

## Develop a python script

|                      |  |
|----------------------|--|
| <b>Team ID</b>       | PNT2022TMID30928                                       |
| <b>Project Title</b> | IoT Based Smart Crop Protection System for Agriculture |

### PYTHON CODE:

```
import cv2

import numpy as np

import wiot.sdk.device

import playsound

import random

import time

import datetime

import ibm_boto3

from ibm_botocore.client import Config, ClientError

#CloudantDB

from cloudant.client import Cloudant

from cloudant.error import CloudantException

from cloudant.result import Result, ResultByKey
```

```
from clarifai_grpc.channel.clarifai_channel import ClarifaiChannel
from clarifai_grpc.grpc.api import service_pb2_grpc
stub = service_pb2_grpc.V2Stub(ClarifaiChannel.get_grpc_channel())
from clarifai_grpc.grpc.api import service_pb2, resource_pb2
from clarifai_grpc.grpc.api.status import status_code_pb2

#This is how you authenticate
metadata = (('authorization', 'key
0620e202302b4508b90eab7efe7475e4'),)
COS_ENDPOINT="https://s3.jp-tok.cloud-object-storage.appdomain.cloud"
COS_API_KEY_ID="g5d4qO8Elgv4TWUCJj4hfEzgalqEjrDbE82AJD
WIAOHo"
COS_AUTH_ENDPOINT = "https://iam.cloud.ibm.com/identity/token"
COS_RESOURCE_CRN="crn:v1:bluemix:public:cloud-object-storage:
global:a/c2fa2836eaf3434bbc8b5b58feff3f0:62e450fd-4c82-4153-ba4
1-ccb53adb8111::"
clientdb=cloudant("apikey-W2njldnwtjO16V53LAVUCqPwc2aHTLmlj1
xXvtdGKJBn","88cc5f47c1a28afbfb8ad16161583f5a",url="https://d6c89f97-cf91-48b7-b14b-c99b2fe27c2f-bluemix.cloudantnosqldb.appdomain.cloud")
clientdb.connect()
```

#Create resource

```
cos = ibm_boto3.resource("s3",  
                           ibm_api_key_id=COS_API_KEY_ID,  
                           ibm_service_instance_id=COS_RESOURCE_CRN,  
                           ibm_auth_endpoint=COS_AUTH_ENDPOINT,  
                           config=Config(signature_version="oauth"),  
                           endpoint_url=COS_ENDPOINT  
                           )
```

```
def = multi_part_upload(bucket_name, item_name, file_path):
```

```
    try:
```

```
        print("Starting file transfer for {0} to bucket:  
{1}\n".format(item_name, bucket_name))
```

```
        #set 5 MB chunks
```

```
        part_size = 1024 * 1024 * 5
```

```
        #set threadhold to 15 MB
```

```
        file_threshold = 1024 * 1024 * 15
```

```
        #set the transfer threshold and chunk size
```

```
        transfer_config = ibm_boto3.s3.transfer.TransferConfig(  
            multipart_threshold=file_threshold,
```

```

        multipart_chunksize=part_size
    )

    #the upload_fileobj method will automatically execute a multi-part
upload

    #in 5 MB chunks size

    with open(file_path, "rb") as file_data:

        cos.Object(bucket_name, item_name).upload_fileobj(

            Fileobj=file_data,

            Config=transfer_config

        )

    print("Transfer for {0} Complete!\n".format(item_name))

except ClientError as be:

    print("CLIENT ERROR: {0}\n".format(be))

except Exception as e:

    print("Unable to complete multi-part upload: {0}".format(e))


def myCommandCallback(cmd):

    print("Command received: %s" % cmd.data)

    command=cmd.data['command']

    print(command)

```

```
if(commamd=="lighton"):
    print('lighton')
elif(command=="lightoff"):
    print('lightoff')
elif(command=="motoron"):
    print('motoron')
elif(command=="motoroff"):
    print('motoroff')
myConfig = {
    "identity": {
        "orgId": "fzb72x",
        "typeId": "ESP-",
        "deviceId": "1234567890"
    },
    "auth": {
        "token": "pByAf4p(2nTbtBIMQM"
    }
}
client = wiot.sdk.device.DeviceClient(config=myConfig,
logHandlers=None)
```

```
client.connect()
```

```
database_name = "sample"
```

```
my_database = clientdb.create_database(database_name)
```

```
if my_database.exists():
```

```
    print(f"({database_name})' successfully created.")
```

```
cap=cv2.VideoCapture("garden.mp4")
```

```
if(cap.isOpened()==True):
```

```
    print('File opened')
```

```
else:
```

```
    print('File not found')
```

```
while(cap.isOpened()):
```

```
    ret, frame = cap.read()
```

```
    gray = cv3.cvtColor(frame, cv2.COLOR_BGR@GRAY)
```

```
    imS= cv2.resize(frame, (960,540))
```

```
    cv2.imwrite('ex.jpg',imS)
```

```
    with open("ex.jpg", "rb") as f:
```

```
        file_bytes = f.read()
```

