# PRASATH V

PNT2022TMID01111

# **ASSIGNMENT 1**

#### **OBJECTIVE:**

Make a Smart Home in Tinkercad, using 2+ sensors, Led, Buzzer in single code and circuit.

#### **CODE:**

```
// C++ code

//

int trig=12;

int echo=11;

void setup()

{

pinMode(trig,OUTPUT);

pinMode(echo,INPUT);

pinMode(13,INPUT);

Serial.begin(9600);

pinMode(10,OUTPUT); // buzzer for temp

pinMode(8,OUTPUT); //led of ultrasonic

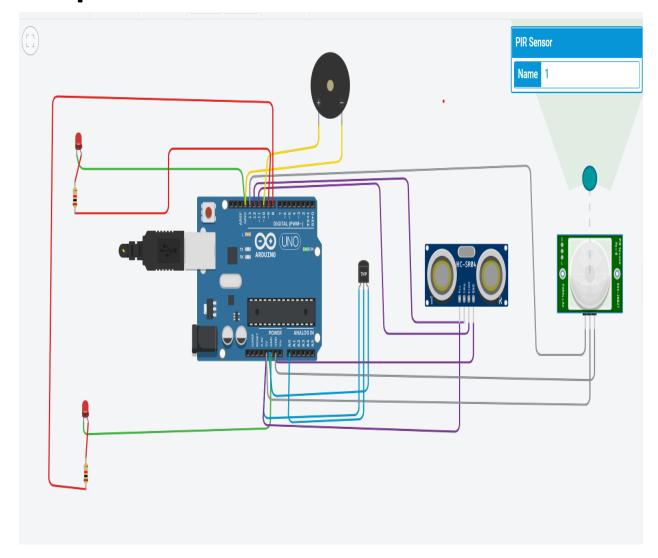
pinMode(9,OUTPUT); //led of pir
```

```
}
void loop()
{
 double a=analogRead(A0);
 Serial.print("adc value:");
 Serial.println(a);
 double v=a/1024;
 double tvolt=v*5; // here 5 is in volt and thhiseqe for elect to temp volt
 Serial.print("temp volt:");
 Serial.println(tvolt);
 double o=tvolt-0.5; //for octol and 0.5 for min volt for octal
 double t=o*100;// this two eqe for volt to temp
 Serial.print("temp is:");
 Serial.println(t);
 //delay(2000);
 digitalWrite(trig,LOW); //off
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
 digitalWrite(trig,LOW); // till this for trigger
 float dur=pulseIn(echo,HIGH); // echo on
 float dist=(dur*0.0343)/4; //cm to m
 Serial.println("distance:");
 Serial.println(dist); //ultra sonic
 int m=digitalRead(13);
```

```
Serial.print("motion detected : ");
Serial.println(m);
if(t>=45)
{
 Serial.println("*******FIRE ALERT*******");
 digitalWrite(10,HIGH);//to get
}
else
{
 digitalWrite(10,LOW);
}
//delay(2000);
if(dist<=20)
 Serial.println("turn on light and fan");
 digitalWrite(8,HIGH); //
}
else
 Serial.println("turn off light and fan");
 digitalWrite(8,LOW);
}
if(m==1)
```

```
{
    Serial.println("open the cupboard");
    digitalWrite(9,HIGH);
    delay(50);
}
else
{
    Serial.println("close the cupboard");
    digitalWrite(9,LOW);
}
delay(50);
}
```

# **Output:**



### **SIMULATION LINK:**

https://www.tinkercad.com/things/8Gr 4fVIBejF-fabulousgogo/editel?tenant=circuits