

Assignment-4

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send "alert" to IBM cloud and display in device recent events

| | |
|-------------------|------------------|
| AssignmentDate | 18 NOVEMBER 2022 |
| StudentName | MAHALAKSHMI S |
| StudentRollNumber | 512219104010 |
| MaximumMarks | 2Marks |

PROGRAM:

```
//ARDUINO PINS (TRIGGER PIN, ECHO PIN)
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//Anything over 400cm (23200 us pulse)
is "out of range" const unsigned int max_dist = 23200;

void setup() {

  //The Trigger pin will tell the sensor
  pinMode(TRIG_PIN, OUTPUT);
  digitalWrite(TRIG_PIN, LOW);

  //Set Echo pin as input to measure the time duration of pulse returning back from the distance sensor
  pinMode(ECHO_PIN, INPUT);

  //We'll use the serial monitor to view the sensor output
  Serial.begin(9600);
```

```
}
```

```
void loop(){
```

```
    unsigned long t1; un
```

```
    signed long t2;
```

```
    unsigned long pulse_width; fl
```

```
    oat cm;
```

```
    float inches;
```

```
    // Hold the trigger pin high for at least
```

```
    10  $\mu$ s digitalWrite(TRIG_PIN, HIGH); delayMicrosecon
```

```
    ds(10);
```

```
    digitalWrite(TRIG_PIN, LOW);
```

```
    // Wait for pulse one chip in
```

```
    while(digitalRead(ECHO_PIN) == 0);
```

```
    // Measure how long the echo pin was held high (pulse width)
```

```
    // Note: the micros() counter will overflow after ~70 min t1 = micros();
```

```
    while(digitalRead(ECHO_PIN) == 1); t2 =
```

```
    micros();
```

```
    pulse_width = t2 - t1;
```

```
    // Calculate distance in centimeters and inches. The constants
```

```
    // are found in the data sheet, and calculated from the assumed speed
```

```
    // of sound in air at sea level (~340 m/s). cm =
```

```
    pulse_width / 58.0;
```

```
    inches = pulse_width / 148.0;
```

```
    // Print out results
```

```
if(pulse_width>max_dist) {
    Serial.println("Outofrange");
}else
{Serial.println("*****")
;Serial.print("DistanceMeasured incm:");
Serial.println(cm);

if(cm<100){
    //while(true){
        Serial.println("Alert!!");
    //}
}

Serial.print("*****");
}

//Waitatleast1000msbefore
nextmeasurementdelay(1000);
}
```

OUTPUT:

WOKWI SAVE SHARE Docs SIGN IN

sketch.ino • diagram.json • Library Manager

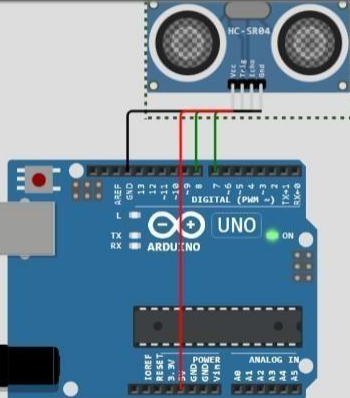
```
1
2
3
4
5 // ARDUINO PINS (TRIGGER PIN, ECHO PIN)
6 const int TRIG_PIN = 7;
7 const int ECHO_PIN = 8;
8
9 // Anything over 400 cm (23200 us pulse) is "out of range"
10 const unsigned int max_dist = 23200;
11
12 void setup() {
13
14     // The Trigger pin will tell the sensor to range find
15     pinMode(TRIG_PIN, OUTPUT);
16     digitalWrite(TRIG_PIN, LOW);
17
18     //Set Echo pin as input to measure the time duration of pulse returning back from the d
19     pinMode(ECHO_PIN, INPUT);
20
21     // We'll use the serial monitor to view the sensor output
22     Serial.begin(9600);
23 }
24
25 void loop() {
26
27     unsigned long t1;
28     unsigned long t2;
29     unsigned long pulse_width;
30     float cm;
31     float inches;
32
33     // Hold the trigger pin high for at least 10 us
34     digitalWrite(TRIG_PIN, HIGH);
```

Simulation

01:27.258 99%

Editing Ultrasonic Distance Sensor

Distance: 2cm



Distance Measured in cm : 2.07
Alert !!

Distance Measured in cm : 2.00
Alert !!

sketch.ino • diagram.json • Library Manager ▾

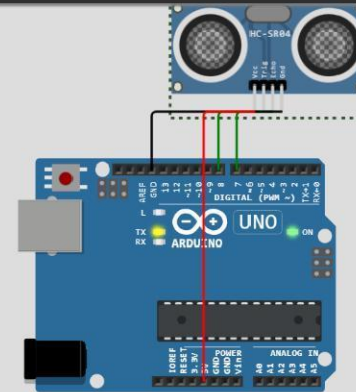
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25 void loop() {
26
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28     unsigned long t2;
29     unsigned long pulse_width;
30     float cm;
31     float inches;
32
33     // Hold the trigger pin high for at least 10 us
34     digitalWrite(TRIG_PIN, HIGH);
```

Simulation

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Editing Ultrasonic Distance Sensor

Distance: 268cm



Distance Measured in cm : 271.79

Distance Measured in cm : 271.72

Distance Measured in cm : 271.72

Distance Measured in cm : 271.79

