## Project Development Phase Sprint - 2

Date	06 November 2022
Team ID	PNT2022TMID35960
Project	Project – Intelligent Vehicle Damage Assessment & Cost Estimator
Name	for Insurance Companies

## Model Building – Level of Damage:

Kaggle code Link: https://www.kaggle.com/code/balasubramaniankn/level-of-damage

## **Importing Phase:**

```
from tensorflow.keras.layers import Input,Dense,Flatten, Dropout
from tensorflow.keras.models import Model,Sequential
from tensorflow.keras.applications.vgg16 import VGG16,preprocess_input
from matplotlib import pyplot as plt
import numpy as np
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator
import os
from tensorflow.keras.preprocessing.image import img_to_array
from tensorflow.keras.preprocessing.image import load_img
import cv2
import shutil
import random
```

#### **Data Collection:**

#### Input (21.26 MB) Data Sources ▼ Car\_damage ▼ □ Car damage ▼ body ▶ 🗖 00-front 01-rear ▶ 🗖 02-side validation ▼ level ▼ training ▶ 🗖 01-minor • 02-moderate 03-severe validation

#### **Creation of Directories:**

Different directories are created such as Main, Augment, Training and Validation and performed move and store operations respectively.

```
# creating directory
os.mkdir('./level')
os.mkdir('./level/training')
os.mkdir('./level/training/imgaug-minor')
os.mkdir('./level/training/imgaug-moderate')
os.mkdir('./level/training/imgaug-severe')
os.mkdir('./level/Main')
os.mkdir('./level/Main/real-minor')
os.mkdir('./level/Main/real-moderate')
os.mkdir('./level/Main/real-severe')
os.mkdir('./level/validation')
os.mkdir('./level/validation/imgaug-minor')
os.mkdir('./level/validation/imgaug-moderate')
os.mkdir('./level/validation/imgaug-severe')
os.mkdir('./level/Augment')
os.mkdir('./level/Augment/imgaug-minor')
os.mkdir('./level/Augment/imgaug-moderate')
os.mkdir('./level/Augment/imgaug-severe')
```

Output (174.4MB / 19.5GB)	
Victor (174.4MB / 19.5GB)  Victor /kaggle/working Victor level Victor Augment Victor imgaug-minor Victor imgaug-moderate Victor imgaug-severe	□ ଘ ଘ ଘ ଘ ଘ ଘ ଘ
validation	<b>65</b>
training training	۵5
) Main	<b>6</b> 5

#### **Merging of Dataset:**

To merge both training and validation image data into one in to the Main directory sub folders to perform together augmentation.

#### 1) Training data:

```
path_minor = "../input/car-damage/Car damage/level/training/01-minor"
dir_list_mi = os.listdir(path_minor)
path_moderate = '../input/car-damage/Car damage/level/training/02-moderate'
dir_list_mo = os.listdir(path moderate)
path_severe = '../input/car-damage/Car damage/level/training/03-severe'
dir_list_s = os.listdir(path_severe)
for j in dir list mi:
    IMAGE PATH = path minor+'/'+j
    image = cv2.imread(IMAGE PATH)
    path = './level/Main/real-minor'
    cv2.imwrite(os.path.join(path,j), image)
for j in dir_list_mo:
    IMAGE PATH = path moderate+'/'+j
    image = cv2.imread(IMAGE_PATH)
    path = './level/Main/real-moderate'
    cv2.imwrite(os.path.join(path,j), image)
for j in dir_list_s:
    IMAGE_PATH = path_severe+'/'+j
    image = cv2.imread(IMAGE PATH)
    path = './level/Main/real-severe'
    cv2.imwrite(os.path.join(path,j), image)
```

#### 2) validation data:

```
path_minorv = "../input/car-damage/Car damage/level/validation/01-minor"
dir_list_miv = os.listdir(path_minorv)
path_moderatev = '../input/car-damage/Car damage/level/validation/02-moderate'
dir_list_mov = os.listdir(path_moderatev)
path_severev = '../input/car-damage/Car damage/level/validation/03-severe'
dir_list_sv = os.listdir(path_severev)

for j in dir_list_miv:
    IMAGE_PATH = path_minorv+'/'+j
    image = cv2.imread(IMAGE_PATH)
    path = './level/Main/real-minor'
    cv2.imwrite(os.path.join(path,j), image)

for j in dir_list_mov:
    IMAGE_PATH = path_moderatev+'/'+j
```

```
image = cv2.imread(IMAGE_PATH)
  path = './level/Main/real-moderate'
  cv2.imwrite(os.path.join(path,j), image)

for j in dir_list_sv:
  IMAGE_PATH = path_severev+'/'+j

  image = cv2.imread(IMAGE_PATH)
  path = './level/Main/real-severe'
  cv2.imwrite(os.path.join(path,j), image)
```

