#### **Assignment -4**

Assignment Date	31 October 2022
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Maximum Marks	2 Marks

### **Ouestion:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

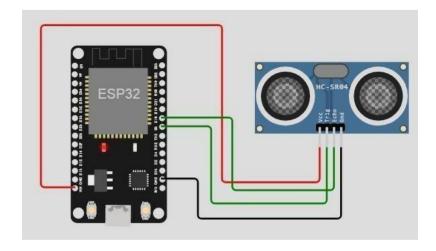
#### Code:

```
#include <WiFi.h>
 #include <PubSubClient.h> void callback(char* subscribetopic,
 byte* payload, unsigned int payloadLength);
 //----credentials of IBM Accounts-----
 #define ORG "kwjr15"//IBM ORGANITION ID
 #define DEVICE TYPE "ultrasonic sensor"//Device type mentioned in ibm watson
 IOT Platform #define DEVICE ID "1234"//Device ID mentioned in ibm watson IOT
 Platform #define TOKEN "3HOX?sRVnfKSMTUxe2" //Token String
 data3; char server[] = ORG
 ".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
 = "iot-2/evt/Data/fmt/json"; char subscribetopic[] = "iot-
 2/cmd/test/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
 char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
 WiFiClient wifiClient;
 PubSubClient client(server, 1883, callback ,wifiClient);
 const int trigPin = 5; const int echoPin = 18; #define
 SOUND_SPEED 0.034 long duration; float distance; void
 setup() { Serial.begin(115200); pinMode(trigPin,
 OUTPUT); pinMode(echoPin, INPUT); wificonnect();
```

```
mgttconnect(); } void loop() { digitalWrite(trigPin,
    LOW); delayMicroseconds(2); digitalWrite(trigPin, HIGH);
    delayMicroseconds(10); digitalWrite(trigPin, LOW);
    duration = pulseIn(echoPin, HIGH); distance = duration *
    SOUND SPEED/2:
    Serial.print("Distance (cm): "):
    Serial.println(distance): if(distance<100)</pre>
    Serial.println("ALERT!!"); delay(1000);
    PublishData(distance) : delay(1000); if
    (!client.loop()) { mattconnect():
    } } delay(1000); } void
    PublishData(float dist) {
    mqttconnect();
    String payload = "{\"Distance\":": payload += dist:
    payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
    payload += "}";
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c str())) {
    Serial.println("Publish ok");
    } else {
    Serial.println("Publish failed");
    } } void mattconnect() {
    if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
    Serial.print(".")
    ; delay(500);
    }
initManagedDevice();
Serial.println();
} }
```

```
void wificonnect()
Serial.println(): Serial.print("Connecting to "):
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() !=
WL CONNECTED) { delay(500);
Serial.print(".");
}
Serial.println(""): Serial.println("WiFi
connected"); Serial.println("IP address: ");
Serial.println(WiFi.localIP());
} void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe
to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
} } void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength) {
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic); for (int i =
0; i < payloadLength; i++) {
//Serial.print((char)payload[i])
    ; data3 += (char)payload[i];
    Serial.println("data: "+ data3); data3="";
    }
         Diagram.json:
      "version": 1, "author":
      "sweetysharon",
      "editor": "wokwi",
```

# **Circuit Diagram:**



## Output:

# Wokwi output:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.98
Distance (cm): 399.98
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.92
Distance (cm): 399.94
```

## **IBM cloud output:**

