**NAME: AKASH P** 

**REG NO: 513219104301** 

## **PROGRAM**

Smart Waste Management System for Metropolitan Cities

## **ASSIGNMENT 4**:

Write code and connections in wokwi for ultrasonic sensors. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events. Uplode document with wokwi share link and images of ibm cloud.

```
and images of ibm cloud.
CODE:
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "ztcz45"
#define DEVICE_TYPE "naveen"
#define DEVICE_ID "naveen123"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
```

PubSubClient client(server, 1883, wifiClient);

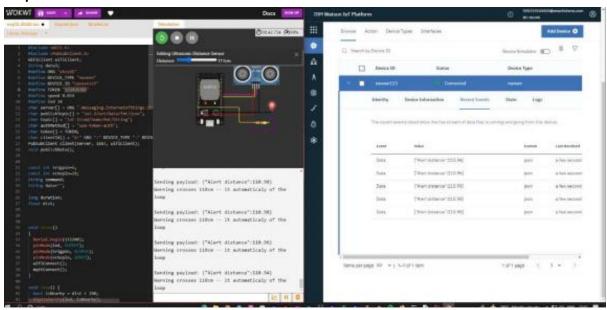
```
void publishData();
const int trigpin=5;
const intechopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
[10:32 pm, 23/10/2022] Gogul B.E CSE: }
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice(){
if (client.subscribe(topic)) {
```

```
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Normal Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}
}
if(dist>101 && dist<111){
```

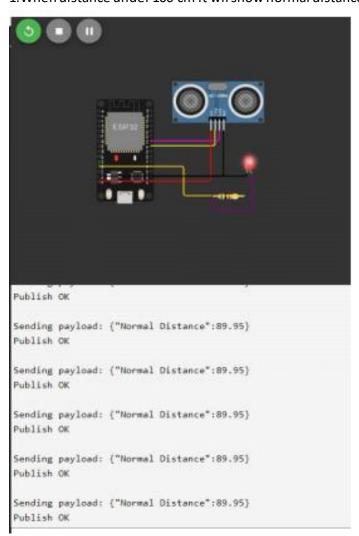
```
String payload = "{\"Alert distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload:");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())){
Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
digitalWrite(led,HIGH);
}else {
Serial.println("Publish FAILED");
}
}
}
void callback(char* subscribe Topic, byte* payload, unsigned int payload Length) {
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){</pre>
dist += (char)payload[i];
}
Serial.println("data:"+data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
}
```

```
data3="";
}
```

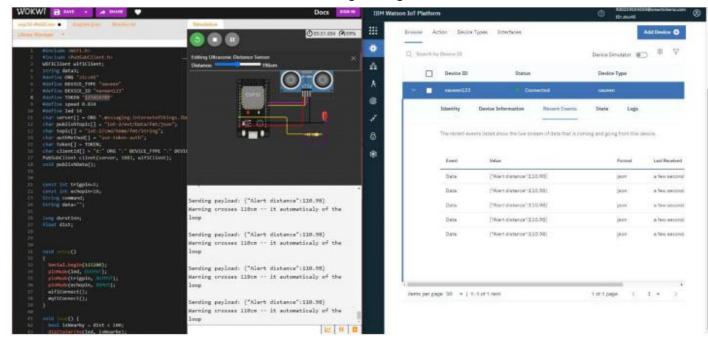
## output:



1. When distance under 100 cm it wil show normal distance.



2. When distance cross 100 cm it will show ALERT warning message distance



3. When it cross above 110 cm it today move to iff state once it

reduce to 110 it on again

Connection information:

Basic conntection information about this device.

Organization ID: ztcz45

Device Type: akash

Device ID: akash123

Authentication Method: use-token-auth Authentication Token: 123456789

