FINAL CODE AND OUTPUT

| Date | 15 November 2022 |
|-----------------|---|
| Team ID | PNT2022TMID04392 |
| Project Name | Smart Waste Management System for Metropolitan Cities |
| | |
| | |

CODING:

```
// #define ORG "3defta"
// #define DEVICE TYPE "hariprasath"
// #define DEVICE ID "12345"
// #define TOKEN "CpL-H1C-Pt4i9iM-F5"
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT
#include <LiquidCrystal I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
// credentials of IBM Accounts -
#define ORG "3defta" //IBM organisation id
#define DEVICE TYPE "hariprasath" // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "12345" // Device ID mentioned in ibm watson iot platform
#define TOKEN "CpL-H1C-Pt4i9iM-F5" // Token
// customise above values -
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID; //Client id
```

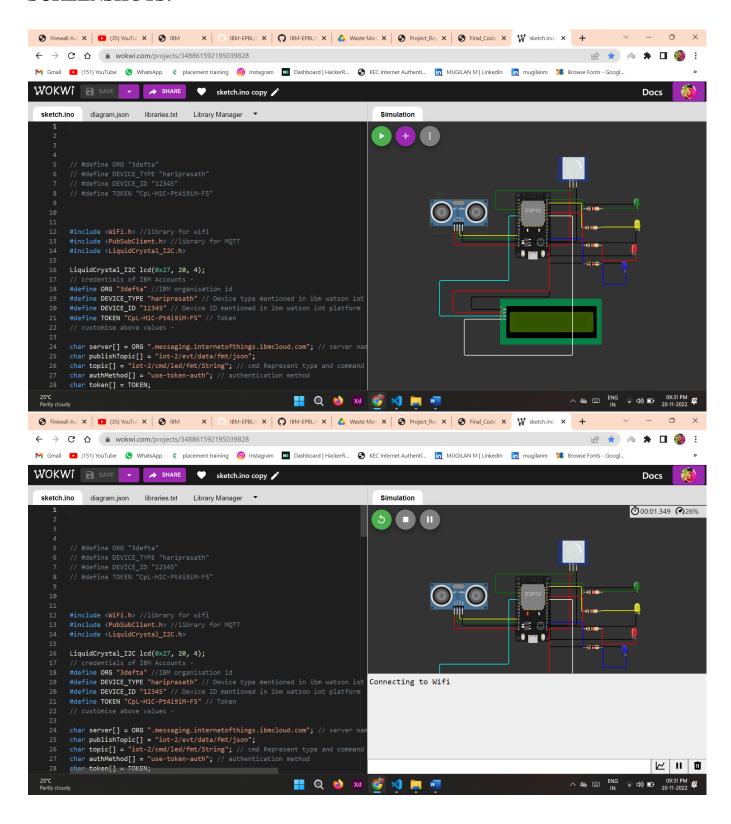
```
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
void setup()
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir
pinMode(4, INPUT);
pinMode(23,OUTPUT);
pinMode(2,OUTPUT);
pinMode(4,OUTPUT);
pinMode(15,OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1,0);
lcd.print("");
wifiConnect();
mqttConnect();
float readcmCM()
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN,HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration =pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
void loop()
lcd.clear();
publishData();
delay(500);
if (!client.loop())
```

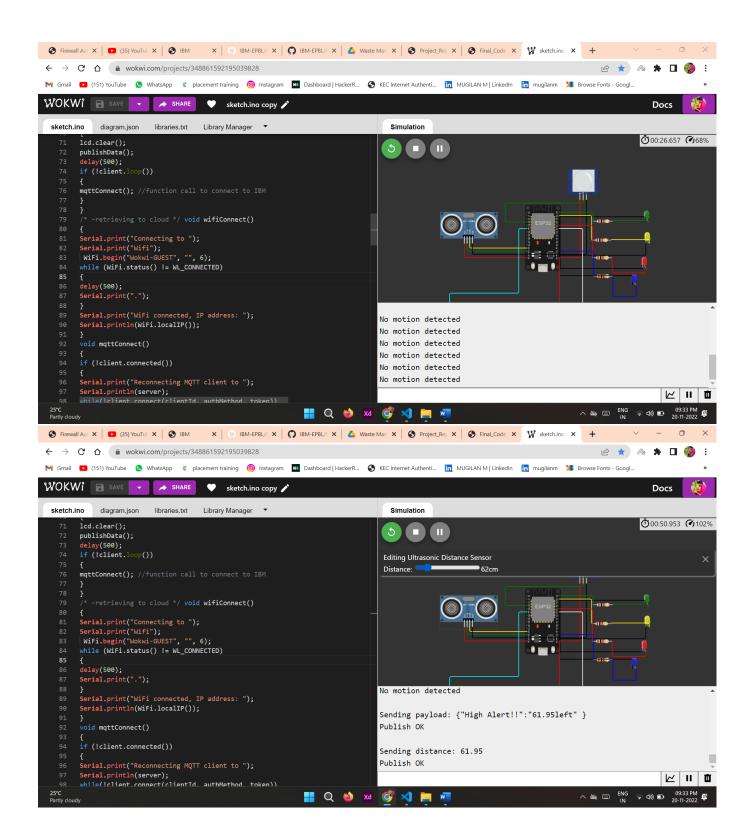
```
mqttConnect(); //function call to connect to IBM
/* -retrieving to cloud */ void wifiConnect()
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
delay(500);
Serial.print(".");
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect()
if (!client.connected())
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while(!client.connect(clientId, authMethod, token))
Serial.print("."); delay(500);
initManagedDevice(); Serial.println();
void initManagedDevice()
if (client.subscribe(topic))
Serial.println("IBM subscribe to cmd OK");
else
Serial.println("subscribe to cmd FAILED");
void publishData()
float cm = readcmCM();
```

