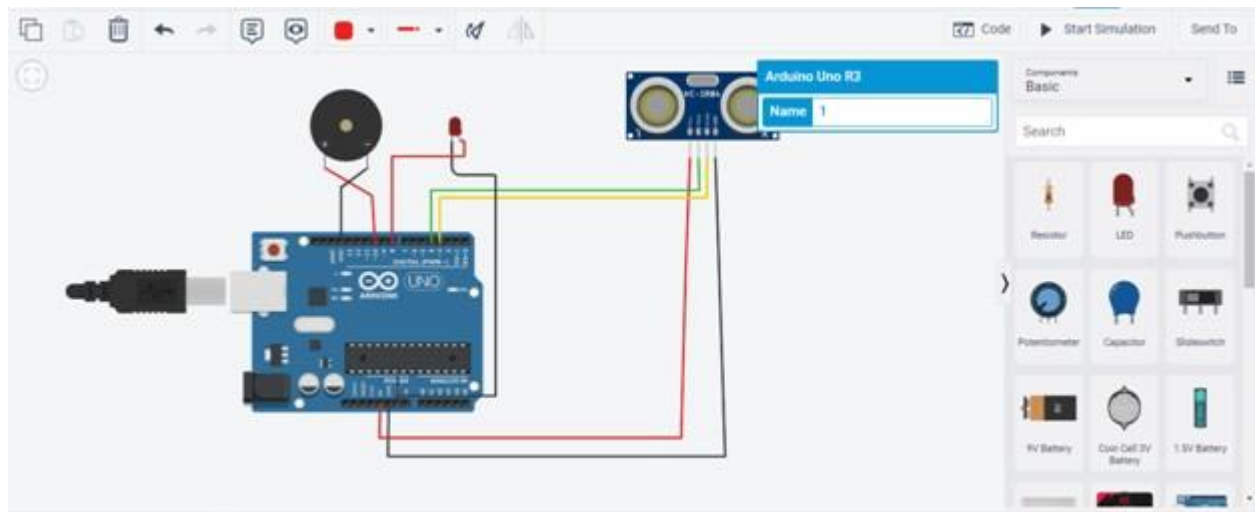


CIRCUIT DIAGRAM



Code:

```
int
```

```
trigpin=4;
```

```
int
```

```
echopin=3;
```

```
int buzzerpin=10;
```

```
int time;
```

```
int distance;
```

```
void setup()
```

```
{
```

```
}
```



```
pinMode(8,OUTPUT);
```

```
pinMode(3,INPUT);
```

```
pinMode(4,OUTPUT);
```

```
pinMode(10,OUTPUT);
```

```
Serial.begin(9600);
```

```
}
```



```
void loop()

{

  digitalWrite(trigpin,

  HIGH);

  delayMicroseconds(100

  0); digitalWrite(trigpin,

  LOW);

  delayMicroseconds(100

  0);

  time=pulseIn(echopin,H

  IGH);

  distance=(time*0.034)

  /2; if(distance<=10)

  {

    Serial.print("Distance= ");

    Serial.println(distance);

    digitalWrite(8,HIGH);

    delay(1000);

    digitalWrite(10,LOW);

    delay(1000);

  }

}
```



```
else
```

```
{
```

```
Serial.print("Distance= ");
```

```
Serial.println(distance);
```

```
digitalWrite(8,LOW);
```

```
delay(1000);
```

```
digitalWrite(10,HIGH);
```

```
delay(1000);
```

```
}
```

```
}
```



OUTPUT

