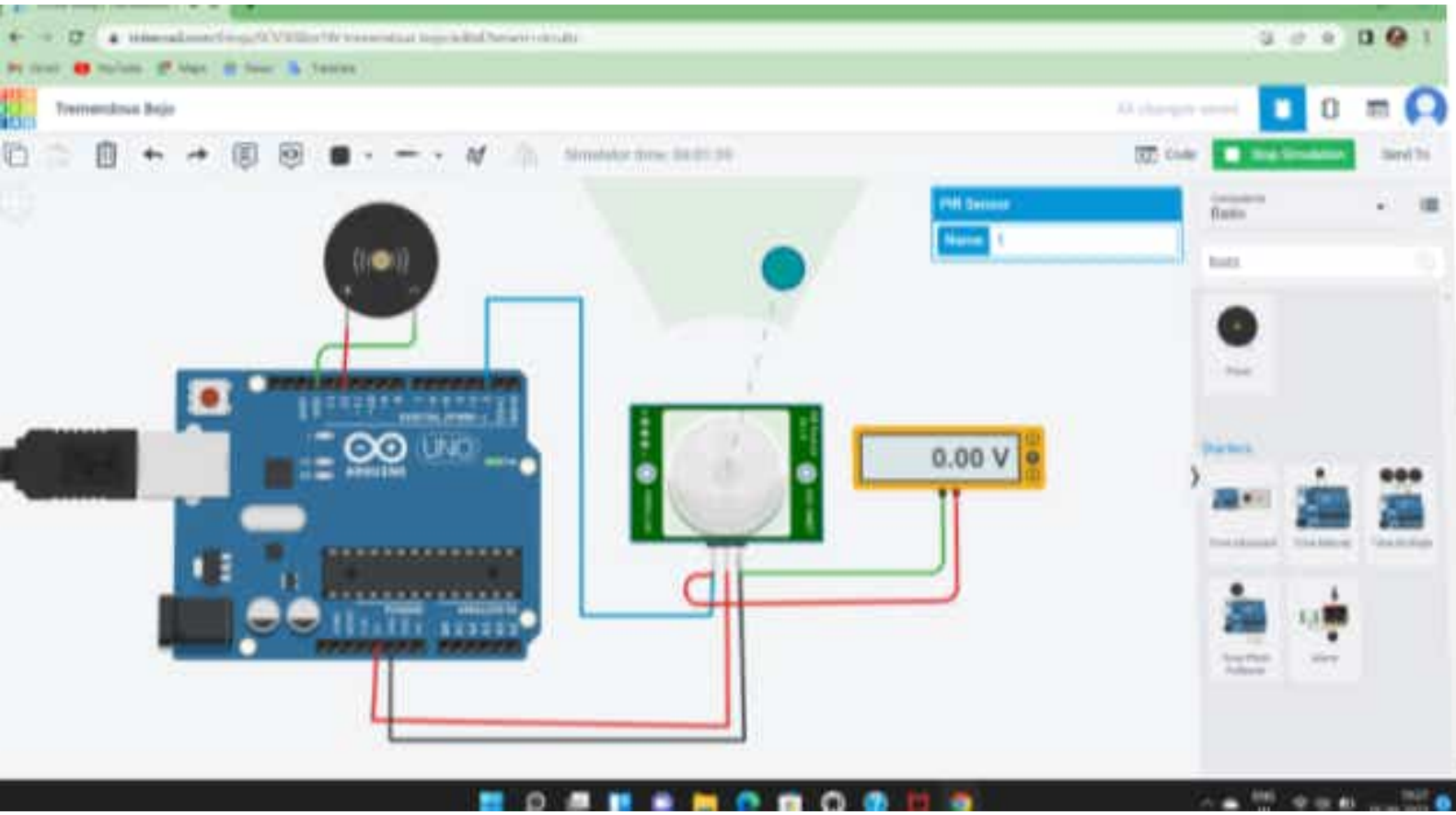
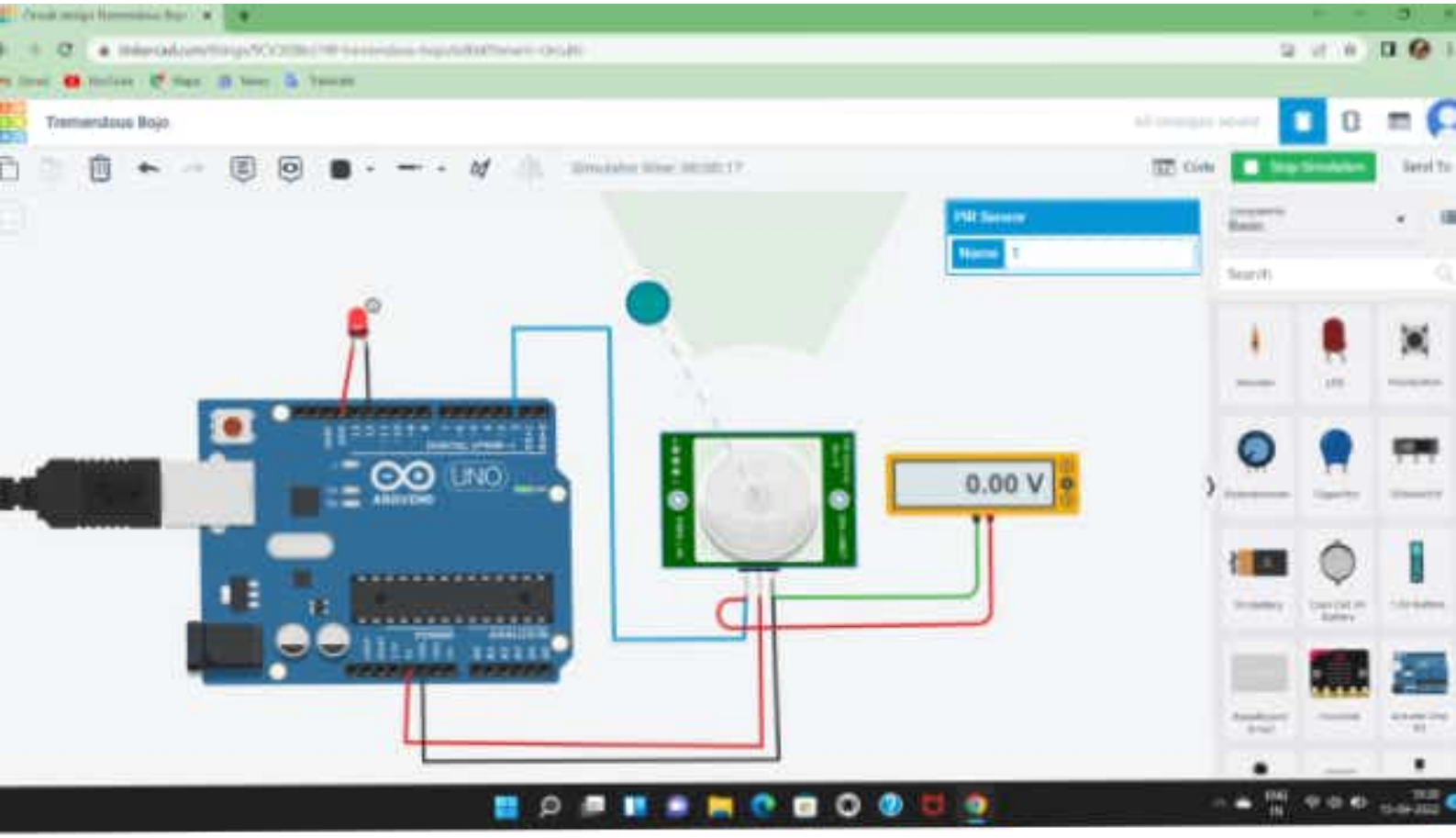

PIR Sensor
Name
0.00 V


Tremendous Bojo
Code
Stop Simulation
PIR Sensor
Name
1
UNO
0.00 V

```
// C++ code
//
void setup()
{
  pinMode(2, INPUT);
  pinMode(12, OUTPUT);
}

void loop()
{
  if (digitalRead(2) == 1) {
    digitalWrite(12, HIGH);
    delay(3000); // Wait for 3000 millisecond(s)
  } else {
    digitalWrite(12, LOW);
  }
}
```