#This is the model ID of a publicly available General model. You may use any other public or custom model ID.

```
request = service_pb2.PostModeloutputsRequest(
    model_id='e9359dbe6ee44dbc8842ebe97247b201',

inputs=[resources_pb2.Input(data=resources_pb2.Data(image=resources_pb2.Image(base64=file_bytes))
))]

response = stub.PostModelOutputs(request, metadata=metadata)
if response.status.code != status_code_pb2.SUCCESS:
    raise Exception("Request failed, status code: " +
str(response.status.code))

detect=False

for concept in response.outputs[0].data.concepts:
    #print('%12s: %.f' % (concept.name, concept.value))

    if(concept.value>0.98):
        #print(concept.name)

        if(concept.name=="animal"):
            print("Alert! Alert! animal detected")
            playsound.playsound('alert.mp3')
```

```
picname=datetime.datetime.now().strftime("%y-%m-%d-%H-%M")

cv2.imwrite(picname+'.jpg',frame)

multi_part_upload('Dhakshesh', picname+'.jpg',
picname+'.jpg')

json_document={"link":COS_ENDPOINT+'/'+ 'Dhakshesh'+'/'+picname
+'.jpg'}

new_document =
my_database.create_document(json_document)

if new_document.exists():

    print(f"Document successfully created.")

    time.sleep(5)

    detect=True

moist=random.randint(0,100)

humidity=random.randint(0,100)

myData={'Animal':detect,'moisture':moist,'humidity':humidity}

print(myData)

if(humidity!=None):

    client.publishEvent(eventId="status",msgFormat="json",
daya=myData, qos=0, onPublish=None)
```



```
    print("Publish Ok..")
client.commandCallback = myCommandCallback
cv2.imshow('frame',imS)
if cv2.waitKey(1) & 0xFF == ord('q'):
    break
client.disconnect()
cap.release()
cv2.destroyAllWindows()
```

```
import random

import ibmiotf.application

import ibmiotf.device

from time import sleep

import sys

#IBM Watson Device Credentials.

organization = "fzb72x"

deviceType = "ESP-"

deviceId = "1234567890"

authMethod = "token"

authToken = "pByAf4p(2nTbtBIMQM"

def myCommandCallback(cmd):

    print("Command received: %s" % cmd.data['command'])

    status=cmd.data['command']

    if status=="sprinkler_on":

        print ("sprinkler is ON")

    else :

        print ("sprinkler is OFF")

    #print(cmd)
```

try:

```
deviceOptions = {"org": organization, "type": deviceType, "id":  
deviceId, "auth-method": authMethod, "auth-token": authToken}
```

```
deviceCli = ibmiotf.device.Client(deviceOptions)
```

except Exception as e:

```
    print("Caught exception connecting device: %s" % str(e))
```

```
sys.exit()
```

#Connecting to IBM watson.

```
deviceCli.connect()
```

while True:

