS
```

```
import weather
```

```
from datetime import datetime as dt
```

```

#IMPORTSECTIONENDS

# .....

#UTILITYLOGICSECTIONSTARTS

defprocessConditions(myLocation,APIKEY,localityInfo):

    weatherData=weather.get(myLocation,APIKEY)


    finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData
    elselocalityInfo["usualSpeedLimit"]/2

    finalSpeed=finalSpeedifweatherData["visibility">35elsefinalSpeed/2


    if(localityInfo["hospitalsNearby"]):

        # hospital

        zonedoNotHonk=True

    else:

        if(localityInfo["schools"]["schoolZone"]==False):

            # neither school nor hospital

            zonedoNotHonk= False

        else:

            # schoolzone

            now=[dt.now().hour,dt.now().minute]

            activeTime = [list(map(int,_split(":")) for _ in

            localityInfo["schools"]["activeTime"])]doNotHonk=activeTime[0][0]<=now[0]<=activ

            eTime[1][0] and

            activeTime[0][1]<=now[1]<=activeTime[1][1]


    return({

        "speed" :

        finalSpeed,"doNotHonk":doNo

        tHonk

    })


#UTILITYLOGICSECTIONENDS

'''

```

(./main.py)

> The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
```python
```

```
#Pythoncode
```

```
#IMPORTSECTIONSTARTS
```

```
import brain
```

```
#IMPORTSECTIONENDS
```

```
#.....
```

```
#USERINPUTSECTIONSTARTS
```

```
myLocation="Chennai,IN"
```

```
APIKEY="bf4a8d480ee05c00952bf65b78ae826b"
```

```
localityInfo =
```

```
{ "schools": {
    "schoolZone": True,
    "activeTime": ["7:00", "17:30"] # schools active from 7AM till 5:30PM
  },
  "hospitalsNearby":
    False, "usualSpeedLimit": 40 # in km
    /hr
}
```

```
#USERINPUTSECTIONENDS
```

```
#.....
```

```
#MICRO-CONTROLLERCODESTARTS
```

```
print(brain.processConditions(myLocation,APIKEY,localityInfo))
```

```
'''
```

```
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT  
SCHEDULE'''
```

```
#MICRO-CONTROLLERCODEENDS
```

```
'''
```

Output:

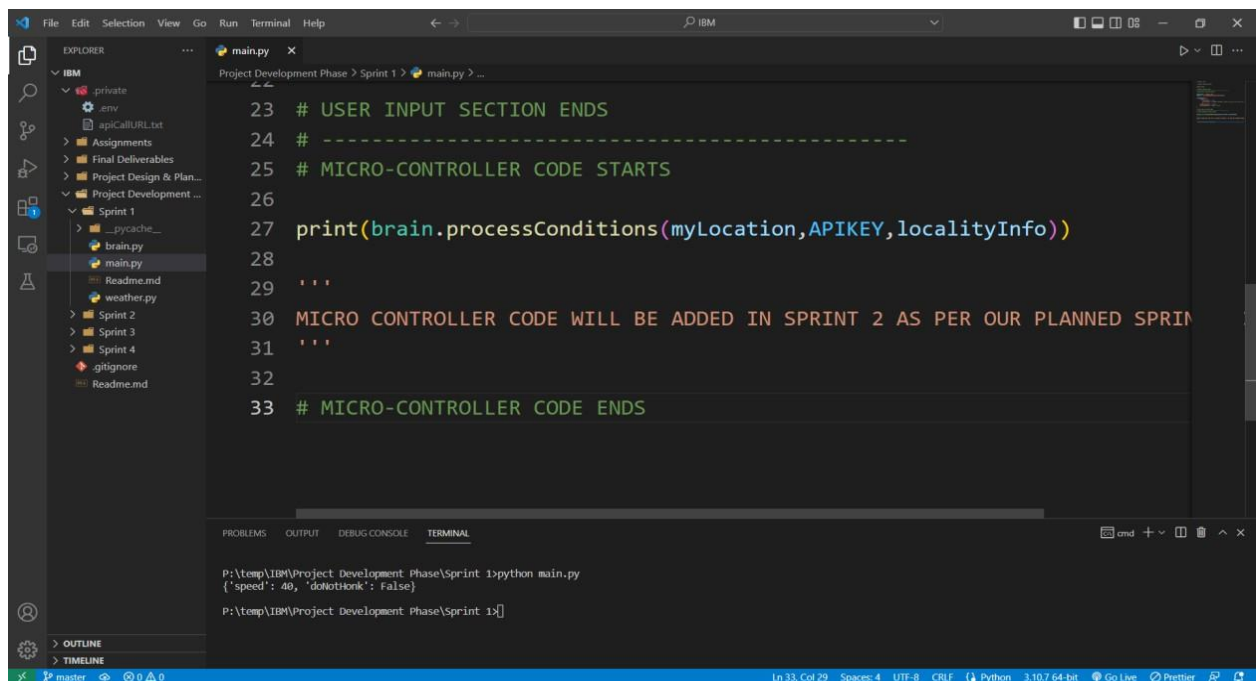
```
```python
```

```
#CodeOutput
```

```
{'speed':40,'doNotHonk':False}
```

```
'''
```

Images:



ThankYou