

**Assignment -4**  
Python Programming

Assignment Date	05 November 2022
Student Name	Nivedha J
Student Roll Number	211519104104
Maximum Marks	2 Marks

**Question-1:**

Write code and connection in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an alert to the IBM cloud and display in the device recent events.

**Solution:**

**Code:**

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>

WiFiClient wifiClient;

#define ORG "50f1c2"
#define DEVICE_TYPE "esp32_rasp"
#define DEVICE_ID "assignment-4"
#define TOKEN "Yu435T(1VH+cV-!0(3"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/event_1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5;
const int echopin=18;
String command;
String data="";
String lat="14.167589";
String lon="80.248510";
String name="point2";
String icon="";

long duration;
int dist;
```

```

void setup()
{
    Serial.begin(115200);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}

void loop() {

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: ");
    Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        Serial.println(client.subscribe(topic));
        Serial.println("subscribe to cmd OK");
    } else {

```

```

        Serial.println("subscribe to cmd FAILED");
    }
}
void publishData()
{
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;

    if(dist<100){
        dist=100-dist;
        icon="fa-trash";
    }else{
        dist=0;
        icon="fa-trash-o";
    }
    DynamicJsonDocument doc(1024);
    String payload;
    doc["Name"]=name;
    doc["Latitude"]=lat;
    doc["Longitude"]=lon;
    doc["Icon"]=icon;
    doc["FillPercent"]=dist;
    serializeJson(doc, payload);
    delay(3000);
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    } else {
        Serial.println("Publish FAILED");
    }
}
}

```

## Diagram.json

```

{
    "version": 1,
    "author": "Nivedha",
    "editor": "wokwi",
    "parts": [
        { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 20,
"left": -24.67, "attrs": {} },

```

```

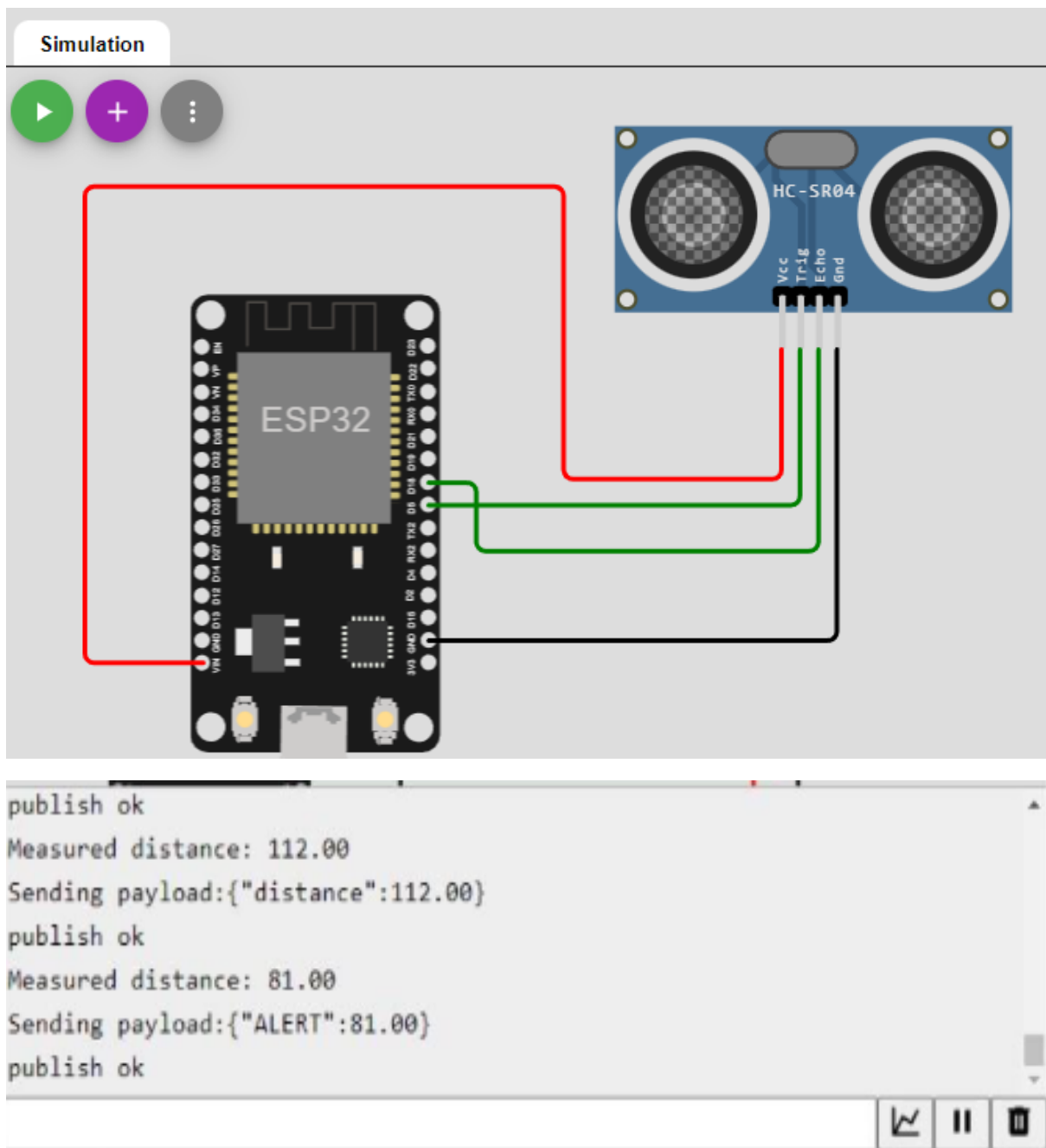
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": -
49.54, "left": 155.67, "attrs": {} }
  ],
  "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
    [
      "esp:VIN",
      "ultrasonic1:VCC",
      "red",
      [ "h-50.66", "v-202.96", "h204.67", "v124.67", "h85.33" ]
    ],
    [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h0" ] ],
    [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h20.37",
"v29.17", "h146" ] ],
    [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h0" ] ]
  ]
}

```

**Wokwi link:**

<https://wokwi.com/projects/305566932847821378>

## OUTPUT:





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The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
event_1	{"distance":311}	json	a few seconds ago
event_1	{"distance":69}	json	a few seconds ago
event_1	{"distance":325}	json	a few seconds ago
event_1	{"distance":124}	json	a few seconds ago
event_1	{"distance":52}	json	a few seconds ago

1 Simulation running