#Getting values from sensors.

```
temp_sensor = round( random.uniform(0,80),2)
```

```
PH_sensor = round(random.uniform(1,14),3)
```

```
camera = ["Detected","Not Detected","Not Detected","Not  
Detected","Not Detected","Not Detected",]
```

```
camera_reading = random.choice(camera)
```

```
flame = ["Detected","Not Detected","Not Detected","Not  
Detected","Not Detected","Not Detected",]
```

```
flame_reading = random.choice(flame)
```

```
moist_level = round(random.uniform(0,100),2)
```

```
water_level = round(random.uniform(0,30),2)
```

```
#storing the sensor data to send in json format to cloud.
```

```
temp_data = { 'Temperature' : temp_sensor }
```

```
PH_data = { 'PH Level' : PH_sensor }
```

```
camera_data = { 'Animal attack' : camera_reading }
```

```
flame_data = { 'Flame' : flame_reading }
```

```
moist_data = { 'Moisture Level' : moist_level }
```

```
water_data = { 'Water Level' : water_level }
```

```
# publishing Sensor data to IBM Watson for every 5-10 seconds.
```

```
success = deviceCli.publishEvent("Temperature sensor", "json",  
temp_data, qos=0)
```

```
sleep(1)
```

```
if success:
```

```
    print (" .....publish ok..... ")
```

```
print ("Published Temperature = %s C" % temp_sensor, "to IBM  
Watson")
```

```
success = deviceCli.publishEvent("PH sensor", "json", PH_data,  
qos=0)  
  
sleep(1)  
  
if success:  
  
    print ("Published PH Level = %s" % PH_sensor, "to IBM Watson")
```

```
success = deviceCli.publishEvent("camera", "json", camera_data,  
qos=0)  
  
sleep(1)  
  
if success:  
  
    print ("Published Animal attack %s " % camera_reading, "to IBM  
Watson")
```

```
success = deviceCli.publishEvent("Flame sensor", "json", flame_data,  
qos=0)  
  
sleep(1)  
  
if success:  
  
    print ("Published Flame %s " % flame_reading, "to IBM Watson")
```

```
success = deviceCli.publishEvent("Moisture sensor", "json",  
moist_data, qos=0)  
  
sleep(1)
```

```
if success:
```

```
    print ("Published Moisture Level = %s " % moist_level, "to IBM  
Watson")
```

```
    success = deviceCli.publishEvent("Water sensor", "json", water_data,  
qos=0)
```

```
    sleep(1)
```

```
if success:
```

```
    print ("Published Water Level = %s cm" % water_level, "to IBM  
Watson")
```

```
    print ("")
```

```
#Automation to control sprinklers by present temperature an to send  
alert message to IBM Watson.
```

```
if (temp_sensor > 35):
```

```
    print("sprinkler-1 is ON")
```

```
    success = deviceCli.publishEvent("Alert1", "json",{ 'alert1' :  
"Temperature(%s) is high, sprinklers are turned ON" %temp_sensor  
}
```

```
, qos=0)
```

```
    sleep(1)
```

if success:

```
print( 'Published alert1 : ', "Temperature(%s) is high, sprinklers  
are turned ON" %temp_sensor,"to IBM Watson")
```

```
print("")
```

else:

```
print("sprinkler-1 is OFF")
```

```
print("")
```

#To send alert message if farmer uses the unsafe fertilizer to crops.

if (PH\_sensor > 7.5 or PH\_sensor < 5.5):

```
success = deviceCli.publishEvent("Alert2", "json",{ 'alert2' :  
"Fertilizer PH level(%s) is not safe,use other fertilizer" %PH_sensor } ,  
qos=0)
```

```
sleep(1)
```

if success:

```
print('Published alert2 : ', "Fertilizer PH level(%s) is not safe,use  
other fertilizer" %PH_sensor,"to IBM Watson")
```

```
print("")
```

#To send alert message to farmer that animal attack on crops.

```
if (camera_reading == "Detected"):
```

```
    success = deviceCli.publishEvent("Alert3", "json", { 'alert3' : "Animal  
attack on crops detected" }, qos=0)
```

```
    sleep(1)
```

```
    if success:
```

```
        print('Published alert3 : ' , "Animal attack on crops detected","to IBM  
Watson","to IBM Watson")
```

```
        print("")
```

#To send alert message if flame detected on crop land and turn ON  
the sprinklers to take immediate action.

```
if (flame_reading == "Detected"):
```

```
    print("sprinkler-2 is ON")
```

```
    success = deviceCli.publishEvent("Alert4", "json", { 'alert4' : "Flame is  
detected crops are in danger,sprinklers turned ON" }, qos=0)
```

```
    sleep(1)
```

```
    if success:
```

```
        print( 'Published alert4 : ' , "Flame is detected crops are in  
danger,sprinklers turned ON","to IBM Watson")
```



#To send alert message if Moisture level is LOW and to Turn ON Motor-1 for irrigation.

```
if (moist_level < 20):
```

```
    print("Motor-1 is ON")
```

```
    success = deviceCli.publishEvent("Alert5", "json", { 'alert5' : "Moisture level(%s) is low, Irrigation started" %moist_level }, qos=0)
```

```
    sleep(1)
```

```
    if success:
```

```
        print('Published alert5 : ' , "Moisture level(%s) is low, Irrigation started" %moist_level,"to IBM Watson" )
```

```
    print("")
```

#To send alert message if Water level is HIGH and to Turn ON Motor-2 to take water out.

```
if (water_level > 20):
```

```
    print("Motor-2 is ON")
```

```
    success = deviceCli.publishEvent("Alert6", "json", { 'alert6' : "Water level(%s) is high, so motor is ON to take water out "
```

```
%water_level }, qos=0)
```

```
    sleep(1)
```

```
    if success:
```

```
print('Published alert6 : ' , "water level(%s) is high, so motor is ON  
to take water out " %water_level,"to IBM Watson" )
```

```
print("")
```

```
#command recived by farmer
```

```
deviceCli.commandCallback = myCommandCallback
```

```
# Disconnect the device and application from the cloud
```

```
deviceCli.disconnect()
```