

Tempexample.py

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import RPi.GPIO as GPIO
import temp
import time

# initialize GPIO
GPIO.setwarnings(False)
GPIO.setmode(GPIO.BCM)
#GPIO.cleanup()

# read data using Pin GPIO21
instance = dht11.DHT11(pin=21)

while True:
    result = instance.read()
    if result.is_valid():
        print("Temp: %d C" % result.temperature + ' '+'Humid: %d %%' %
result.humidity)

        time.sleep(1)
```

temp.py

```
import time
import RPi

class tempResult:
    'temp sensor result returned by temp.read() method'

    ERR_NO_ERROR = 0
    ERR_MISSING_DATA = 1
    ERR_CRC = 2

    error_code = ERR_NO_ERROR
    temperature = -1
    humidity = -1

    def __init__(self, error_code, temperature, humidity):
        self.error_code = error_code
        self.temperature = temperature
        self.humidity = humidity

    def is_valid(self):
        return self.error_code == tempResult.ERR_NO_ERROR

class temp:
    'temp sensor reader class for Raspberry'

    __pin = 0
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def __init__(self, pin):
    self.__pin = pin

def read(self):
    RPi.GPIO.setup(self.__pin, RPi.GPIO.OUT)

    # send initial high
    self.__send_and_sleep(RPi.GPIO.HIGH, 0.05)

    # pull down to low
    self.__send_and_sleep(RPi.GPIO.LOW, 0.02)

    # change to input using pull up
    RPi.GPIO.setup(self.__pin, RPi.GPIO.IN, RPi.GPIO.PUD_UP)

    # collect data into an array
    data = self.__collect_input()

    # parse lengths of all data pull up periods
    pull_up_lengths = self.__parse_data_pull_up_lengths(data)

    # if bit count mismatch, return error (4 byte data + 1 byte
checksum)
    if len(pull_up_lengths) != 40:
        return DHT11Result(DHT11Result.ERR_MISSING_DATA, 0, 0)

    # calculate bits from lengths of the pull up periods
    bits = self.__calculate_bits(pull_up_lengths)

    # we have the bits, calculate bytes
    the_bytes = self.__bits_to_bytes(bits)

    # calculate checksum and check
    checksum = self.__calculate_checksum(the_bytes)
    if the_bytes[4] != checksum:
        return DHT11Result(DHT11Result.ERR_CRC, 0, 0)

    # ok, we have valid data, return it
    return DHT11Result(DHT11Result.ERR_NO_ERROR, the_bytes[2],
the_bytes[0])

def __send_and_sleep(self, output, sleep):
    RPi.GPIO.output(self.__pin, output)
    time.sleep(sleep)

def __collect_input(self):
    # collect the data while unchanged found
    unchanged_count = 0

    # this is used to determine where is the end of the data
    max_unchanged_count = 100

    last = -1
    data = []

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while True:
    current = RPi.GPIO.input(self.__pin)
    data.append(current)
    if last != current:
        unchanged_count = 0
        last = current
    else:
        unchanged_count += 1
        if unchanged_count > max_unchanged_count:
            break

return data

def __parse_data_pull_up_lengths(self, data):
    STATE_INIT_PULL_DOWN = 1
    STATE_INIT_PULL_UP = 2
    STATE_DATA_FIRST_PULL_DOWN = 3
    STATE_DATA_PULL_UP = 4
    STATE_DATA_PULL_DOWN = 5

    state = STATE_INIT_PULL_DOWN

    lengths = [] # will contain the lengths of data pull up periods
    current_length = 0 # will contain the length of the previous
period

    for i in range(len(data)):

        current = data[i]
        current_length += 1

        if state == STATE_INIT_PULL_DOWN:
            if current == RPi.GPIO.LOW:
                # ok, we got the initial pull down
                state = STATE_INIT_PULL_UP
                continue
            else:
                continue
        if state == STATE_INIT_PULL_UP:
            if current == RPi.GPIO.HIGH:
                # ok, we got the initial pull up
                state = STATE_DATA_FIRST_PULL_DOWN
                continue
            else:
                continue
        if state == STATE_DATA_FIRST_PULL_DOWN:
            if current == RPi.GPIO.LOW:
                # we have the initial pull down, the next will be the
data pull up
                state = STATE_DATA_PULL_UP
                continue
            else:
                continue
        if state == STATE_DATA_PULL_UP:

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        if current == RPi.GPIO.HIGH:
            # data pulled up, the length of this pull up will
determine whether it is 0 or 1
            current_length = 0
            state = STATE_DATA_PULL_DOWN
            continue
        else:
            continue
    if state == STATE_DATA_PULL_DOWN:
        if current == RPi.GPIO.LOW:
            # pulled down, we store the length of the previous
pull up period
            lengths.append(current_length)
            state = STATE_DATA_PULL_UP
            continue
        else:
            continue

    return lengths

def __calculate_bits(self, pull_up_lengths):
    # find shortest and longest period
    shortest_pull_up = 1000
    longest_pull_up = 0

    for i in range(0, len(pull_up_lengths)):
        length = pull_up_lengths[i]
        if length < shortest_pull_up:
            shortest_pull_up = length
        if length > longest_pull_up:
            longest_pull_up = length

    # use the halfway to determine whether the period it is long or
short
    halfway = shortest_pull_up + (longest_pull_up - shortest_pull_up)
/ 2

    bits = []

    for i in range(0, len(pull_up_lengths)):
        bit = False
        if pull_up_lengths[i] > halfway:
            bit = True
        bits.append(bit)

    return bits

def __bits_to_bytes(self, bits):
    the_bytes = []
    byte = 0

    for i in range(0, len(bits)):
        byte = byte << 1
        if (bits[i]):
            byte = byte | 1

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        else:
            byte = byte | 0
        if ((i + 1) % 8 == 0):
            the_bytes.append(byte)
            byte = 0

    return the_bytes

def __calculate_checksum(self, the_bytes):
    return the_bytes[0] + the_bytes[1] + the_bytes[2] + the_bytes[3]
& 255
```