

## Assignment -4

### Distance Detection Using Ultrasonic Sensor

#### Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK : <https://wokwi.com/projects/345964118720643668>

#### CODE:

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQTT

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE_TYPE "ultrasonicsensor"//Device type mentioned in
ibm watson IOT Platform
#define DEVICE_ID "distancedetection"//Device ID mentioned in ibm
watson IOT Platform
#define TOKEN "ALMGaaF01nawa1QA3" //Token
String data3;
float dist;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//
Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and
type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";//
cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client
id

//
WiFiClient wifiClient; // creating the instance for wificlient
```

```

PubSubClient client(server, 1883, callback ,wifiClient);
//calling the predefined client id by passing parameter like
server id,portand wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED, OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}
void loop()// Recursive Function
{

  digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}

/*.....retrieving to
Cloud ..... */

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
    creating the String in in form JSon to update the data to
    ibm cloud
  */
  String object;

```

```

if (dist <100)
{
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\":\"";
payload += dist;
payload += "\", \"object\":\"";
payload += object;
payload += "\"}";

Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data
on the cloud then it will print publish ok in Serial monitor or
else it will print publish failed
} else {
    Serial.println("Publish failed");
}
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!!!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}
}

```

```

void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6); //passing the wifi credentials
to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }

    // Serial.println("data: "+ data3);
    // if(data3=="Near")
    // {
    // Serial.println(data3);
    // digitalWrite(LED,HIGH);

    // }

    // else
    // {
    // Serial.println(data3);

```

```

// digitalWrite(LED,LOW);

// }
data3="";

}

```

## OUTPUT:

### When object is not near to the ultrasonic sensor

The screenshot displays the Wokwi IoT simulator interface. On the left is the code editor for a sketch named 'sketch.ino'. The code includes libraries for WiFi and MQTT, defines IBM IoT credentials, and sets up a callback function for MQTT messages. It also defines an LED and a trigger pin. The main loop checks for an object using the ultrasonic sensor and sends a JSON payload to the cloud if no object is found.

On the right is the simulation window, which shows a 3D model of the ESP32 microcontroller connected to an HC-SR04 ultrasonic sensor and a red LED. The simulation is running, and the console output shows the following messages:

