

## Assignment -4

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Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events. Upload document with wokwi share link and images of ibm cloud

## CODE

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json"; char topic[] = "iot-
2/cmd/home/fmt/String"; char authMethod[] = "use-tokenauth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5; const
int echopin=18;
String command;
String data="";

long duration; float
dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
```

```

pinMode(echopin, INPUT);
 wifiConnect(); mqttConnect();
}

void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);

 publishData();
 delay(500);

 if (!client.loop()) {
   mqttConnect();
 }
}

void wifiConnect() {
 Serial.print("Connecting to ");
 Serial.print("Wifi");
 WiFi.begin("WokwiGUEST", "", 6); while
 (WiFi.status() !=
 WL_CONNECTED) {
   delay(500);
   Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: ");
 Serial.println(WiFi.localIP());
}

void mqttConnect() {
 if (!client.connected()) {
   Serial.print("Reconnecting MQTT client to ");
   Serial.println(server); while
   (!client.connect(clientId, authMethod, token)) {
     Serial.print(".");
     delay(500);
   }
   initManagedDevice(); Serial.println();
 }
}

void initManagedDevice() {
 if (client.subscribe(topic)) {
   // Serial.println(client.subscribe(topic));
   Serial.println("IBM subscribe to cmd OK");
 } else {
   Serial.println("subscribe to cmd FAILED");
 }
}

```

```

    } } void
publishData()
{ digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH)
; dist=duration*speed/2;
if(dist<100){
    String payload = "{\"Normal Distance\":\"";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: "); Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str()))
    { Serial.println("Publish OK");
    }
}

} if(dist>101 &&
dist<111){
    String payload = "{\"Alert distance\":\"";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload); if(client.publish(publishTopic,
(char*) payload.c_str())) {
        Serial.println("Warning crosses 110cm -- it automatically of the loop");
        digitalWrite(led,HIGH);
    }else {
        Serial.println("Publish FAILED");
    }
}

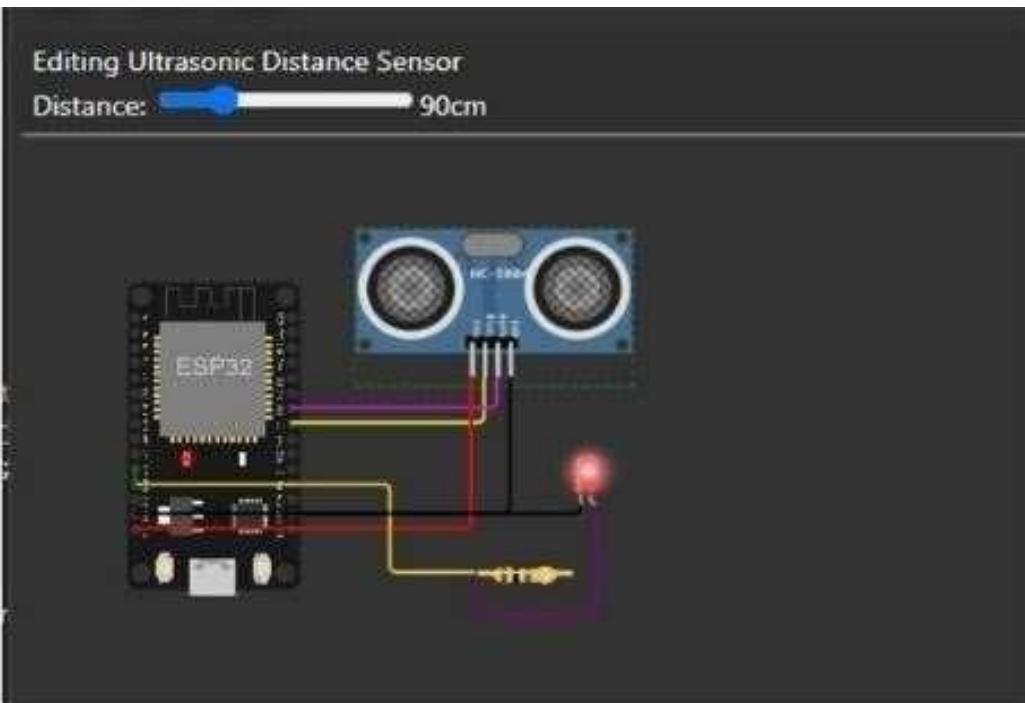
}

void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){
dist += (char)payload[i];
}

```

