Sprint 02

Signs with Smart Connectivity for Better Road Safety Team ID - PNT2022TMID17220

Sprint Goals: Push data from local code to cloud **Program Code:** > weather.py This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response. # Python code import requests as reqs def get(myLocation,APIKEY): apiURL = f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={API KEY}" responseJSON = (reqs.get(apiURL)).json() returnObject = { "temperature": responseJSON['main']['temp'] - 273.15, "weather": [responseJSON['weather'][_]['main'].lower() for _ in range(len(responseJSON['weather']))], "visibility": responseJSON['visibility']/100, # visibility in percentage where 10km is 100% and 0km is 0% if("rain" in responseJSON): returnObject["rain"] = [responseJSON["rain"][key] for key in responseJSON["rain"]] return(returnObject) > publishData.py This code pushes data to the cloud and logs data. IBM Cloud is configured such that the data is displayed in the following website: CLICK TO OPEN NODE RED

DASHBOARD

```
# Python code
# IMPORT SECTION STARTS
import wiotp.sdk.device # python -m pip install wiotp import
time
# IMPORT SECTION ENDS
# API CONFIG SECTION STARTS
myConfig = {
  "identity": {
    "orgId": "epmoec",
    "typeId": "testDevice",
    "deviceId": "device0"
  },
  "auth" : {
    "token": "?-KDXUPMvDo_TK2&b1"
# API CONFIG SECTION ENDS
# FUNCTIONS SECTION STARTS
def myCommandCallback(cmd):
print("recieved cmd : ",cmd)
def logData2Cloud(location,temperature,visibility):
  client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
client.connect()
  client.publishEvent(eventId="status",msgFormat="json",data={
    "temperature": temperature,
    "visibility": visibility,
    "location": location
  },qos=0,onPublish=None)
  client.command Callback = my Command Callback \\
```

client.disconnect()
 time.sleep(1)

FUNCTIONS SECTION ENDS

UTILITY LOGIC SECTION ENDS

> brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

from datetime import datetime as dt from publishData import logData2Cloud as log2cloud

```
# IMPORT SECTION ENDS
UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
  weatherData = weather.get(myLocation,APIKEY)
  log2cloud(myLocation, weatherData["temperature"], weatherData["visibility"])
  finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
  finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
  if(localityInfo["hospitalsNearby"]):
    # hospital zone
doNotHonk = True
                     else:
    if(localityInfo["schools"]["schoolZone"]==False):
       # neither school nor hospital zone
doNotHonk = False
                        else:
       # school zone
       now = [dt.now().hour,dt.now().minute]
activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
       doNotHonk = activeTime[0][0] <= now[0] <= activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]
  return({
    "speed": finalSpeed,
     "doNotHonk" : doNotHonk
  })
```

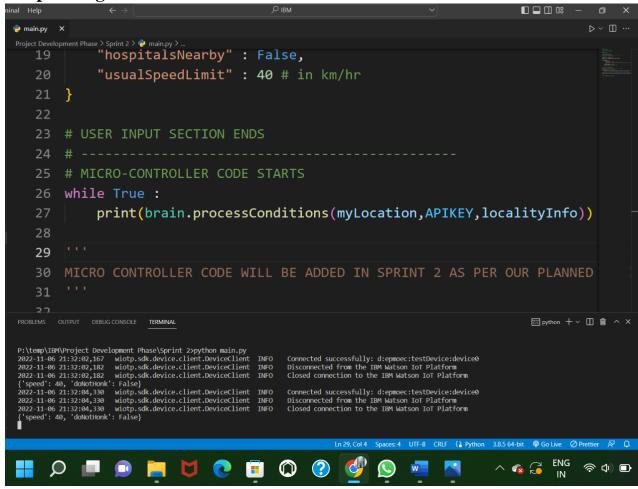
```
> main.py
```

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# USER INPUT SECTION STARTS
myLocation = "Chennai, IN" \\
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
  "schools": {
    "schoolZone": True,
    "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
  "hospitalsNearby": False,
  "usualSpeedLimit": 40 # in km/hr
}
# USER INPUT SECTION ENDS
# MICRO-CONTROLLER CODE STARTS while
True:
  print(brain.processConditions(myLocation,APIKEY,localityInfo))
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR
PLANNED SPRINT SCHEDULE
# MICRO-CONTROLLER CODE ENDS
Output:
LINK TO NODE RED DASHBOARD
```

```
# Code Output
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO
                                                                    Closed
connection to the IBM Watson IoT Platform
{'speed': 40, 'doNotHonk': False}
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
Connected successfully: d:epmoec:testDevice:device0
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO
Disconnected from the IBM Watson IoT Platform
2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO Closed
connection to the IBM Watson IoT Platform {'speed': 40, 'doNotHonk': False}
... repeats every 1 sec Images
```

OutputImage 1:



OutputImage2:

