SPRINT 4

Project Execution and Testing

Date	13 November 2022
Team ID	PNT2022TMID21140
Project Name	Smart waste management system for
	metropolitan cities
Points	20

Python Code for Bin 1

```
#Bin 1
```

```
import wiotp.sdk.device
import time
import random
myConfig = {
  "identity": {
    "orgId": "0kzyfe",
    "typeId": "BIN 1",
    "deviceId":"BIN1"
  },
  "auth": {
    "token": "12345678"
  }
}
def myCommandCallback(cmd):
  print("Message received from IBM IoT Platform: %s" % cmd.data['command'])
  m=cmd.data['command']
client = wiotp.sdk.device.DeviceClient(config=myConfig, logHandlers=None)
client.connect()
while True:
  level=random.randint(0,10)
  weight=random.randint(0,10)
  myData={ 'name': 'Bin_1', 'lat': 13.092677, 'lon': 80.188314, 'Level':level,
'Weight':weight }
  client.publishEvent(eventId="status", msgFormat="json", data=myData,
qos=0,onPublish=None)
  print ("Published data Successfully: %s", myData)
```

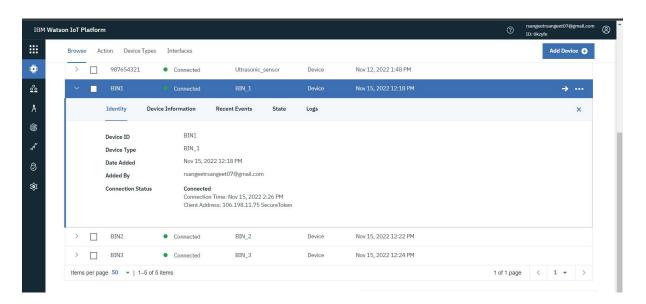
client.commandCallback = myCommandCallback
time.sleep(2)
client.disconnect()

EXECUTION

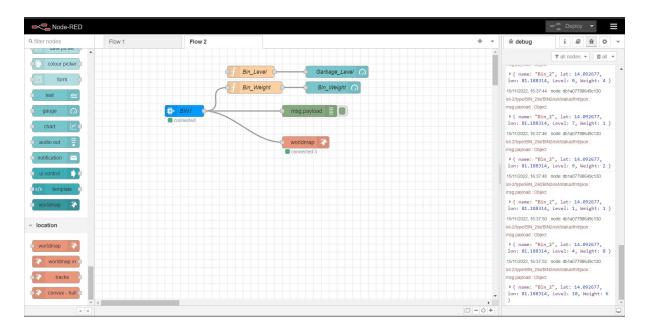
✓ Executing the code to find the location of the Trash bin with random latitude and longitude which sends the data to the IBM Watson IOT platform

```
| Import viotp.sdr.device | Import time | Im
```

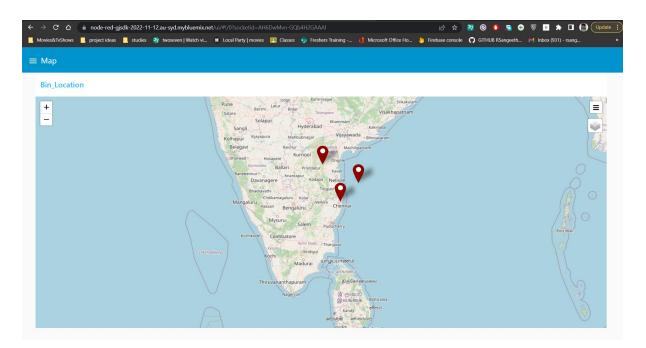
✓ The data from the Python IDLE is received by the device created in the IBM Watson IOT platform where the latitude and longitude of bin is shown below



✓ The connections are made between the nodes in Node-RED Services to create web UI of the location

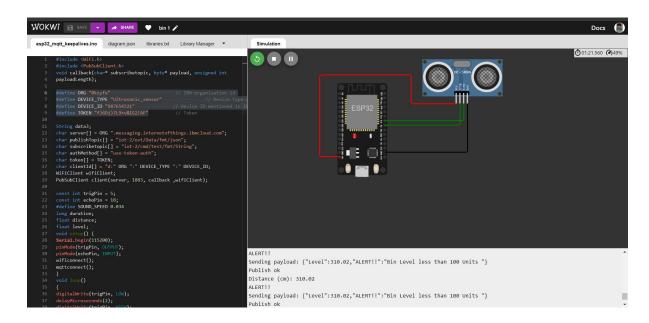


 \checkmark The location of the bin is shown in The World Map



- ✓ The SENSOR values sent to the IBM Watson IOT platform by two ways:
 - o From ESP32-Wokwi
 - From Python IDLE-Random Values

