

Assignment - 4

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Maximum Marks: 2 Marks

Question-1:

Write a code connection in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send “alert” to ibm cloud and display in device recent events.

Solution:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "s3qdw6"
#define DEVICE_TYPE "CloudProject"
#define DEVICE_ID "164163"
#define TOKEN "0903202008052002"
#define speed 0.034 #define
led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json"; char topic[] =
"iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-
auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5; const
int echopin=18;
String command;
String data="";

long duration;
float dist;

void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
```

```

    wifiConnect();
    mqttConnect();
}
void loop() {
    bool isNearby = dist < 100; digitalWrite(led,
    isNearby);

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to ");
    Serial.print("Wifi"); WiFi.begin("Wokwi-
    GUEST", "", 6); while (WiFi.status() !=
    WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd
        OK"); } else {
        Serial.println("subscribe to cmd FAILED");
    } } void publishData()
{ digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);

```

```

delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
    String payload = "{\"Normal Distance\":\"";
    payload += dist;
    payload += "\"}";

    Serial.print("\n");
    Serial.print("Sending payload: "); Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str()))
    { Serial.println("Publish OK");
    }

} if(dist>101 &&
dist<111){
    String payload = "{\"Alert distance\":\"";
    payload += dist;
    payload += "\"}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload); if(client.publish(publishTopic,
(char*) payload.c_str())) {
        Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
        digitalWrite(led,HIGH);
    }else {
        Serial.println("Publish FAILED");
    }

}

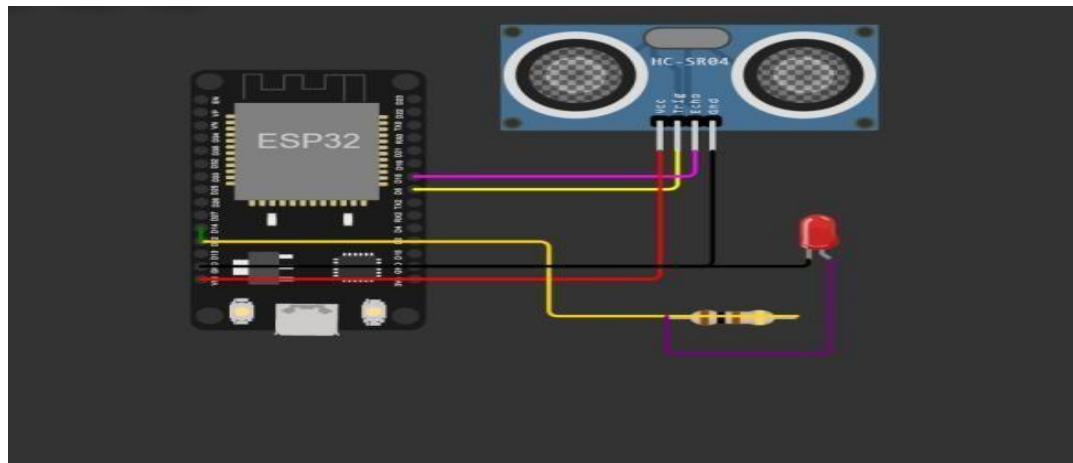
}

}

void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
    Serial.print("callback invoked for topic:");
    Serial.println(subscribeTopic);
    for(int i=0; i<payloadLength; i++){
        dist += (char)payload[i];
    }
    Serial.println("data:" + data3);
    if(data3=="lighton"){
        Serial.println(data3);
        digitalWrite(led,HIGH);
    }
    data3="";
}

```

Output:



```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

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