Karpagam College of Engineering

(Electronics and Communication Engineering)

TEAM ID: PNT2022TMID12796

PROJECT TITLE: Industry-Specific Intelligent Fire Management System

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Assignment 4:

Write code and connections in wokwi for the ultrasonic sensor

```
#include <WiFi.h>
#include <PubSubClient.h>

WiFiClient wifiClient;

String data3;
#define ORG "86ykjn"

#define DEVICE_TYPE "assignment4"

#define DEVICE_ID "12345"

#define TOKEN "6DGHyn)mYb)gRuXJvt"

#define speed 0.034

#define led 14

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char publishTopic[] = "iot-2/evt/event2/fmt/json";

char topic[] = "iot-2/cmd/home/fmt/String";

char authMethod[] = "use-token-auth";

char token[] = TOKEN;
```

```
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);

const int trigpin=5;
const int echopin=18;
String command;
String data="";
```

```
long duration;
float dist;
```

```
void setup()
{
    Serial.begin(115200);
    pinMode(led, OUTPUT);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}
```

```
void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);</pre>
```

```
publishData();
delay(500);
```

```
if (!client.loop()) {
  mqttConnect();
}
```

```
void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
```

```
void mqttConnect() {
   if (!client.connected()) {
      Serial.print("Reconnecting MQTT client to "); Serial.println(server);
      while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
      initManagedDevice();
      Serial.println();
   }
}
```

```
void initManagedDevice() {
   if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
   } else {
        Serial.println("subscribe to cmd FAILED");
   }
}
```

```
void publishData()
{
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;
    if(dist<100){
        String payload = "{\"Alert!! Alert!! Distance\":";
        payload += dist;
        payload += "}";</pre>
```

```
Serial.print("\n");
Serial.print("Sending payload: ");

Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}

if(dist>100){
String payload = "{\"Distance\":";
    payload += dist;
    payload += "}";
```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}else {
```

```
Serial.println("Publish FAILED");
}
```

```
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```