

```
int v=2;
int s=3;

void setup()
{
    Serial.begin(9600);
    pinMode(v,OUTPUT);
    pinMode(s,INPUT);
    pinMode(12,OUTPUT);
}

void loop()
{
    //ultrasonic sensor
    digitalWrite(v,LOW);
    digitalWrite(v,HIGH);
```

```
delayMicroseconds(10);
digitalWrite(v,LOW);
float dur=pulseIn(s,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is: ");
Serial.println(dis);
 //LED ON
if(dis > = 100)
 digitalWrite(8,HIGH);
 digitalWrite(7,HIGH);
}
//Buzzer For ultrasonic Sensor
if(dis > = 100)
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
}
 //Temperate Sensor
double b= analogRead(A0);
double v=(((b/1024)*5)-0.5)*100;
Serial.print("Temp Value: ");
Serial.println(v);
delay(1000);
```

```
if(v > = 100)
  digitalWrite(8,HIGH);
  digitalWrite(7,HIGH);
 }
 //Buzzer for Temperature Sensor
 if(v > = 100)
 for(int i=0; i<=30000; i=i+10)
 tone(12,i);
 delay(1000);
 noTone(12);
 delay(1000);
 }
 }
 //LED OFF
 if(v<100)
  digitalWrite(8,LOW);
  digitalWrite(7,LOW);
}
}
```