## **ASSIGNMENT-4**

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**DOMAIN** : IOT

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an"alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

## **Solution:**

```
#include <WiFi.h>
#include
<PubSubClient.h>
#include
<ArduinoJson.h>
WiFiClient
wifiClient;#define
ORG "kr9fjo"
#define DEVICE_TYPE "TestDeviceType"
#define DEVICE_ID "12345"
#define TOKEN "VJsSC148dk1dCN3UqS"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/abcd_1/fmt/json";
char topic[] = "iot-
2/cmd/home/fmt/String";char authMethod[]
= "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883,
wifiClient);void publishData();
const int
trigpin=5; const
int echopin=18;
String command;
String data="";
String
lat="14.167589";
String
lon="80.248510";
```

```
String
  name="point2";
  String icon="";
  long
  duration;
  int dist;
        void setup()
  {
Serial.begin(115200);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
  }
 void loop() {
    publishData
    ();
    delay(500);
    if
      (!client.loop())
      {mqttConnect();
    }
  }
  void wifiConnect() {
    Serial.print("Connecting to ");
    Serial.print("Wifi");WiFi.begin("Wokwi-GUEST", "",
    6);
    while (WiFi.status() != WL_CONNECTED)
      {delay(500);
      Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
  }
  void mqttConnect() {
    if (!client.connected()) {
      Serial.print("Reconnecting MQTT client to "); Serial.println(server);
      while (!client.connect(clientId, authMethod, token)) {
        Serial.print(".
        ");
        delay(1000);
      initManagedDevice();
      Serial.println();
    }}
```

```
void initManagedDevice() {
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
          } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){</pre>
    dist=100-
    dist;
    icon="fa-
    trash";
  }else{
    dist=0;
    icon="fa-trash-o";
  }
  DynamicJsonDocument
  doc(1024);String payload;
  doc["Name"]=name;
  doc["Latitude"]=lat;
  doc["Longitude"]=lon;
  doc["Icon"]=icon;
  doc["FillPercent"]=dist;
  serializeJson(doc,
  payload); delay(3000);
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
  } else {
    Serial.println("Publish FAILED");
  }
}
```

## **OUTPUT:**



