Sprint-3

DATE	18 November 2022
TEAM ID	PNT2022TMID13267
PROJECT NAME	SMART WASTE MANAGEMENT FOR METROPOLITAN CITIES

Code for wokwi to connect ibm watson

```
#include <WiFi.h>                                // library for wifi
#include <PubSubClient.h>                        // library for MQTT
#include <LiquidCrystal_I2C.h>
#include <mjson.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);

//---------------------- credentials of IBM Accounts ------------------------------
```

```
#define ORG "vi4esk"                            // IBM organisation id
#define DEVICE_TYPE "sudhan"                    // Device type mentioned in ibm watson iot
platform
#define DEVICE_ID "12345"                 // Device ID mentioned in ibm watson iot platform
#define TOKEN "12345678"              // Token
```

```
//---------------------- customise above values ---------------------------------------
-----------
```

```
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";                 // server
name
char publishTopic[] = "iot-2/evt/data/fmt/json";                                // topic name
and type of event perform and format in which data to be send
char topic[] = "iot-2/cmd/led/fmt/String";                                      // cmd
Represent type and command is test format of strings
char authMethod[] = "use-token-auth";                                           //
authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;                      //Client id
```

```
//---------------------------------------------------------------------------------------
---------------------------
```

```
WiFiClient wifiClient;                                                  // creating
instance for wificlient
PubSubClient client(server, 1883, wifiClient);
```

```
#define ECHO_PIN 12
```

```
#define TRIG_PIN 13
float dist;
String data3;
bool SealBin = true;
void setup()
{
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  //pir pin
  pinMode(34, INPUT);
```

```
  //ledpins
  pinMode(23, OUTPUT);
  pinMode(2, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(15, OUTPUT);
```

```
  lcd.init();
  lcd.backlight();
  lcd.setCursor(1, 0);
  lcd.print("");
  wifiConnect();
  mqttConnect();
}
```

```
float readcmCM()
{
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}
```

```
void loop()
 {
```

```
  lcd.clear();
```

```
  publishData();
  delay(500);
  if (!client.loop())
    {
      mqttConnect();                              // function call to connect to IBM
```

```
    }
}
```

```
/* ---------------------------------retrieving to cloud-------------------------------------
---------------*/
```

```
void wifiConnect()
{
  Serial.print("Connecting to ");
  Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED)
    {
      delay(500);
      Serial.print(".");
    }
  Serial.print("WiFi connected, IP address: ");
  Serial.println(WiFi.localIP());
}
void mqttConnect()
  {
    if (!client.connected())
      {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token))
          {
            Serial.print(".");
            delay(500);
          }
        initManagedDevice();
        Serial.println();
      }
  }
void initManagedDevice()
  {
    if (client.subscribe(topic))
      {
        Serial.println("IBM subscribe to cmd OK");
      }
    else
      {
        Serial.println("subscribe to cmd FAILED");
      }
  }
void publishData()
{
  float cm = readcmCM();
```

```
 if(digitalRead(34))                                  //pir motion detection
 {
   Serial.println("Motion Detected");
   Serial.println("Lid Opened");
   digitalWrite(15, HIGH);



if(digitalRead(34)== true)
{
 if(cm <= 100)                                                //Bin level detection
 {
   digitalWrite(2, HIGH);
   Serial.println("High Alert!!!,Trash bin is about to be full");
   Serial.println("Lid Closed");
   lcd.print("Full! Don't use");
   delay(2000);
   lcd.clear();
   digitalWrite(4, LOW);
   digitalWrite(23, LOW);
 }
 else if(cm > 100 && cm < 180)
 {
   digitalWrite(4, HIGH);
   Serial.println("Warning!!,Trash is about to cross 50% of bin level");
   digitalWrite(2, LOW);
   digitalWrite(23, LOW);

 }
 else if(cm > 180)
 {
   digitalWrite(23, HIGH);
   Serial.println("Bin is available");
   digitalWrite(2,LOW);
   digitalWrite(4, LOW);

 }
   delay(10000);
   Serial.println("Lid Closed");
}
else
{
  Serial.println("No motion detected");
   digitalWrite(2, LOW);
   digitalWrite(15, LOW);
   digitalWrite(4, LOW);
   digitalWrite(23, LOW);
}
```

```
}
  else
  {
    digitalWrite(15, LOW);

  }
```

```
  if(cm <= 100)
{
digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str()))         // if data is uploaded
to cloud successfully,prints publish ok else prints publish failed
{
Serial.println("Publish OK");
}
}
else if(cm <= 180)
{
digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cm ;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
else if(cm > 180)
{
digitalWrite(23,HIGH);
String payload = "{";
payload += cm;
```

```
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str()))         // if data is uploaded
to cloud successfully,prints publish ok else prints publish failed
{
Serial.println("Publish OK");
}
```

```
}
```

```
  float inches = (cm / 2.54);                                      //print on lcd
  lcd.setCursor(0,0);
  lcd.print("Inches");
  lcd.setCursor(4,0);
  lcd.setCursor(12,0);
  lcd.print("cm");
  lcd.setCursor(1,1);
  lcd.print(inches, 1);
  lcd.setCursor(11,1);
  lcd.print(cm, 1);
  lcd.setCursor(14,1);
  delay(1000);
  lcd.clear();
}
```

