ASSIGNMENT- 1

Domain: IOT

PROJECT TITLE: GAS DETECTION MONITORING &

ALERTING SYSTEM

TEAM ID: PNT2022TMID15954

TEAM MEMBERS:

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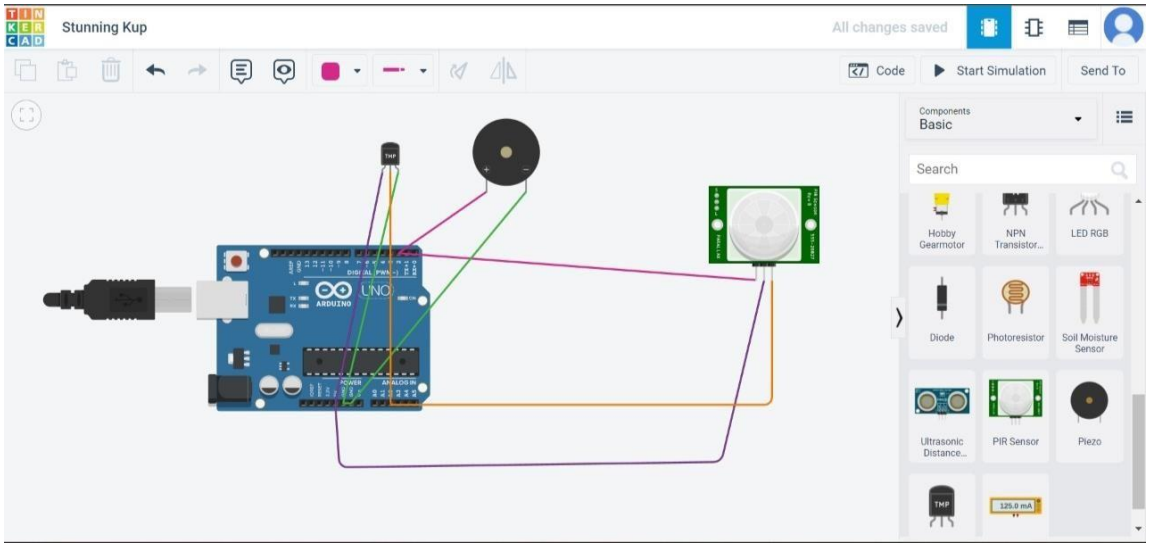