√ To send sensor readings from ESP32-Wokwi



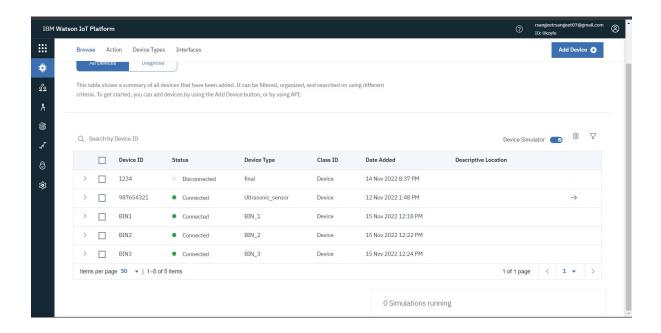
Run The ESP32 code Here: Wokwi

✓ Run the Python using IDLE to send the Random Values of Level and Weight of the Trash in the bin to IBM Watson IOT platform

TESTING

✓ Executing codes for multiple Bins

✓ For Example, Three IOT device is create in Watson IOT platform and also connected with the sensor Devices or IDLE . It shows the device is connected



- ✓ The payload received to the IOT device in IBM platform as shown below
- ✓ To Monitor the level and Weight of the bins , the Node-RED platform is used. The Nodes are used to make connections.
- ✓ IBM IOT Node is to receive message from IBM IOT device.
- ✓ Several Functions, Templates, Gauge, Graph Nodes are used to create UI

A filter nodes

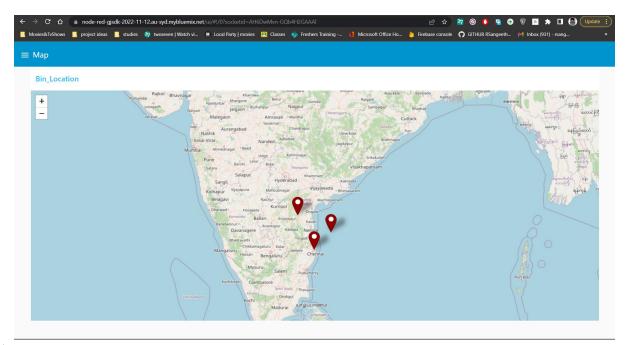
Flow 1

Flow 2

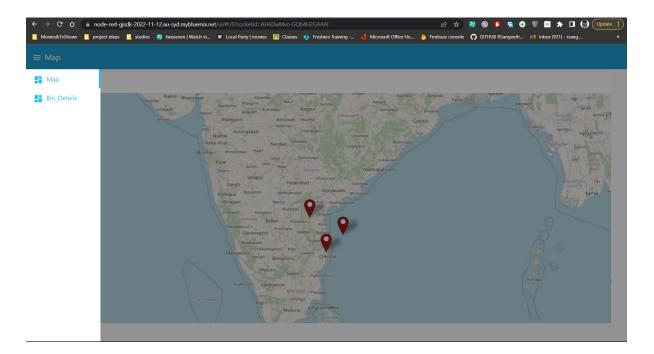
V Midebug is Midebug

Web UI: Smart Waste Management

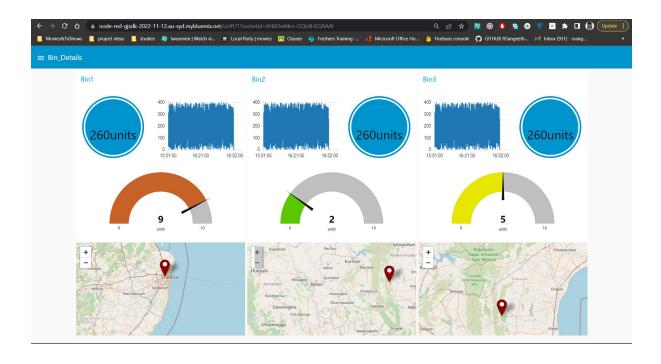
✓ The Web UI is created using Node-RED services , The Dashboard is used to Navigate between the Number of Bins

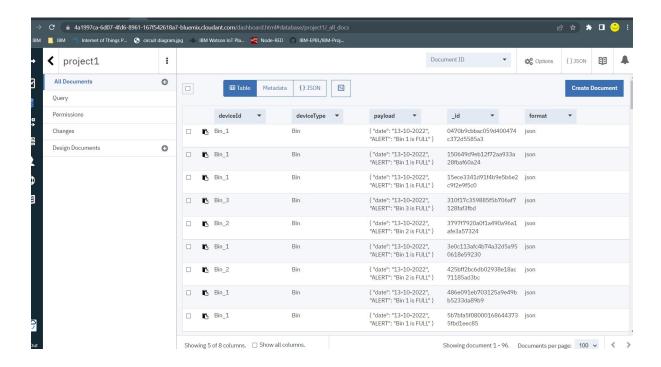


- ✓ The UI is used to monitor the garbage by weight and Level of the Trash as shown Below.
- \checkmark The previous Level of the bins can also be viewed using the chart



✓ If the level of the Trash is FULL or the Weight of the Trash is MAXIMUM , The ALERT message is Displayed





✓ The Message stored in cloud contains Bin details , Date and The ALERT message

