

### Develop a python script

Team ID	PNT2022TMID07841
Project Name	Smart waste management system for metropolitan cities

Step 1: Open python idle Step2: Type the program Step 3: Then click on file and save the document Step 4: Then click on Run then Run Module Step 5: output will be appeared in the idle window

## Python script

```
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys
# watson device details
organization ="4yi0vc"
devicType ="tamili78"
deviceId ="tamil23"
authMethod="token"
authToken="123456789"
#generate random values for randomo variables (temperature&humidity)
def myCommandCallback(cmd):
    global a
    print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
    print(control)
try:
    deviceOptions={"org": organization, "type": devicType,"id": deviceId,"authmethod":authMethod,"authtoken":authToken}
    deviceCli
```

```

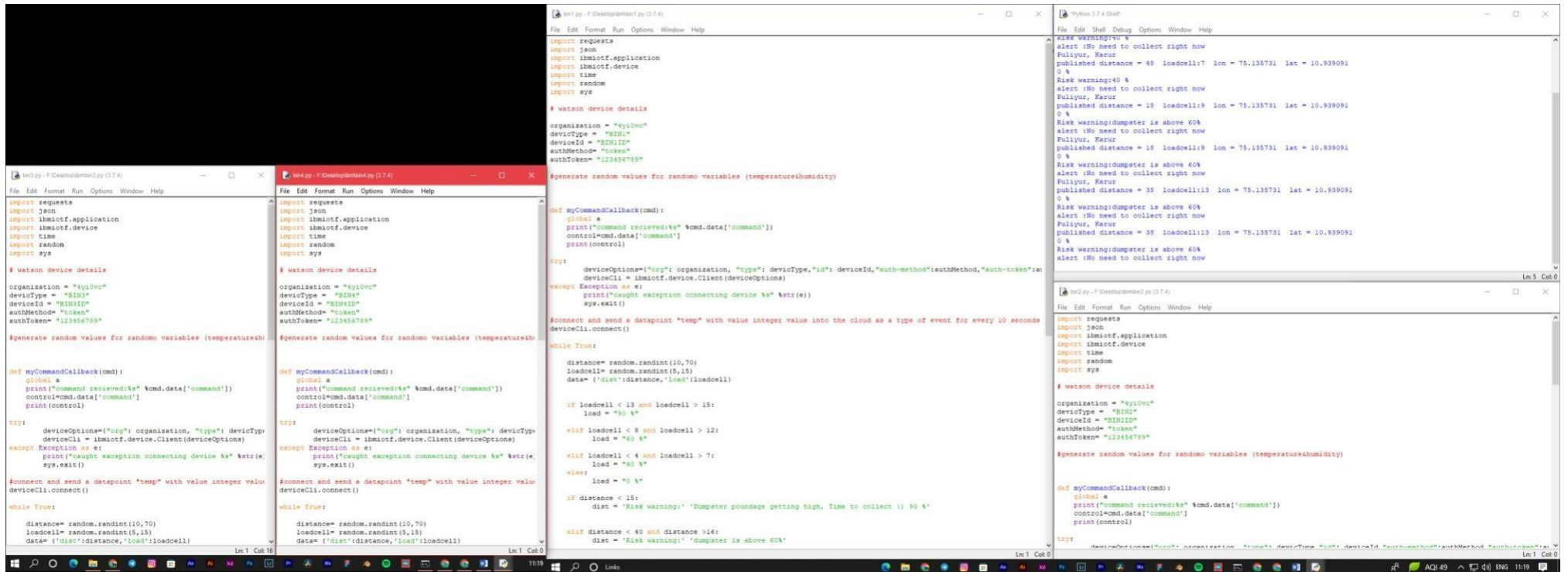
= ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()
#connect and send a datapoint "temp" with value integer value into the cloud as a type of event for every 10 seconds
deviceCli.connect()
while True:
    distance= random.randint(10,70)
    loadcell= random.randint(5,15)
    data={'dist':distance,'load':loadcell}
    if loadcell < 13 and loadcell> 15:
        load = "90 %"
    elif loadcell < 8 and loadcell > 12:
        load = "60 %"
    elif loadcell < 4 and loadcell > 7:
        load = "40 %"
    else:
        load = "0 %"
    if distance < 15:
        dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'
        elif
    distance < 40 and distance >16:
        dist = 'Risk warning:' 'dumpster is above 60%'
        elif distance < 60 and distance > 41: dist = 'Risk warning:' '40 %'
        else:
            dist = 'Risk warning:' '17 %'
        if load == "90 %" or distance == "90 %":
            warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)'
        elif load == "60 %" or distance == "60 %":
            warn = 'alert :''dumpster is above 60%'
        else : warn = 'alert :' 'No need to collect right now '
def myOnPublishCallback(lat=10.678991,long=78.177731):
    print("Gandigramam, Karur") print("published distance = %s " %distance,"loadcell:%s "
%loadcell,"lon = %s " %long,"lat = %s" %lat) print(load) print(dist)print(warn)

```

```
time.sleep(10)
    success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on_publish=
myOnPublishCallback) success=deviceCli.publishEvent
("IoTSensor","json",data,qos=0,on_publish= myOnPublishCallback)
    if not success:
print("not connected to ibmiot")
time.sleep(30)
```

```
deviceCli.commandCallback=myCommandCallback
#disconnect the device deviceCli.disconnect
```

# Screenshots Python script:



```
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys

# Watson device details
organization = "4y10vc"
deviceType = "BINI"
deviceId = "BINIID"
authMethod = "token"
authToken = "123456789"

#Generate random values for random variables (temperature,humidity)

def myCommandCallback(cmd):
    global a
    print("Command received: %s" % cmd.data['command'])
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try:
    deviceOptions={"org": organization, "type": deviceType, "id": deviceId, "auth-method": authMethod, "auth-token": authToken}
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    else:
        load = "0 %"

    if distance < 15:
        dist = 'Risk warning: ' 'Dumpster poundage getting high, Time to collect :)' 90 %'
    elif distance < 40 and distance > 14:
        dist = 'Risk warning: ' 'Dumpster is above 60%'

    deviceCli.publishEvent("temp", json.dumps(data))
    time.sleep(10)
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