```

no object found
Sending payload: {"distance":403.45,"object":"No"}
Publish ok
Distancein cm233.00
no object found
Sending payload: {"distance":233.00,"object":"No"}
Publish ok

```

## Data sent to the IBM cloud device when the object is far

The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains various icons for navigation. The main content area displays a device named 'distancedetection' with a status of 'Connected' and a device type of 'ultrasonicsensor'. The device was last updated on 'Oct 19, 2022 11:56 AM'. Below this, there are tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is selected, showing a table of live stream data. The table has four columns: 'Event', 'Value', 'Format', and 'Last Received'. It lists five data points, each with a 'Data' event and a JSON value: `{"distance":235.02,"object":"No"}`. The format for all entries is 'json', and the last received time for each is 'a few seconds ago'. At the bottom of the page, there is a status bar indicating '0 Simulations running' and a pagination control showing 'Items per page 50' and '1-1 of 1 item'.

Event	Value	Format	Last Received
Data	<code>{"distance":235.02,"object":"No"}</code>	json	a few seconds ago
Data	<code>{"distance":235.02,"object":"No"}</code>	json	a few seconds ago
Data	<code>{"distance":235.02,"object":"No"}</code>	json	a few seconds ago
Data	<code>{"distance":235.02,"object":"No"}</code>	json	a few seconds ago
Data	<code>{"distance":235.02,"object":"No"}</code>	json	a few seconds ago

When object is nearer to the ultrasonic sensor

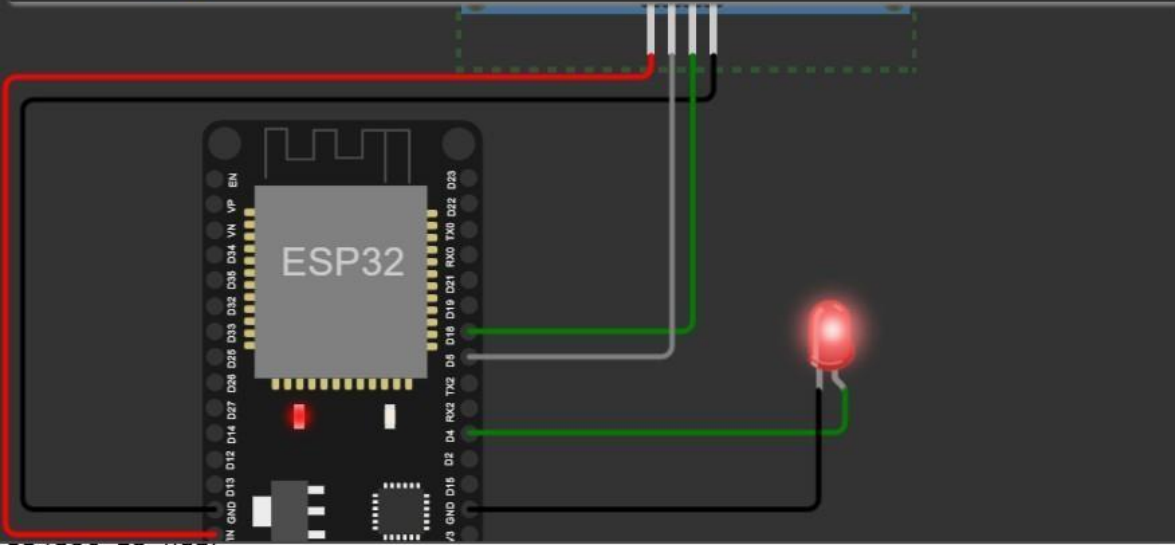
Simulation

01:03.599 94%

HC-SR04

Editing Ultrasonic Distance Sensor

Distance: 91cm



ESP32

Sending payload: {"distance":91.77,"object":"Near"}

Publish ok

Distancein cm91.77

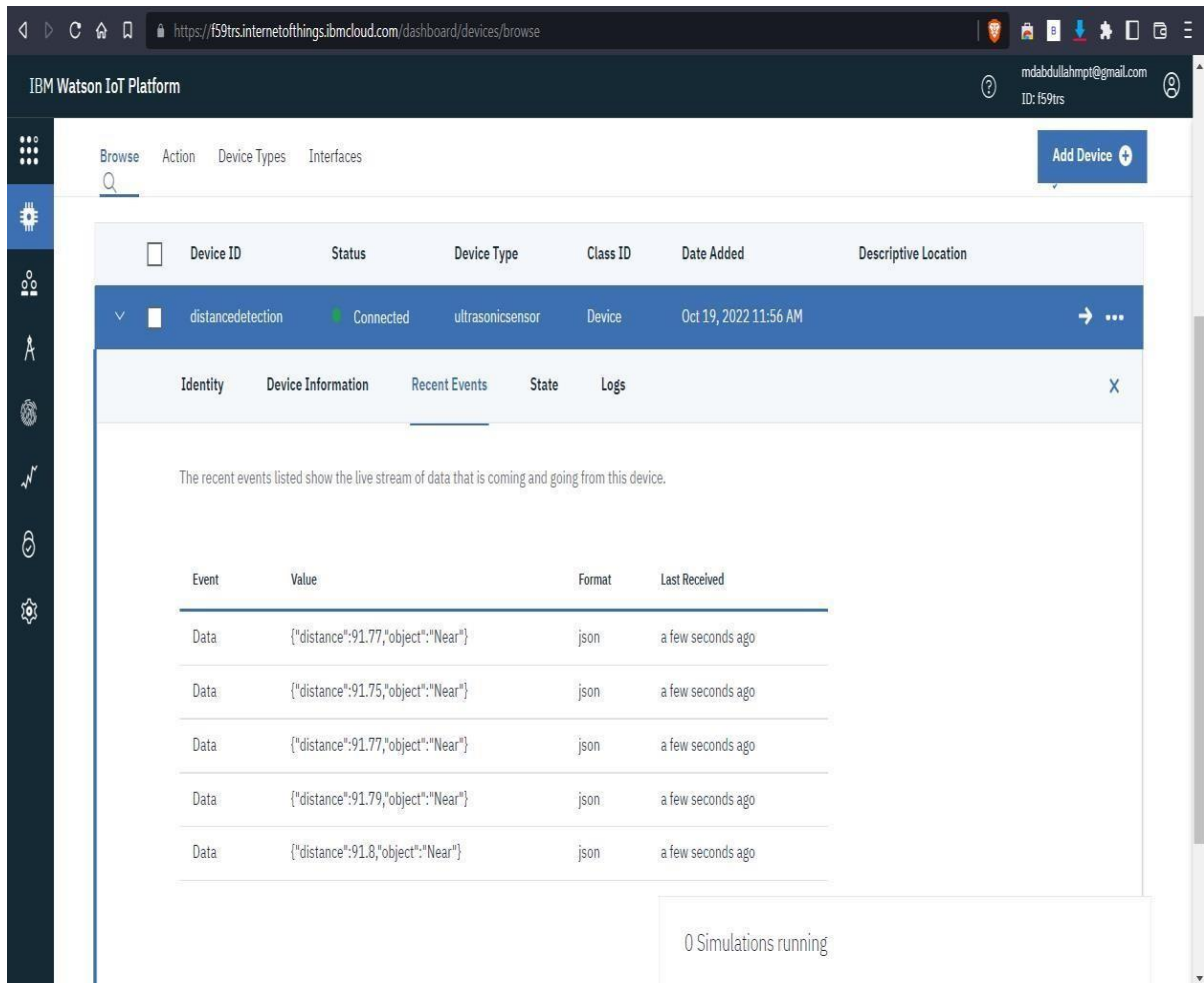
object is near

Sending payload: {"distance":91.77,"object":"Near"}

Publish ok

Distancein cm91.77

## Data sent to the IBM cloud device when the object is near



IBM Watson IoT Platform

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Browse Action Device Types Interfaces

Add Device

Device ID	Status	Device Type	Class ID	Date Added	Descriptive Location
distancedetection	Connected	ultrasonicsensor	Device	Oct 19, 2022 11:56 AM	

Identity Device Information Recent Events State Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"distance":91.77,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.75,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.77,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.79,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.8,"object":"Near"}	json	a few seconds ago

0 Simulations running

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