## **ASSIGNMENT-1**

## **Objective:**

Make a smart home in Tinkercad using 2+ sensors, LED, Buzzer in single code and circuit.

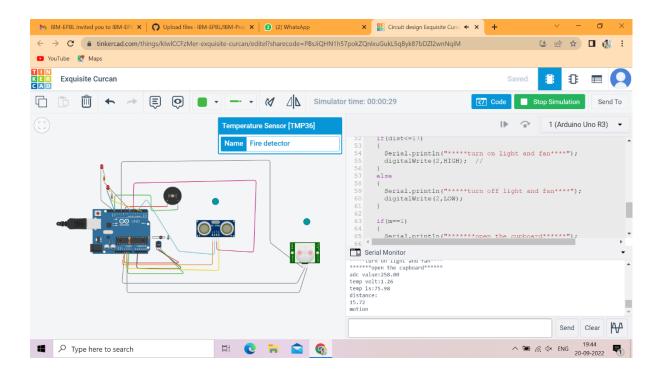
## **Coding:**

```
// C++ code
//
int trig=4;
int echo=6;
void setup()
{
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(11,INPUT);
  Serial.begin(9600);
  pinMode(9,OUTPUT); // buzzer for temp
  pinMode(2,OUTPUT); //led of ultrasonic
  pinMode(7,OUTPUT); //led of pir
}
```

```
void loop()
{
 double a=analogRead(A1);
 Serial.print("adc value:");
 Serial.println(a);
 double v=a/1024;
 double tvolt=v*5; // here 5 is in volt and thhisege for elect to
temp volt
 Serial.print("temp volt:");
 Serial.println(tvolt);
 double o=tvolt-0.5; //for octol and 0.5 for min volt for octal
 double t=o*100;// this two ege for volt to temp
 Serial.print("temp is:");
 Serial.println(t);
 //delay(2000);
 digitalWrite(trig,LOW); //off
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
 digitalWrite(trig,LOW); // till this for trigger
 float dur=pulseIn(echo,HIGH); // echo on
 float dist=(dur*0.0343)/4; //cm to m
 Serial.println("distance:");
 Serial.println(dist); //ultra sonic
 int m=digitalRead(11);
```

```
Serial.print("motion detected : ");
Serial.println(m);
if(t>=50)
{
 Serial.println("******house on fire*****");
 digitalWrite(9,HIGH);//to get
}
else
{
 digitalWrite(9,LOW);
//delay(2000);
if(dist<=17)
 Serial.println("*****turn on light and fan****");
 digitalWrite(2,HIGH); //
else
{
 Serial.println("*****turn off light and fan****");
digitalWrite(2,LOW);
}
```

```
if(m==1)
{
    Serial.println("******open the cupboard*****");
    digitalWrite(7,HIGH);
    delay(50);
}
else
{
    Serial.println("********close the cupboard*****");
    digitalWrite(7,LOW);
}
delay(50);
```



## Simulation link:

https://www.tinkercad.com/things/klwlCCFzMerexquisite-

curcan/editel?sharecode=PBsJiQHN1h57pokZQnlxuGukL5qByk87bDZl2wnNqiM&sharecode=PBsJiQHN1h57pokZQnlxuGukL5qByk87bDZl2wnNqiM