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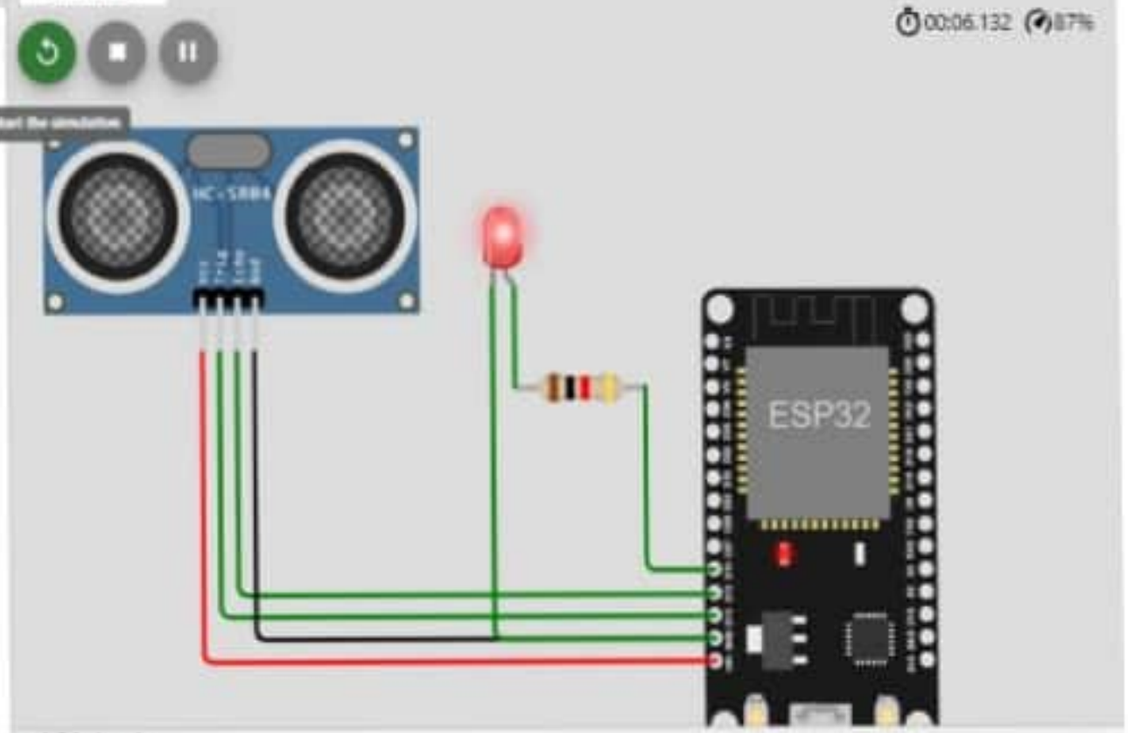
```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int payloadLength);
#define ORG "tca72r"
#define DEVICE_TYPE "raspberrypi"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
String data3;

char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/Data/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;

WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);

#define ECHO_PIN 12
#define TRIG_PIN 13
#define led 14

void setup() {
  // put your setup code here, to run once:
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  wificonnect();
  mqttconnect();
}
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
```

Simulation

00:06.132 87%




```
publish ok
Measured distance: 83.00
Sending payload:{"ALERT":83.00}
publish ok
Measured distance: 42.00
Sending payload:{"ALERT":42.00}
publish ok
```