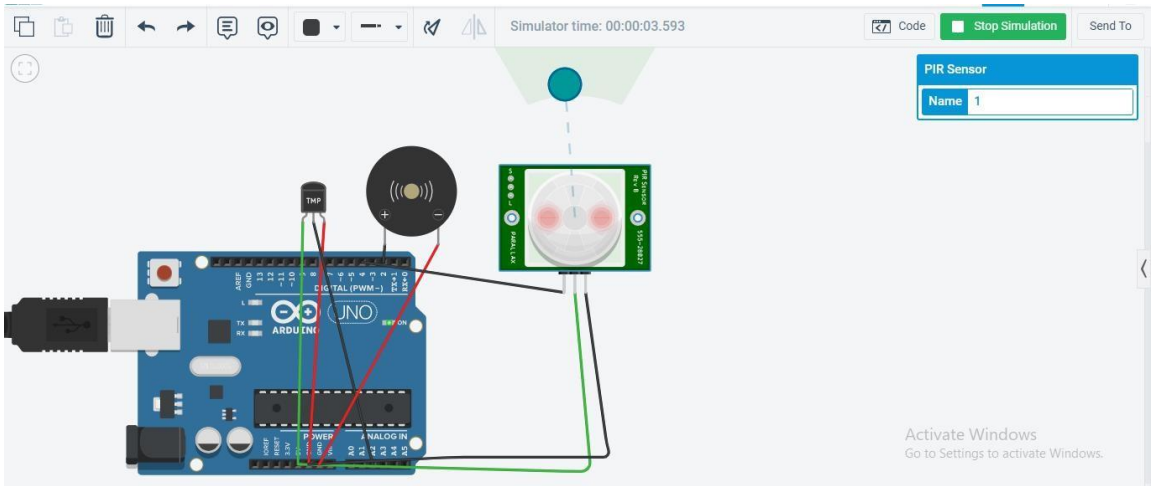

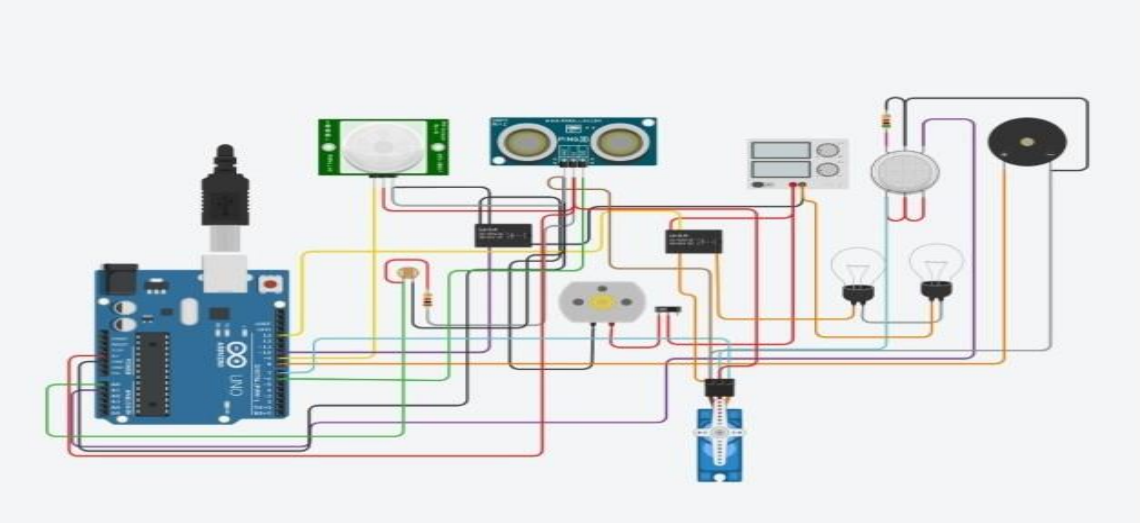

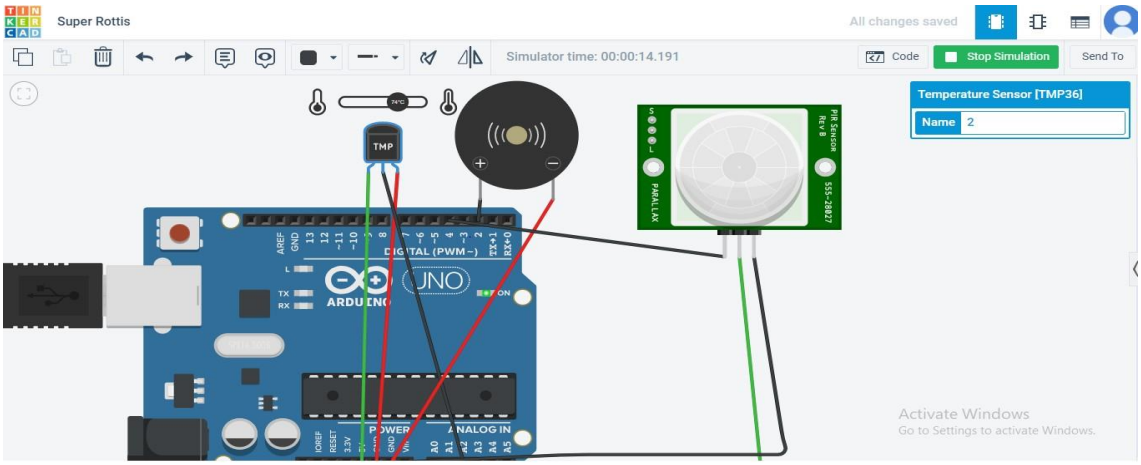

SourceCode:

```
#include <Servo.h>

int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const gas_sensor = A1;
int const LDR = A0;
int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)
{
  pinMode(triggerPin, OUTPUT);  // Clear the trigger
  digitalWrite(triggerPin, LOW);
  delayMicroseconds(2);
// Sets the trigger pin to HIGH state for 10 microseconds
  digitalWrite(triggerPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(triggerPin, LOW);
  pinMode(echoPin, INPUT);
```

```
 // Reads the echo pin, and returns the sound wave travel time in microseconds
 return pulseIn(echoPin, HIGH);
}

Servo servo_7;

void setup()
{
  Serial.begin(9600);              //initialize serial communication
 pinMode(A0, INPUT);              //LDR
 pinMode(A1,INPUT);               //gas sensor
 pinMode(13, OUTPUT);                    //connected to relay
 servo_7.attach(7, 500, 2500); //servo motor

 pinMode(8,OUTPUT);               //signal to piezo buzzer
 pinMode(9, INPUT);               //signal to PIR
 pinMode(10, OUTPUT);                    //signal to npn as switch
 pinMode(4, OUTPUT);                     //Red LED
 pinMode(3, OUTPUT);                     //Green LED

}

void loop()
{
 //------light intensity control------//
   int val1 = analogRead(LDR);
 if (val1 > 500)
          {
          digitalWrite(13, LOW);
   Serial.print("Bulb ON = ");
   Serial.print(val1);
          }
 else
          {
          digitalWrite(13, HIGH);
    Serial.print("Bulb OFF = ");
   Serial.print(val1);
          }
//------ light & fan control --------//

 sen2Value = digitalRead(9);
 if (sen2Value == 0)
          {
          digitalWrite(10, LOW); //npn as switch OFF
          digitalWrite(4, HIGH); // Red LED ON,indicating no motion
          digitalWrite(3, LOW); //Green LED OFF, since no Motion detected
   Serial.print("     || NO Motion Detected    " );
          }

 if (sen2Value == 1)
          {
          digitalWrite(10, HIGH);//npn as switch ON
   delay(5000);
          digitalWrite(4, LOW); // RED LED OFF
```

```
        digitalWrite(3, HIGH);//GREEN LED ON , indicating motion detected
    Serial.print("              || Motion Detected!     " );
        }
  // ------- Gas Sensor --------//
int val = analogRead(gas_sensor);     //read sensor value
  Serial.print("|| Gas Sensor Value = ");
  Serial.print(val);                                        //Printing in serial monitor
//val = map(val, 300, 750, 0, 100);
  if (val > limit)
        {
        tone(8, 650);
        }
        delay(300);
        noTone(8);

 //-------  servo motor  ---------//
  sen1Value = 0.01723 * readUltrasonicDistance(6, 6);

  if (sen1Value < 100)
        {
        servo_7.write(90);
    Serial.print("              || Door Open!  ; Distance = ");
    Serial.print(sen1Value);
   Serial.print("\n");

        }
  else
        {
        servo_7.write(0);
    Serial.print("              || Door Closed! ; Distance =  ");
    Serial.print(sen1Value);
    Serial.print("\n");
  }
  delay(10); // Delay a little bit to improve simulation performance
}
```