ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Question1:

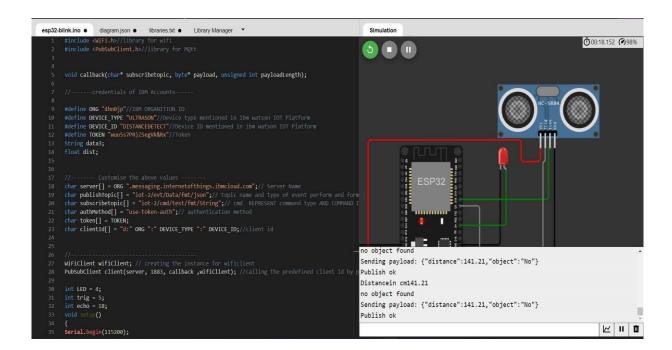
Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events

CODE:

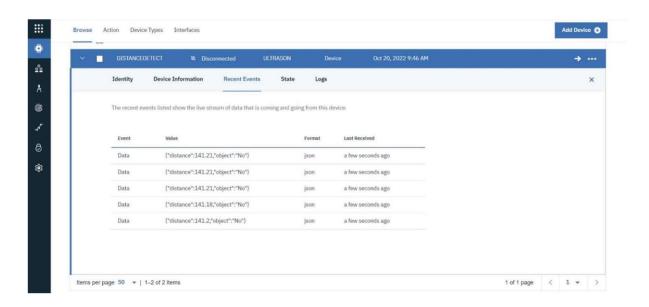
```
esp32-blink.ino
                 diagram.json •
                                  libraries.txt ●
                                                 Library Manager
       pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
          mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino
                    diagram.json •
                                       libraries.txt ●
                                                       Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL_CONNECTED) {
            delay(500);
            Serial.print(".");
          Serial.println("");
          Serial.println("WiFi connected");
          Serial.println("IP address: ");
Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {
   //Serial.print((char)payload[i]);</pre>
            data3 += (char)payload[i];
```

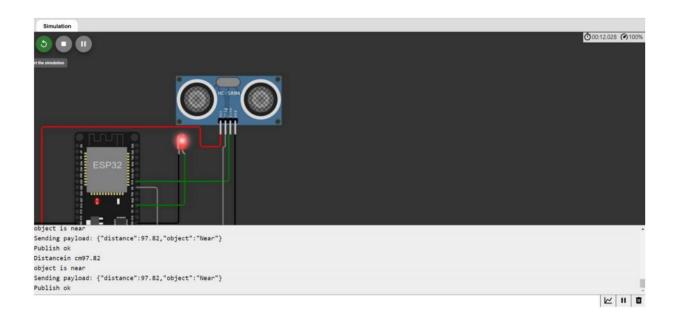
OUTPUT:



Data send to the IBM cloud device when the object is far



When object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

