

Assignment -4

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Project Name	Smart Waste Management System for Metropolitan Cities.

Question:

Write a Code and Connections in wokwi for **ultrasonic sensor**. Whenever distance is less than 100 cms send “**alert**” to ibm cloud and display in device recent events.

Code :

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQTT
WiFiClient wifiClient;
String data3;
#define ORG "0x5bsz"
#define DEVICE_TYPE "Arduino"
#define DEVICE_ID "234566"
#define TOKEN "87654321"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Arduino/fmt/json";
char topic[] = "iot-2/cmd/status/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);

const int trigpin=19;
const int echopin=18;
String command;
String data="";

long duration;
float dist;

void setup()
```

```

{
    Serial.begin(115200);
    pinMode(led, OUTPUT);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}

void loop() {
    bool isNearby = dist < 100;
    digitalWrite(led, isNearby);

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: ");
    Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    }
}

```

```

    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}
void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration=pulseIn(echopin, HIGH);
    dist=duration*speed/2;
    if(dist<100){
        String payload = "{\"Alert Distance\":";
        payload += dist;
        payload += "}";

        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish OK");
        }
    }

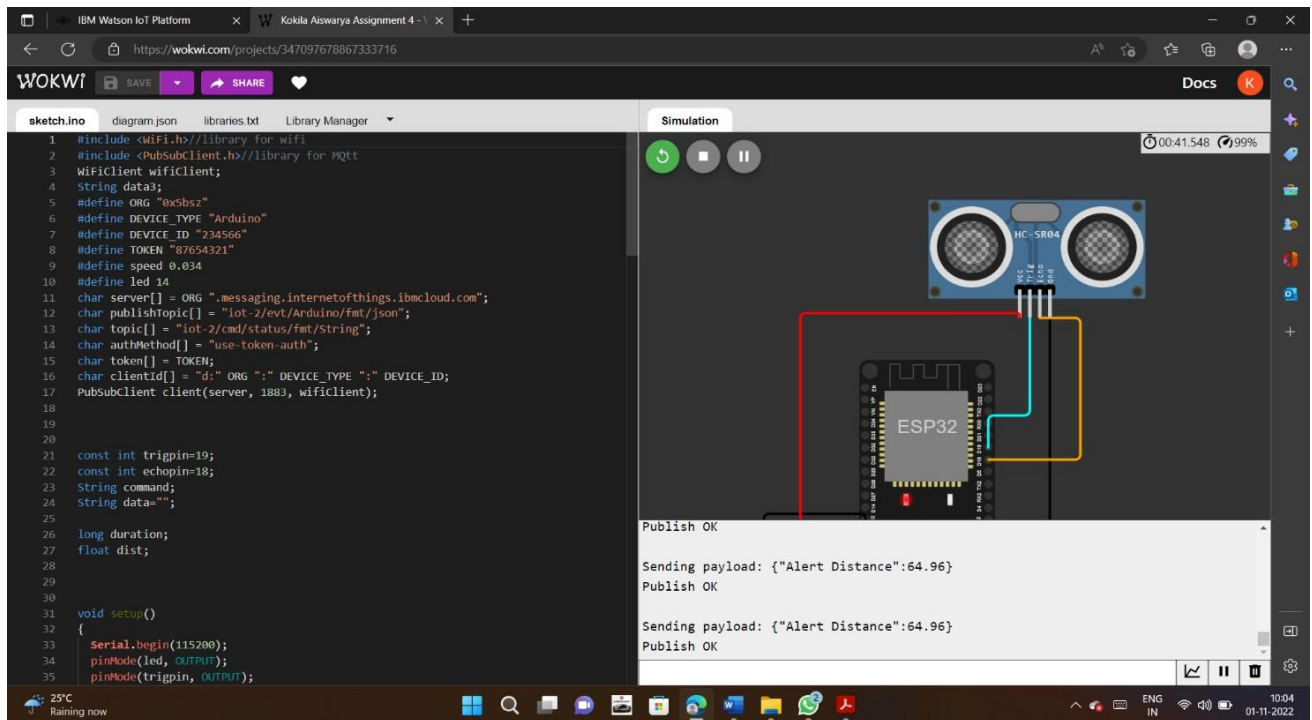
    if(dist>100){
        String payload = "{\"Distance\":";
        payload += dist;
        payload += "}";

        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if(client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish OK");
        }else {
            Serial.println("Publish FAILED");
        }
    }
}
}

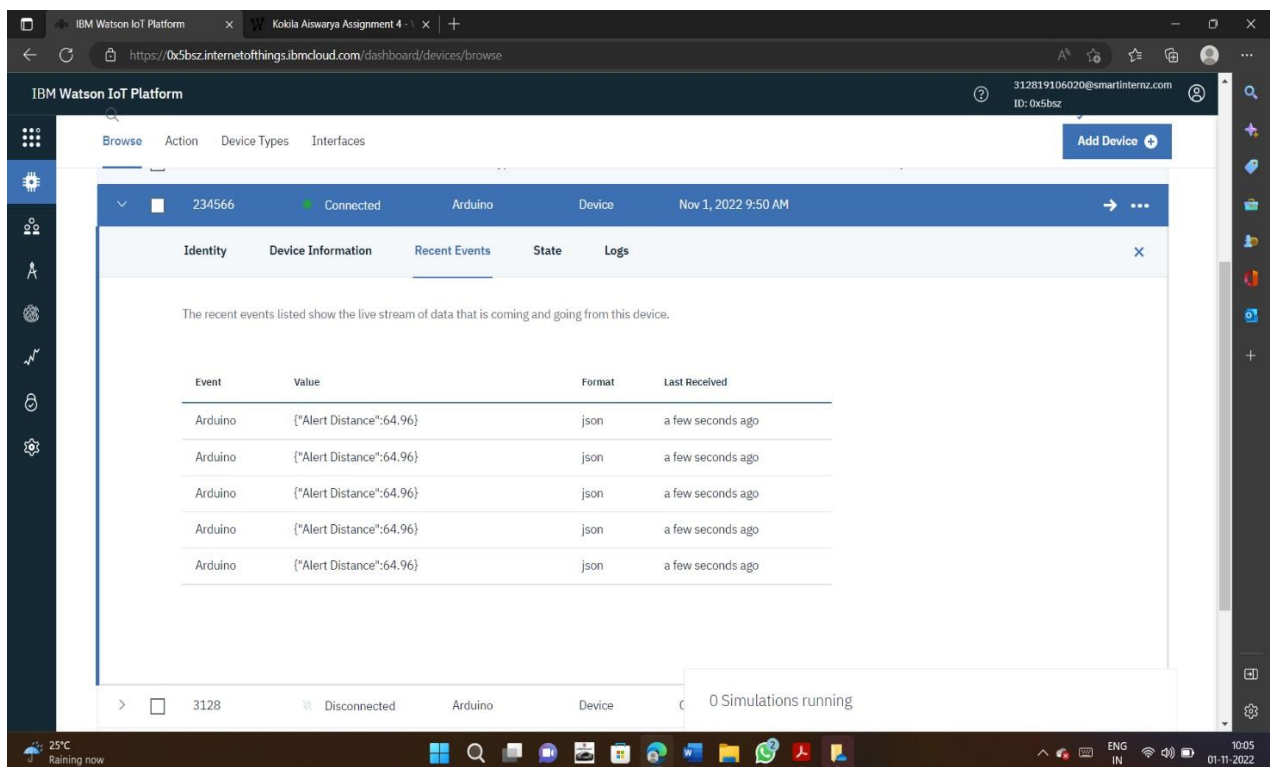
```

OUTPUT:

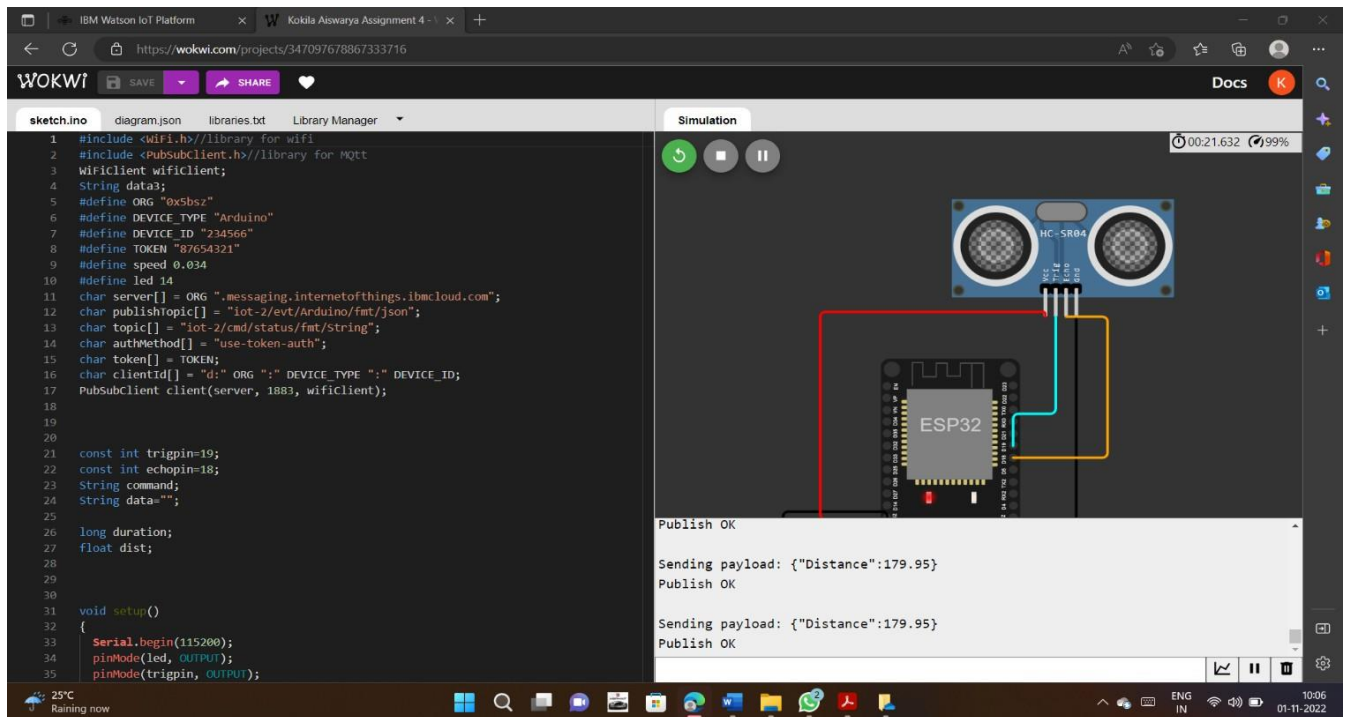
- 1) When distance is less than 100 cm



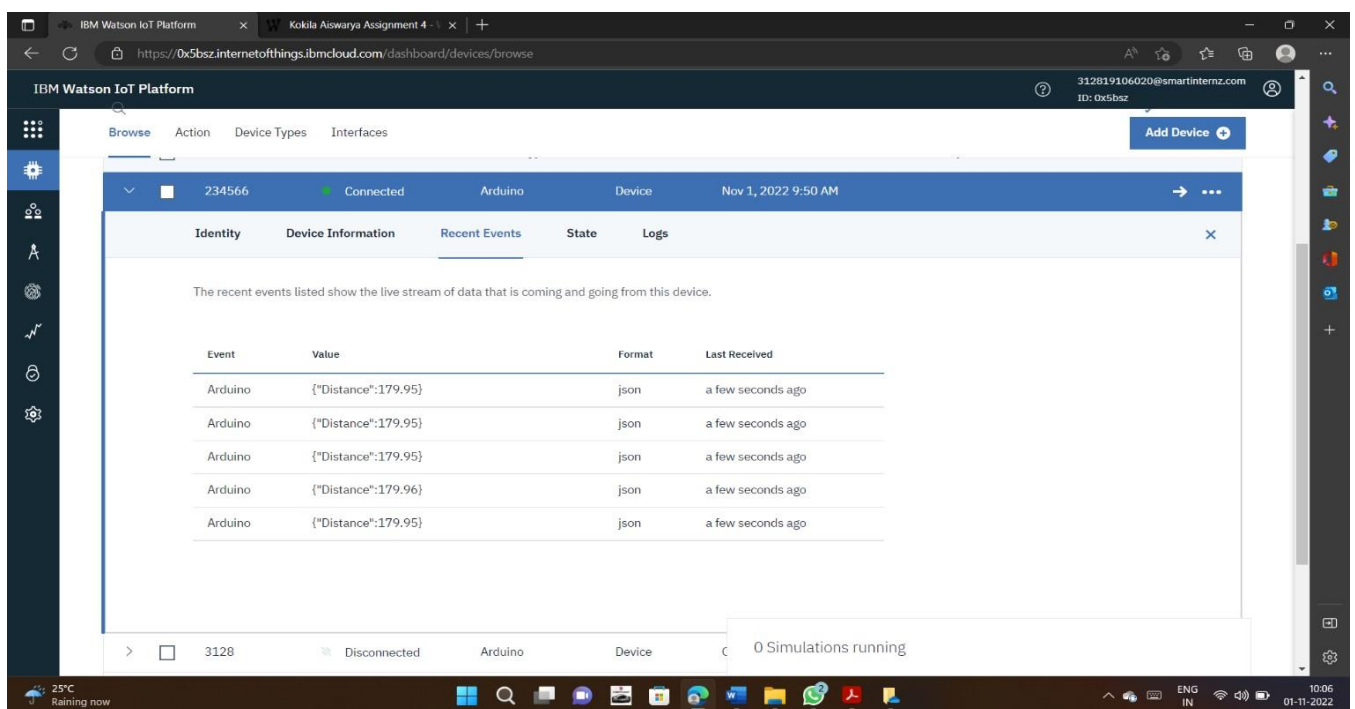
IBM RECENT EVENTS:



2) When distance is greater than 100 cm



IBM RECENT EVENTS:



WOKWI LINK:

<https://wokwi.com/projects/347097678867333716>