```
 }
Serial.println("data:"+ data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
}
data3="";
}
```

## NODE-RED



```
Sending payload: {"Normal Distance":89.95}
```

```
Publish OK
```

```
Sending payload: {"Normal Distance":89.95}
```

```
Publish OK
```

```
Sending payload: {"Normal Distance":89.95}
```

```
Publish OK
```

```
Sending payload: {"Normal Distance":89.98}
```

```
Publish OK
```

```
Sending payload: {"Normal Distance":89.95}
```

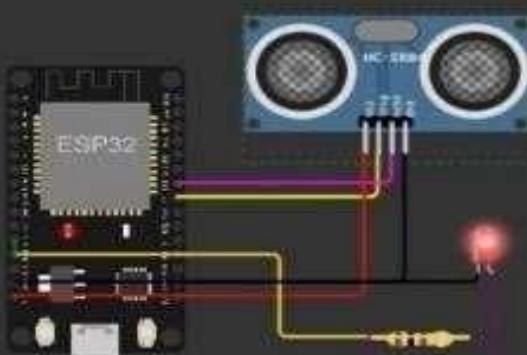
```
Publish OK
```

```
Sending payload: {"Normal Distance":89.95}
```

```
Publish OK
```

### Editing Ultrasonic Distance Sensor

Distance:  107cm



```
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

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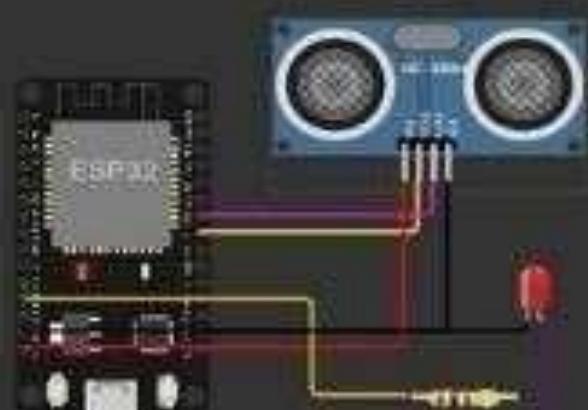
Sending payload: {"Alert distance":106.98}
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Warning crosses 110cm -- it automatically of the loop
```

### Editing Ultrasonic Distance Sensor

Distance:  125cm



```
Sending payload: {"Alert distance":106.96}
Warning crosses 110cm -- it automatically of the loop

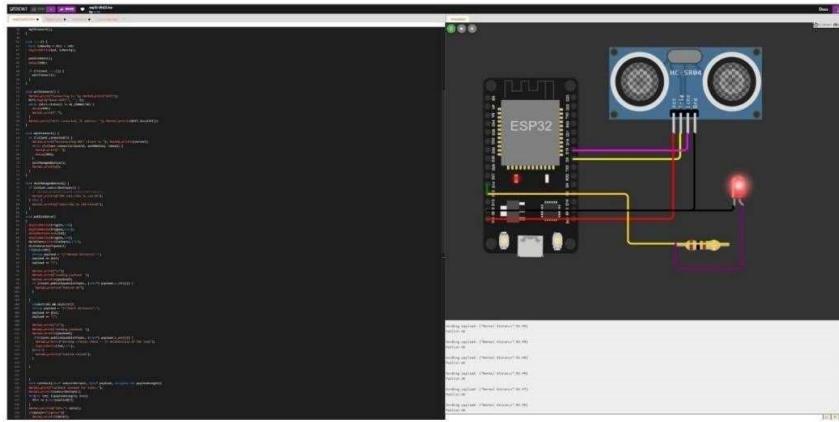
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

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Warning crosses 110cm -- it automatically of the loop
```

## OUTPUT



### Connection Information

Basic connection information about this device.

Device ID	Assignment4
Device Type	nodeMcu
Date Added	23 Oct 2022 07:20
Added By	920219104302@smartinternz.com
Connection Status	Disconnected
Last Connected:	23 Oct 2022 16:57
Client Address:	145.40.94.93 Insecure
Duration:	3 minutes
Data Transferred:	14.4 KB

### Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago