

# ASSIGNMENT 4

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Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

## Sketch.ino

```
#include <WiFi.h>

#include <PubSubClient.h>

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "engn92"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP1"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "Assignment4"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token

String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback ,wifiClient);

const int trigPin = 5;
const int echoPin = 18;

#define SOUND_SPEED 0.034

long duration;
float distance;

void setup() {
```

```

Serial.begin(115200);

pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
}

void loop()
{
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
{
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
}
delay(1000);
}

void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":\"";
payload += dist;
payload += "\",\"ALERT!!\":\"\"Distance less than 100cms\"";
payload += "\"}";
}

```

```
Serial.print("Sending payload: ");

Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
} else {
    Serial.println("Publish failed");
}
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void wificonnect()
{
    Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}
```

```

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
  data3="";
}

```

## Diagram.json

```

{
  "version": 1,
  "author": "6154_ SWATHI S",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 17.33, "left": -98.67, "attrs": {} },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": -11.41, "left": 50.44, "attrs": {} }
  ],
  "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],

```

```

[ "ultrasonic1:VCC", "esp:VIN", "red", [ "v0" ] ],
[ "ultrasonic1:GND", "esp:GND.1", "black", [ "v0" ] ],
[ "ultrasonic1:TRIG", "esp:D5", "green", [ "v0" ] ],
[ "ultrasonic1:ECHO", "esp:D18", "green", [ "v0" ] ]
]
}

```

## Wokwi link:

<https://wokwi.com/projects/347186552083841620>

## Output :

The screenshot displays the Wokwi web IDE interface. On the left, the 'sketch.ino' file contains the following code:

```

1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 void callback(char* subscribetopic, byte* payload, unsigned int
4 payloadLength);
5 //-----credentials of IBM Accounts-----
6 #define ORG "engn92"//IBM ORGANITION ID
7 #define DEVICE_TYPE "ESP1"//Device type mentioned in ibm watson IOT Platfo
8 #define DEVICE_ID "Assignment4"//Device ID mentioned in ibm watson IOT Pla
9 #define TOKEN "12345678" //Token
10 String data3;
11 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
12 char publishTopic[] = "iot-2/evt/Data/fmt/json";
13 char subscribetopic[] = "iot-2/cmd/test/fmt/String";
14 char authMethod[] = "use-token-auth";
15 char token[] = TOKEN;
16 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
17 WiFiClient wifiClient;
18 PubSubClient client(server, 1883, callback, wifiClient);
19 const int trigPin = 5;
20 const int echoPin = 18;
21 #define SOUND_SPEED 0.034
22 long duration;
23 float distance;
24 void setup() {
25   Serial.begin(115200);
26   pinMode(trigPin, OUTPUT);
27   pinMode(echoPin, INPUT);

```

On the right, the 'Simulation' window shows a visual representation of the ESP32 and the HC-SR04 sensor. A slider for 'Distance' is set to 84cm. Below the simulation, the console output shows the following sequence of events:

```

100cms}
Publish ok
Distance (cm): 83.98
ALERT!!
Sending payload: {"Distance":83.98,"ALERT!!":"Distance less than
100cms"}
Publish ok

```

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Distance":83.98,"ALERT!!":"Distance less than ...	json	a few seconds ago
Data	{"Distance":83.98,"ALERT!!":"Distance less than ...	json	a few seconds ago
Data	{"Distance":83.98,"ALERT!!":"Distance less than ...	json	a few seconds ago
Data	{"Distance":83.98,"ALERT!!":"Distance less than ...	json	a few seconds ago
Data	{"Distance":83.98,"ALERT!!":"Distance less than ...	json	a few seconds ago