

## IBM ASSIGNMENT- 4

**TEAM ID: PNT2022TMID26661**

**NAME:SARAN KUMAR.S**

**ROLL NO: 212919106078**

**Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.**

**Solution:**

```
//Pins
```

```
const int TRIG_PIN = 7 ;
```

```
const int ECHO_PIN = 8;
```

```
//Anything over 400 cm (23200 us pulse) is "out of  
range" const unsigned int MAX_DIST = 23200;
```

```
void setup() {
```

```
// The Trigger pin will tell the sensor to  
range find Pin Mode(TRIG_PIN, OUTPUT);  
digital Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the
duration of //pulses coming back from the
distance sensor pinMode(ECHO_PIN,
INPUT );

// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}

void loop() {
unsigned long t1;
unsigned long t2;
unsigned long
pulse_width; float
cm; float inches;

// Hold the trigger pin high for at least 10
us digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);

// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN
)==0 );
```

```

// Measure how long the echo pin was held high
(pulse width) // Note: the micros() counter will
overflow after 70 min t1= micros ();

while (digitalRead(ECHO_PIN)
== 1);      t2= micros ();
pulse_width = t2-t1;

// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed
speed
// of sound in air at sea level (-
340m/s) cm=pulse_Width / 58 ;
inches = pulse_width/148.0;

// Print out results if
(pulse_width >MAX _ DIST
){
Serial.println("Out of range");
} else {
Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

```

```

if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
    //}
}

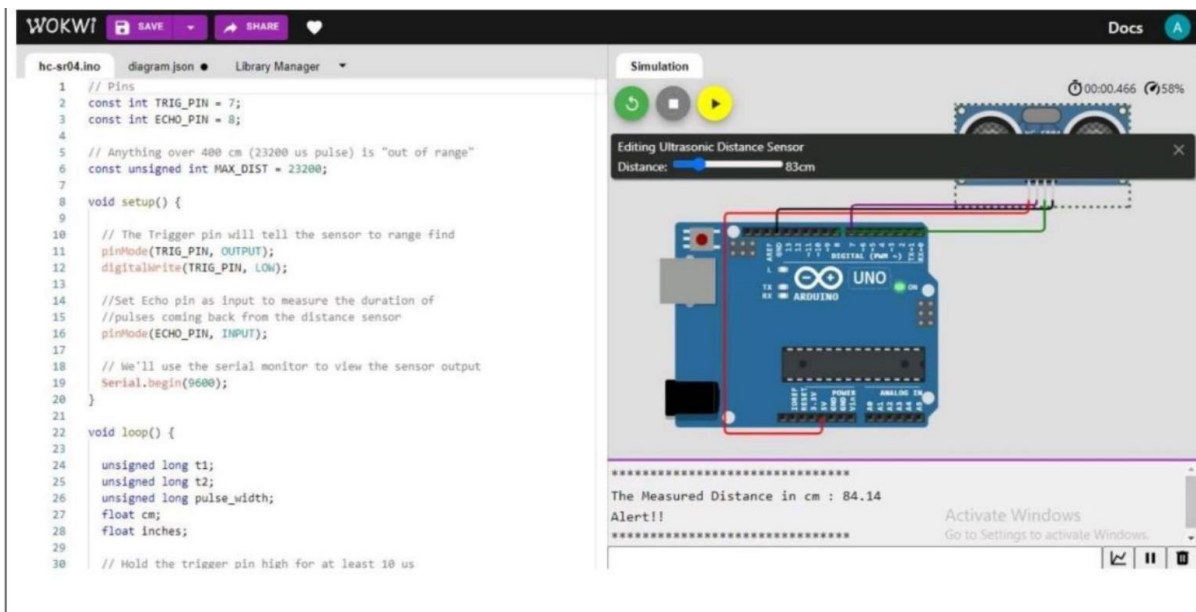
Serial.print("*****");
}

//wait at least 1000ms before next measurement
Delay(1000);
}

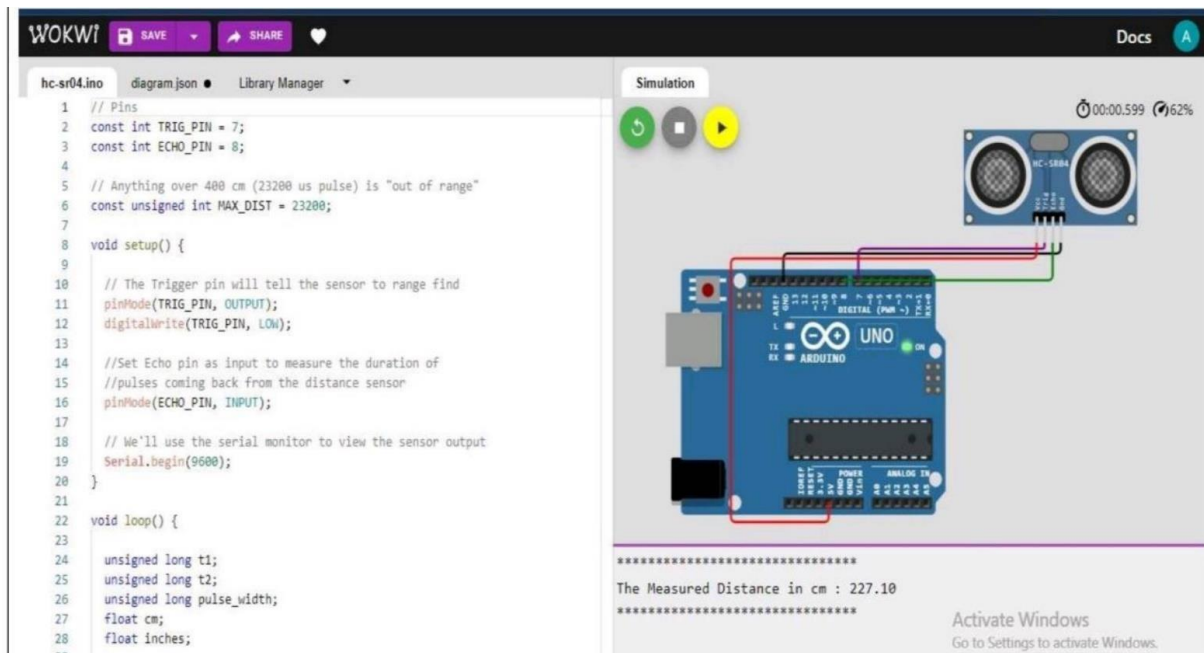
```

## Output:

1.If the distance is less than 100 cms ,it alerts.



**2.If the distance is more than 100 cms,it won't alert**



**3.Simulation and code execution**