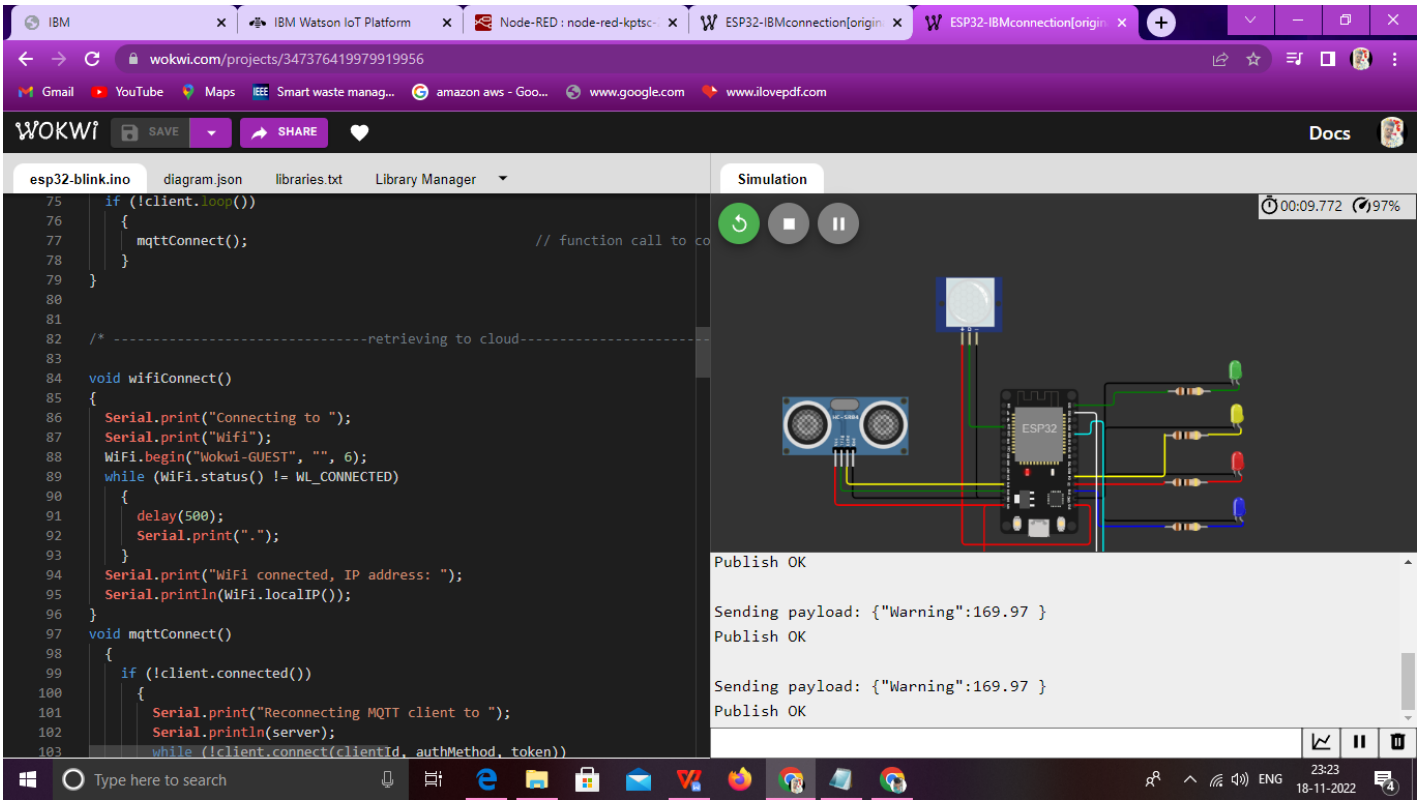
```
//handles commands from user side
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {

    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
```