#### Image Augmentation:

To perform shifting, Right rotation and horizontal flip on all the images and store the result in the augment directory.

```
#Augmenting and saving train level minor view images
OUTPUT_DIRECTORY = './level/Augment/imgaug-minor'
# Get the list of all files and directories
path minor = "./level/Main/real-minor"
dir list = os.listdir(path minor)
for j in dir_list:
    IMAGE_PATH = path_minor+'/'+j
    image = cv2.imread(IMAGE PATH)
    path = './level/Augment/imgaug-minor'
    cv2.imwrite(os.path.join(path,j), image)
    image = load img(IMAGE PATH)
    image = img_to_array(image)
    image = np.expand_dims(image, axis=0)
   datagen shift = ImageDataGenerator(height shift range=0.2, width shift range=
0.2)
   PREFIX = 'Shifted'
    imGen = datagen_shift.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTOR
Υ,
                        save prefix=PREFIX, save format='jpg')
    for i in range(6):
        batch = imGen.next()
   datagen_rot = ImageDataGenerator(rotation_range=30)
    PREFIX = 'Rotated'
    imGen = datagen_rot.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTORY,
                        save prefix=PREFIX, save format='jpg')
    for i in range(6):
        batch = imGen.next()
    datagen_hf = ImageDataGenerator(horizontal_flip=True)
```

```
#Augmenting and saving train level moderate view images
OUTPUT DIRECTORY = './level/Augment/imgaug-moderate'
# Get the list of all files and directories
path_mod = "./level/Main/real-moderate"
dir list = os.listdir(path mod)
for j in dir list:
    IMAGE_PATH = path_mod+'/'+j
    image = cv2.imread(IMAGE PATH)
    path = './level/Augment/imgaug-moderate'
    cv2.imwrite(os.path.join(path,j), image)
    image = load img(IMAGE PATH)
    image = img to array(image)
    image = np.expand_dims(image, axis=0)
   datagen shift = ImageDataGenerator(height shift range=0.2, width shift range=
0.2)
   PREFIX = 'Shifted'
    imGen = datagen_shift.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTOR
Υ,
                        save prefix=PREFIX, save format='jpg')
    for i in range(6):
        batch = imGen.next()
    datagen rot = ImageDataGenerator(rotation range=30)
    PREFIX = 'Rotated'
    imGen = datagen_rot.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTORY,
                        save_prefix=PREFIX, save_format='jpg')
    for i in range(6):
        batch = imGen.next()
    datagen_hf = ImageDataGenerator(horizontal_flip=True)
    PREFIX = 'Hortizonal_flip'
    imGen = datagen_hf.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTORY,
                        save_prefix=PREFIX, save_format='jpg')
    for i in range(1):
        batch = imGen.next()
```

```
#Augmenting and saving train level severe view images

OUTPUT_DIRECTORY = './level/Augment/imgaug-severe'
```

```
# Get the list of all files and directories
path sev = "./level/Main/real-severe"
dir_list = os.listdir(path_sev)
for j in dir list:
    IMAGE_PATH = path sev+'/'+j
    image = cv2.imread(IMAGE_PATH)
    path = './level/Augment/imgaug-side'
    cv2.imwrite(os.path.join(path,j), image)
    image = load img(IMAGE PATH)
    image = img to array(image)
    image = np.expand dims(image, axis=0)
   datagen_shift = ImageDataGenerator(height_shift_range=0.2, width_shift_range=
0.2)
   PREFIX = 'Shifted'
    imGen = datagen_shift.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTOR
Υ,
                        save_prefix=PREFIX, save_format='jpg')
   for i in range(6):
        batch = imGen.next()
    datagen_rot = ImageDataGenerator(rotation_range=30)
    PREFIX = 'Rotated'
    imGen = datagen_rot.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTORY,
                        save prefix=PREFIX, save format='jpg')
    for i in range(6):
        batch = imGen.next()
    datagen_hf = ImageDataGenerator(horizontal_flip=True)
    PREFIX = 'Hortizonal flip'
    imGen = datagen_hf.flow(image, batch_size=1, save_to_dir = OUTPUT_DIRECTORY,
                        save prefix=PREFIX, save format='jpg')
    for i in range(1):
        batch = imGen.next()
```

