DATE	10/10/2022
TEAM ID	PNT2022TMID43222
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MAXIMUM MARKS	2 MARKS

## **ASSIGNMENT 1**

## **OBJECTIVE:**

Make a smart Home in, using 2+ sensors, led, buzzer in single code and circuit.

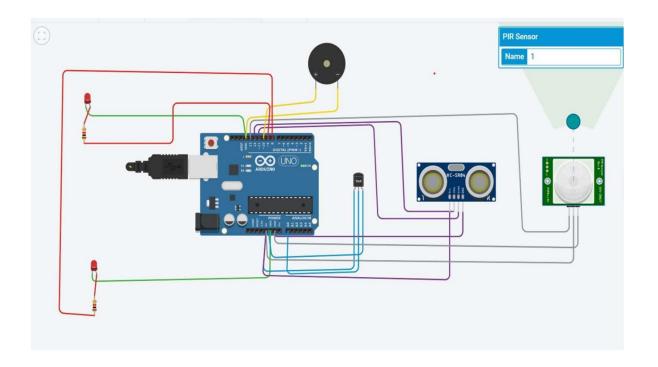
## CODE:

```
// C++ code
int trig=13;
int echo=12;
void setup()
{
 pinMode(trig,OUTPUT);
 pinMode(echo,INPUT);
 pinMode(11,INPUT);
Serial.begin(9600);
 pinMode(10,OUTPUT); // buzzer for temp
 pinMode(8,OUTPUT); //led of ultrasonic
pinMode(9,OUTPUT); //led of pir
}
void loop()
{
double a=analogRead(A5);
Serial.print("adc value:");
```

Serial.println(a);

```
double v=a/1024;
double tvolt=v*5; // here 5 is in volt and thhiseqe for elect to temp volt
Serial.print("temp volt:");
Serial.println(tvolt);
double o=tvolt-0.5; //for octol and 0.5 for min volt for octal
double t=o*100;// this two eqe for volt to temp
Serial.print("temp is:");
Serial.println(t);
//delay(2000);
digitalWrite(trig,LOW); //off
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW); // till this for trigger
float dur=pulseIn(echo,HIGH); // echo on
float dist=(dur*0.0343)/4; //cm to m
Serial.println("distance:");
Serial.println(dist); //ultra sonic
int m=digitalRead(11);
Serial.print("motion detected : ");
Serial.println(m);
if(t>=40)
 Serial.println("******house on fire*****");
 digitalWrite(10,HIGH);//to get
}
else
 digitalWrite(10,LOW);
}
//delay(2000)
```

```
if(dist<=18)
{
 Serial.println("**please kindly turn on light and fan**");
  digitalWrite(8,HIGH); //
}
else
{
  Serial.println("*****turn off light and fan****");
  digitalWrite(2,LOW);
}
if(m==1)
  Serial.println("******open the cupboard*****");
  digitalWrite(9,HIGH);
  delay(50);
}
else
{
  Serial.println("*******close the cupboard*****");
  digitalWrite(9,LOW);
}
delay(50);
}
OUTPUT:
```



## STIMULATION LINK:

https://www.tinkercad.com/things/4P62geulvcp-terrific-bruticus-jaagub/editel