

Assignment-4

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send "alert" to IBM cloud and display in device recent events

AssignmentDate	18 NOVEMBER 2022
StudentName	DIVYA T
StudentRollNumber	512219104005
MaximumMarks	2Marks

PROGRAM:

```
//ARDUINO PINS (TRIGGER PIN, ECHO PIN)
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//Anything over 400cm (23200 us pulse)
is "out of range" const unsigned int max_dist = 23200;

void setup(){

  //The Trigger pin will tell the sensor
  to range find pinMode(TRIG_PIN, OUTPUT);
  digitalWrite(TRIG_PIN, LOW);

  //Set Echo pin as input to measure the time duration of pulse returning back from the distance sensor pinMode(ECHO_PIN, INPUT);

  //We'll use the serial monitor to view the sensor output
  Serial.begin(9600);
```

```
}
```

```
void loop(){
```

```
    unsigned long t1; un
```

```
    signed long t2;
```

```
    unsigned long pulse_width; fl
```

```
    oat cm;
```

```
    float inches;
```

```
    // Hold the trigger pin high for at least
```

```
    10  $\mu$ s digitalWrite(TRIG_PIN, HIGH); delayMicrosecon
```

```
    ds(10);
```

```
    digitalWrite(TRIG_PIN, LOW);
```

```
    // Wait for pulse on echo pin
```

```
    while(digitalRead(ECHO_PIN) == 0);
```

```
    // Measure how long the echo pin was held high (pulse width)
```

```
    // Note: the micros() counter will overflow after ~70 min t1 = micros();
```

```
    while(digitalRead(ECHO_PIN) == 1); t2 =
```

```
    micros();
```

```
    pulse_width = t2 - t1;
```

```
    // Calculate distance in centimeters and inches. The constants
```

```
    // are found in the data sheet, and calculated from the assumed speed
```

```
    // of sound in air at sea level (~340 m/s). cm =
```

```
    pulse_width / 58.0;
```

```
    inches = pulse_width / 148.0;
```

```
    // Print out results
```

```
if(pulse_width>max_dist) {
    Serial.println("Outofrange");
}else
{Serial.println("*****")
;Serial.print("DistanceMeasured incm:");
Serial.println(cm);

if(cm<100){
    //while(true){
        Serial.println("Alert!!");
    //}
}

Serial.print("*****");
}

//Waitatleast1000msbefore
nextmeasurementdelay(1000);
}
```

OUTPUT:

WOKWI SAVE SHARE Docs SIGN IN

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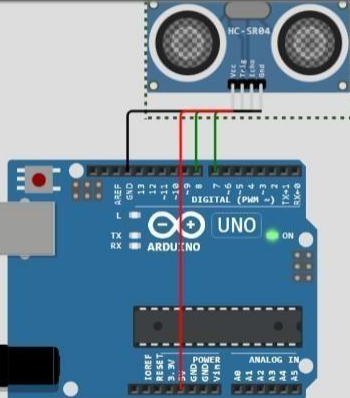
```
1
2
3
4
5 // ARDUINO PINS (TRIGGER PIN, ECHO PIN)
6 const int TRIG_PIN = 7;
7 const int ECHO_PIN = 8;
8
9 // Anything over 400 cm (23200 us pulse) is "out of range"
10 const unsigned int max_dist = 23200;
11
12 void setup() {
13
14     // The Trigger pin will tell the sensor to range find
15     pinMode(TRIG_PIN, OUTPUT);
16     digitalWrite(TRIG_PIN, LOW);
17
18     //Set Echo pin as input to measure the time duration of pulse returning back from the d
19     pinMode(ECHO_PIN, INPUT);
20
21     // We'll use the serial monitor to view the sensor output
22     Serial.begin(9600);
23 }
24
25 void loop() {
26
27     unsigned long t1;
28     unsigned long t2;
29     unsigned long pulse_width;
30     float cm;
31     float inches;
32
33     // Hold the trigger pin high for at least 10 us
34     digitalWrite(TRIG_PIN, HIGH);
```

Simulation

01:27.258 99%

Editing Ultrasonic Distance Sensor

Distance: 2cm



Distance Measured in cm : 2.07
Alert !!
Distance Measured in cm : 2.00
Alert !!

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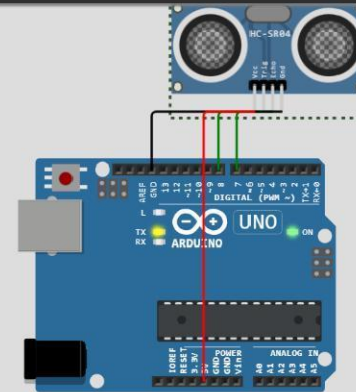
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19   pinMode(ECHO_PIN, INPUT);
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21   // We'll use the serial monitor to view the sensor output
22   Serial.begin(9600);
23 }
24
25 void loop() {
26
27   unsigned long t1;
28   unsigned long t2;
29   unsigned long pulse_width;
30   float cm;
31   float inches;
32
33   // Hold the trigger pin high for at least 10 us
34   digitalWrite(TRIG_PIN, HIGH);
```

Simulation

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Editing Ultrasonic Distance Sensor

Distance: 268cm



Distance Measured in cm : 271.79

Distance Measured in cm : 271.72

Distance Measured in cm : 271.72

Distance Measured in cm : 271.79