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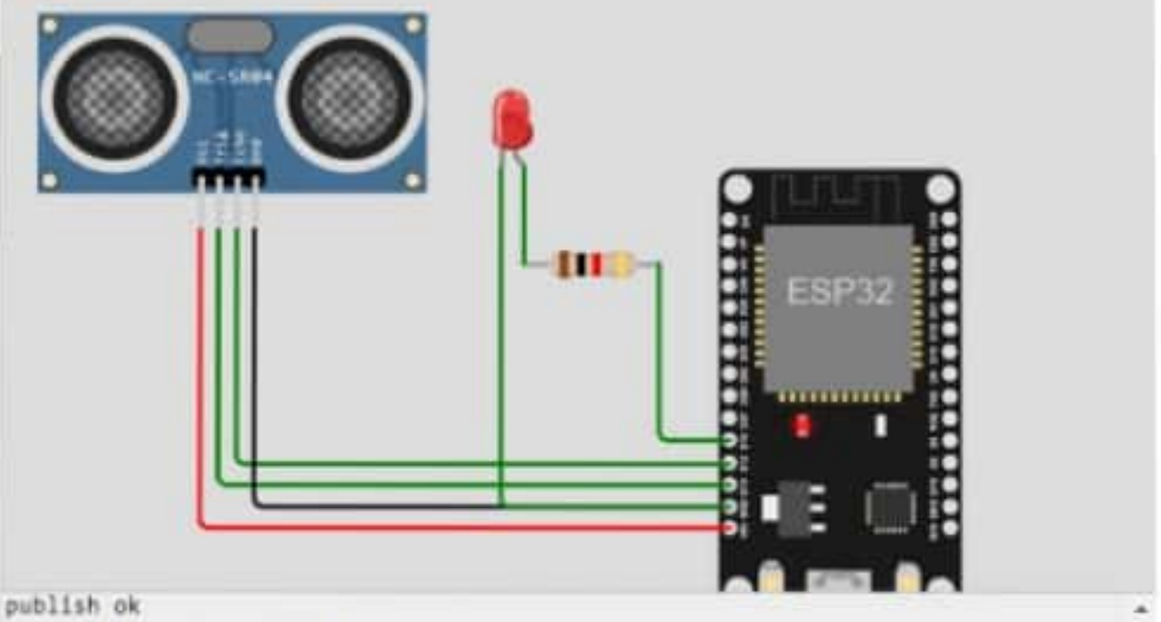
```
  mqttconnect();
}
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration=random(1,200);
  //Serial.println(duration);
  //duration = pulseIn(ECHO_PIN, HIGH);
  return duration ;
  //Serial.println(duration);

}

void loop() {
  float distance = readDistanceCM();
  //Serial.println(distance);

  bool isNearby = distance < 100;
  digitalWrite(led, isNearby);

  Serial.print("Measured distance: ");
  Serial.println(distance);
if(distance<100){
  PublishData2(distance);

}else{
  PublishData1(distance);

}
//PublishData(distance);
delay(1000);
```

Simulation

00:13.147 94%




```
publish ok
Measured distance: 90.00
Sending payload:{"ALERT":90.00}
publish ok
Measured distance: 191.00
Sending payload:{"distance":191.00}
publish ok
```

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```
//PublishData(distance);
delay(1000);
if(!client.loop()){
  mqttconnect();
}

  //delay(2000);
}
void PublishData1(float dist){
  mqttconnect();
  String payload= "{\"distance\":";
  payload += dist;
  payload+="}";

  Serial.print("Sending payload:");
  Serial.println(payload);

  if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
}
void PublishData2(float dist){
  mqttconnect();
  String payload= "{\"ALERT\":";
  payload += dist;
  payload+="}";

  Serial.print("Sending payload:");
  Serial.println(payload);

  if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
```

Simulation

00:20.978 99%


```
publish ok
Measured distance: 123.00
Sending payload:{"distance":123.00}
publish ok
Measured distance: 68.00
Sending payload:{"ALERT":68.00}
publish ok
```

```
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
}
void mqttconnect(){
  if(!client.connected()){
    Serial.print("Reconnecting to");
    Serial.println(server);
    while(!!!client.connect(clientID, authMethod, token)){
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void wificonnect(){
  Serial.println();
  Serial.print("Connecting to");

  WiFi.begin("Wokwi-GUEST","",6);
  while(WiFi.status()!=WL_CONNECTED){
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WIFI CONNECTED");
  Serial.println("IP address:");
  Serial.println(WiFi.localIP());
}

void initManagedDevice(){
  if(client.subscribe(subscribeTopic)){
```

```
publish ok
Measured distance: 154.00
Sending payload:{"distance":154.00}
publish ok
Measured distance: 143.00
Sending payload:{"distance":143.00}
publish ok
```

```
void initManagedDevice(){
  if(client.subscribe(subscribeTopic)){
    Serial.println((subscribeTopic));
    Serial.println("subscribe to cmd ok");
  }else{
    Serial.println("subscribe to cmd failed");
  }
}

void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){
    data3 += (char)payload[i];
  }
  Serial.println("data:"+ data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }else{
    Serial.println(data3);
    digitalWrite(led,LOW);
  }
  data3="";
}
```

```
publish ok
Measured distance: 13.00
Sending payload:{"ALERT":13.00}
publish ok
Measured distance: 116.00
Sending payload:{"distance":116.00}
publish ok
```