## **Splitting of Dataset:**

To split the augmented image in the ratio of 80:20 and store it in respective folders and sub folders.

```
# Split the minor level data in 80:20 ratio
no_of_minor = os.listdir('./level/Augment/imgaug-minor')
len(no_of_minor)
augment_data = './level/Augment/imgaug-minor'
for f in no_of_minor:
    if random.random() > 0.80:
        shutil.move(f'{augment_data}/{f}','./level/validation/imgaug-minor')
```

```
else:
    shutil.move(f'{augment_data}/{f}','./level/training/imgaug-minor')
```

```
# Split the moderate level data in 80:20 ratio
no_of_mod = os.listdir('./level/Augment/imgaug-moderate')
augment data = './level/Augment/imgaug-moderate'
for f in no_of_mod:
    if random.random() > 0.80:
        shutil.move(f'{augment_data}/{f}','./level/validation/imgaug-moderate' )
    else:
        shutil.move(f'{augment data}/{f}','./level/training/imgaug-moderate')
# Split the severe level data in 80:20 ratio
no_of_sev = os.listdir('./level/Augment/imgaug-severe')
augment_data = './level/Augment/imgaug-severe'
for f in no of sev:
    if random.random() > 0.80:
        shutil.move(f'{augment_data}/{f}','./level/validation/imgaug-severe' )
    else:
        shutil.move(f'{augment_data}/{f}','./level/training/imgaug-severe')
```

## Flow from Directory – Augmentation:

To store the path of the train and validating data.

```
img_size = [224,224] #List which stores the resolution
main_train = './level/training' #Stores the path of the train directory
main_test = './level/validation' #Stores the path of the test directory
```

To modify the train and validation data with respect to the properties.

```
Found 10216 images belonging to 3 classes.
Found 2551 images belonging to 3 classes.
```

# Class\_indices will display the respective class value
training\_set.class\_indices

```
Out[13]: {'imgaug-front': 0, 'imgaug-rear': 1, 'imgaug-side': 2}
```

## **Model Building:**

- Loading the VGG16 pre trained model.
- Include\_top this specifies whether the final layer before the output layer has to be include.
- If included then there will be 1000 number of classes at the output. # Weights are trained using imagenet

```
vgg_model = VGG16(include_top=False,
    weights="imagenet",
    input_shape=img_size + [3])
```

# # To print the hidden layer summary of vgg model without top layer vgg\_model.summary()

Layer (type)	Output Shape	Param #
input_1 (InputLayer)		
block1_conv1 (Conv2D)	(None, 224, 224, 64)	1792
block1_conv2 (Conv2D)	(None, 224, 224, 64)	
block1_pool (MaxPooling2D)	(None, 112, 112, 64)	0
block2_conv1 (Conv2D)	(None, 112, 112, 128)	73856
block2_conv2 (Conv2D)	(None, 112, 112, 128)	147584
block2_pool (MaxPooling2D)	(None, 56, 56, 128)	
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168
block3_conv2 (Conv2D)	(None, 56, 56, 256)	 590080