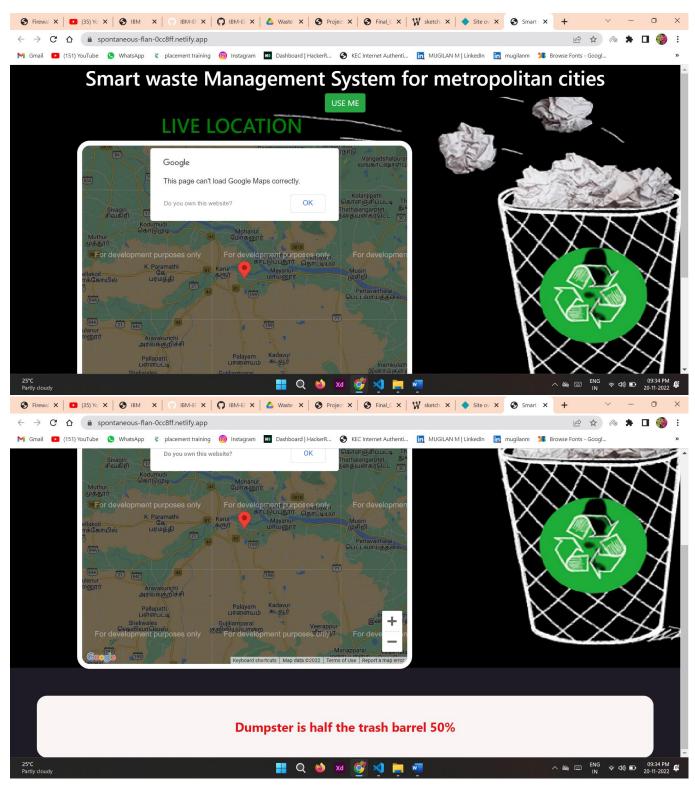
```
if(digitalRead(34)) //PIR motion detection
Serial.println("Motion Detected"); Serial.println("Lid Opened"); digitalWrite(15, HIGH);
else
digitalWrite(15, LOW);
if(digitalRead(34)== true)
if(cm <= 100) //Bin level detection</pre>
digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("Lid Closed");
lcd.print("Full! Don't use");
delay(2000);
lcd.clear();
digitalWrite(4, LOW);
digitalWrite(23, LOW);
else if(cm > 150 && cm < 250)
digitalWrite(4, HIGH);
Serial.println("Warning!!,Trash is about to cross 50% of bin level");
digitalWrite(2,LOW);
digitalWrite(23, LOW);
else if(cm > 250 && cm <=400)
digitalWrite(23, HIGH);
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
delay(10000);
Serial.println("Lid Closed");
else
Serial.println("No motion detected");
if(cm <= 100)
```

```
digitalWrite(21,HIGH);
String payload = "{\"High Alert!!\":\"";
payload += cm;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to
cloud successfully, prints publish ok or prints publish failed
Serial.println("Publish OK");
if(cm <= 250)
digitalWrite(22,HIGH);
String payload = "{\"Warning!!\":\"";
payload += dist;
payload += "left\" }";
Serial.print("\n");
Serial.print("Sending distance: ");
Serial.println(cm);
if(client.publish(publishTopic,(char*) payload.c_str()))
Serial.println("Publish OK");
else
Serial.println("Publish FAILED");
float inches = (cm / 2.54); //print on LCD lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
```

SCREENSHOTS:







LINK:

https://wokwi.com/projects/348861592195039828