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#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
  Serial.begin(115200);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  wificonnect();
  mqttconnect();
}
void loop()
{
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = duration * SOUND_SPEED/2;
  Serial.print("Distance (cm): ");

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Serial.println(distance);
if(distance<100)
{
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
}
delay(1000);
}

void PublishData(float dist) {
mqttconnect();
String payload = "{\\"Distance\\":";
payload += dist;
payload += ",\\"ALERT!!\\"::\\"Distance less than 100cms\\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}

void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}

void wificonnect()

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{
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() !=
WL_CONNECTED) { delay(500);
Serial.print(".");
}
Serial.println(""); Serial.println("WiFi
connected"); Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe to
cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
}
Serial.println("data: "+ data3);
data3="";
}
Diagram.json:
{
"version": 1,
"author": "sweetysharon",
"editor": "wokwi",
"parts": [
{ "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
{ "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
],
"connections": [
[ "esp:TX0", "$serialMonitor:RX", "", [] ],

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[ "esp:RX0", "$serialMonitor:TX", "", [] ],  
[  
  "esp:VIN",  
  "ultrasonic1:VCC",  
  "red",  
  [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]  
],  
[ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],  
[ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],  
[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]  
]  
}
```