plock4_conv3 (Conv2D) (None, 28, 28, 512) 2359808  plock4_pool (MaxPooling2D) (None, 14, 14, 512) 0  plock5_conv1 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv2 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808  plock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  fotal params: 14,714,688  frainable params: 14,714,688	block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
plock4_pool (MaxPooling2D) (None, 14, 14, 512) 0 plock5_conv1 (Conv2D) (None, 14, 14, 512) 2359808 plock5_conv2 (Conv2D) (None, 14, 14, 512) 2359808 plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808 plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808 plock5_pool (MaxPooling2D) (None, 7, 7, 512) 0 plock5_pool	block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808
plock4_pool (MaxPooling2D) (None, 14, 14, 512) 0  plock5_conv1 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv2 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808  plock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  fotal params: 14,714,688  Trainable params: 14,714,688			
plock5_conv2 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808  plock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  Total params: 14,714,688  Trainable params: 14,714,688			
plock5_conv2 (Conv2D) (None, 14, 14, 512) 2359808  plock5_conv3 (Conv2D) (None, 14, 14, 512) 2359808  plock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  fotal params: 14,714,688  Trainable params: 14,714,688			
olock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  Total params: 14,714,688  Trainable params: 14,714,688			
olock5_pool (MaxPooling2D) (None, 7, 7, 512) 0  Total params: 14,714,688  Trainable params: 14,714,688			
otal params: 14,714,688 rainable params: 14,714,688	block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0
rainable params: 14,714,688			
lon-trainable params: 0	Trainable params: 14,714,688		
	Non-trainable params: 0		

```
# To fix the weights of the pre trained model
for lay in vgg_model.layers:
    lay.trainable = False

# Flatten() is used to convert the last layer to vector or as fully connected
x = Flatten(name="first_flatten")(vgg_model.output)
# Dense() layer is added such that it outputs only two classess
# Softmax activation layer produces probabilities for different classess.
x = Dropout(0.5)(x)
pred = Dense(3,activation='softmax')(x)
# Model() is used to group layers
model = Model(inputs=vgg_model.input,outputs=pred)
model.summary()
```

```
first_flatten (Flatten) (None, 25088) 0

dropout (Dropout) (None, 25088) 0

dense (Dense) (None, 3) 75267

Total params: 14,789,955
Trainable params: 75,267
Non-trainable params: 14,714,688
```

## **Model Fitting:**

- Loss function is used to find the errors or deviations in learning process.
- Optimizer is used to optimize the input weights.
- Metrics is used to measure the performance

```
model.compile(optimizer="adam",
    loss="categorical_crossentropy",
    metrics=['accuracy'])
```

Training the model for 8 epochs:

```
0.5368 - val_loss: 0.5413 - val_accuracy: 0.7882
Epoch 2/8
100/100 [============ ] - 38s 376ms/step - loss: 0.5157 - accuracy:
0.7891 - val_loss: 0.4553 - val_accuracy: 0.8209
Epoch 3/8
100/100 [============ ] - 37s 370ms/step - loss: 0.3666 - accuracy:
0.8547 - val_loss: 0.3729 - val_accuracy: 0.8661
Epoch 4/8
0.8837 - val_loss: 0.3692 - val_accuracy: 0.8580
Epoch 5/8
0.9017 - val_loss: 0.3201 - val_accuracy: 0.8778
Epoch 6/8
100/100 [=============] - 37s 373ms/step - loss: 0.2278 - accuracy:
0.9215 - val_loss: 0.3148 - val_accuracy: 0.8830
Epoch 7/8
0.9271 - val_loss: 0.3125 - val_accuracy: 0.8818
Epoch 8/8
0.9247 - val_loss: 0.2934 - val_accuracy: 0.8931
```

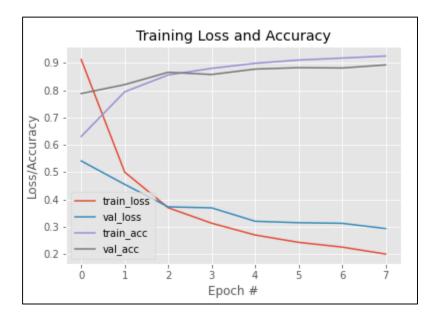
## Saving the Model:

```
# To save the particular model in .h5 format
import tensorflow as tf
from tensorflow.keras.models import load_model
model.save('vggmodelfinallevel.h5')
```

#### **Model Visualization:**

```
from matplotlib import pyplot as plt
N = 8
plt.style.use("ggplot")
plt.figure()
plt.plot(np.arange(0, N), mod.history["loss"], label="train_loss")
plt.plot(np.arange(0, N), mod.history["val_loss"], label="val_loss")
plt.plot(np.arange(0, N), mod.history["accuracy"], label="train_acc")
plt.plot(np.arange(0, N), mod.history["val_accuracy"], label="val_acc")
```

```
plt.title("Training Loss and Accuracy")
plt.xlabel("Epoch #")
plt.ylabel("Loss/Accuracy")
plt.legend(loc="lower left")
plt.savefig('grp.png')
```



It is evident from the graph that the model is not overfitting and it near to best fit. The validation accuracy obtained is 89%.

