

IOT Smart Crop Protection System for Agriculture .

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DEVELOPING PYTHON SCRIPT

LOCATION DATA:

```
import wiotp.sdk.device
import time
import random
myConfig={
    "identity": (
        "orgId": "gagtey",
        "typeId": "GPS",
        "deviceId":"12345"},
    "auth": {
        "token": "12345678"
    }
}

def myCommandCallback (cmd): print ("Message received from IBM
IoT Platform: %s" % cmd.data['command']) m=cmd.data['command']
client=
wiotp.sdk.device.DeviceClient (config=myConfig,
    logHandlers=None) client.connect()
def pub (data):
    client.publishEvent      (eventId="status",      msgFormat="json",
    data=myData, qos=0, print("Published data Successfully: %s",
myData) while True:
```

```

myData={'name': 'Train1', 'lat': 17.6387448, 'lon':
78.4754336) pub
(myData)
time.sleep (3)
#myData('name': 'Train2', 'lat': 17.6387448, 'lon': 78.4754336)
#pub (myData) #time.sleep (3) myData={'name':
'Train1', 'lat': 17.6341908, 'lon':
78.4744722) pub
(myData)
time.sleep(3)
myData={'name': 'Train1', 'lat': 17.6340889, lon': 78.4745052)
pub (myData) time.sleep(3)
myData={'name': 'Train1', 'lat': 17.6248626, 'lon': 78.4720259)
pub (myData) time.sleep (3)
myData={'name': 'Train1', 'lat': 17.6188577, 'lon': 78.4698726)
pub (myData) time.sleep (3)
myData={'name': 'Train1', 'lat':
17.6132382, 'lon':
78.4707318) pub
(myData)
time.sleep (3)
client.commandCallback = myCommandCallback
client.disconnect()

```

QR SCANNER CODE:

```

Import cv2 import

```

```

numpy as np import
time
Import pyzbar.pyzbar as pyzbar
from ibmcloudant.cloudant_v1 import CloudantV1 from
ibmcloudant import CouchDbSessionAuthenticator
from ibm_cloud_sdk_core.authenticators import
BasicAuthenticator
authenticator= BasicAuthenticator ('apikey-v2-
16u3crmdpkghhxefdikvpssoh5fwezrmuup5fv5g3ubz',
'b0ab119f45d3e6255eabb978
service      Cloudant      V1      (authenticator-authenticator)
service.set_service_url('https://apikey
v216u3crmdpkghhxefdikvpssoh5fwezrmuup5fv5g3ubz:b0ab
119 f45d3e6255eabb978e7e2f0 cap= cv2.VideoCapture (0)
font cv2.FONT_HERSHEY_PLAIN while True:
frame cap.read()
decodedobjects pyzbar.decode (frame)
for obj in decodedObjects: #print ("Data", obj.data)
aobj.data.decode('UTF-8')
cv2.putText (frame, "Ticket", (50, 50), font, 2,
(255, 0, 0), 3) #print (a)
try: response = service.get_document ( db='booking,
doc_id = a ).
get_result()
print (response) time.sleep(5)
except Exception as e:

```

```
print ("Not a Valid Ticket")
time.sleep (5) cv2.imshow("Frame",
    frame) if cv2.waitKey(1) &
    0xFF==ord('q'):
    break cap.release()
cv2.destroyAllWindows () client.disconnect()
```