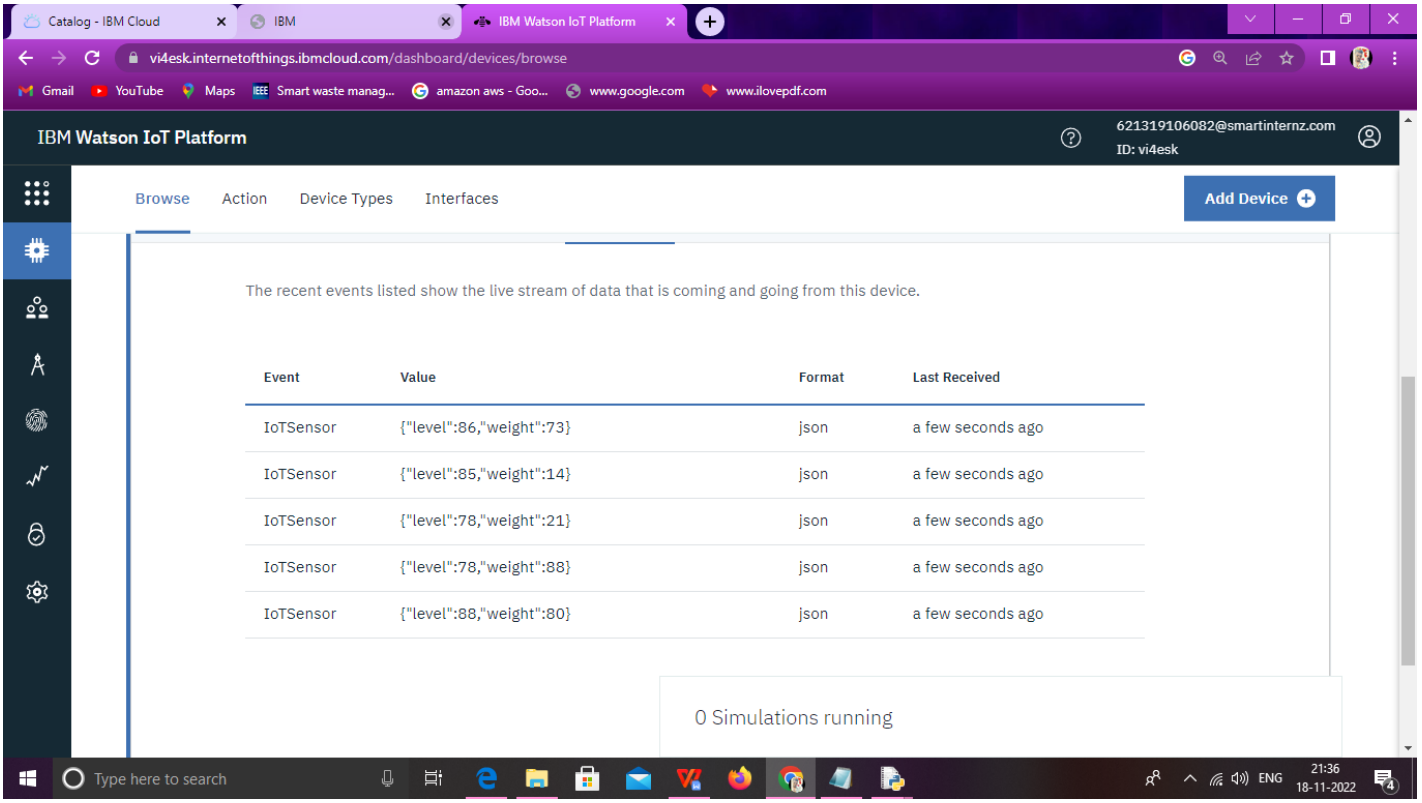
```
  const char *s =(char*) data3.c_str();
  double pincode = 0;



        const char *buf;
        int len;

        if (mjson_find(s, strlen(s), "$.command", &buf, &len))  // And print it
```

```
        {

          String command(buf,len);

          if(command=="\"SealBin\"")
          {
            SealBin = true;

          }


          }

  data3="";
}
```

Output image:



Ibm watson:


Catalog - IBM Cloud
IBM
IBM Watson IoT Platform
vi4esk.internetofthings.ibmcloud.com/dashboard/devices/browse
Gmail
YouTube
Maps
Smart waste manag...
amazon aws - Goo...
www.google.com
www.ilovepdf.com
IBM Watson IoT Platform
621319106082@smartinternz.com
ID: vi4esk
Browse
Action
Device Types
Interfaces
Add Device
The recent events listed show the live stream of data that is coming and going from this device.
Event
Value
Format
Last Received
IoTSensor
{"level":86,"weight":73}
json
a few seconds ago
IoTSensor
{"level":85,"weight":14}
json
a few seconds ago
IoTSensor
{"level":78,"weight":21}
json
a few seconds ago
IoTSensor
{"level":78,"weight":88}
json
a few seconds ago
IoTSensor
{"level":88,"weight":80}
json
a few seconds ago
0 Simulations running
Type here to search
ENG
21:36
18-11-2022