## **Model Testing:**

1)

```
from tensorflow.keras.preprocessing import image
img12 =image.load_img('../input/car-damage/Car damage/level/validation/01-minor/0
010.JPEG',target_size=(224,224))
plt.imshow(img12)
img12 = image.img_to_array(img12)
img12 = img12/255.0
img12 = np.expand_dims(img12,axis=0)
pred1 = model.predict(img12)
print(pred1)
pred1 = np.argmax(pred1,axis=1)
if pred1[0] == 1:
    print("Moderate")
elif pred1[0] == 0:
```

```
print("Minor")
else:
   print("Severe")
```



## 2)

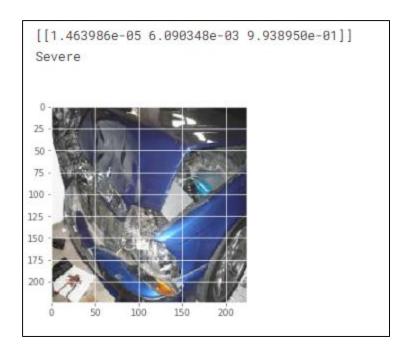
```
img12 =image.load_img('../input/car-damage/Car damage/level/validation/02-moderat
e/0006.JPEG',target_size=(224,224))
plt.imshow(img12)
img12 = image.img_to_array(img12)
img12 = img12/255.0
img12 = np.expand_dims(img12,axis=0)
pred1 = model.predict(img12)
print(pred1)
pred1 = np.argmax(pred1,axis=1)

if pred1[0] == 1:
    print("Moderate")
elif pred1[0] == 0:
    print("Minor")
else:
    print("Severe")
```

```
3)
```

```
img12 =image.load_img('../input/car-damage/Car damage/level/validation/03-severe/
0009.JPEG',target_size=(224,224))
plt.imshow(img12)
img12 = image.img_to_array(img12)
img12 = img12/255.0
img12 = np.expand_dims(img12,axis=0)
pred1 = model.predict(img12)
print(pred1)
pred1 = np.argmax(pred1,axis=1)

if pred1[0] == 1:
    print("Moderate")
elif pred1[0] == 0:
    print("Minor")
else:
    print("Severe")
```



## **Building Application:**

Creation of web pages without integrating with the flask module:

## Index.html

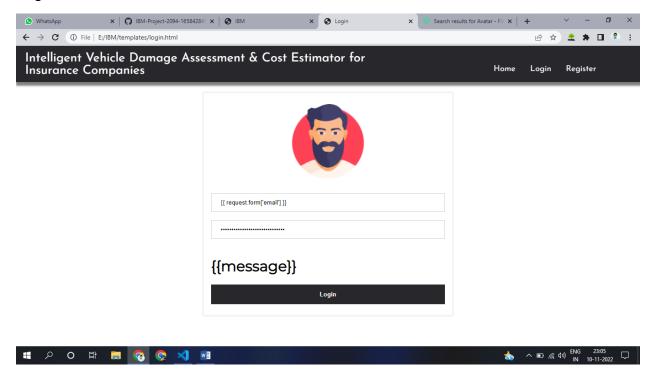


## **ABOUT PROJECT**

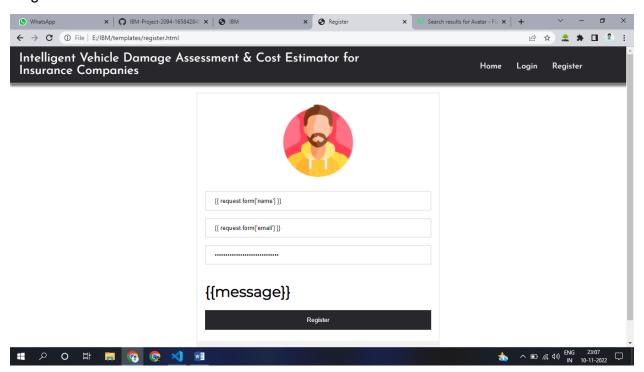
In the Recent times a lot of money is being wasted in the car insurance business due to leakage claims. Claims leakage Underwriting leakage is characterized as the discrepancy between the actual payment of claims made and the sum that should have been paid if all of the industry's leading practices were applied. Visual examination and testing have been used to may these results. However, they impose delays in the processing of claims. Here we try to auto mate the procedure. Using this automation, we can avoid time conception for the insurance claim parties.



## Login.html



## Register.html



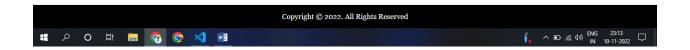
## Logout.html



## **Successfully Logged Out...**

Login For More Information

Click Here To Login



#### Prediction.html

