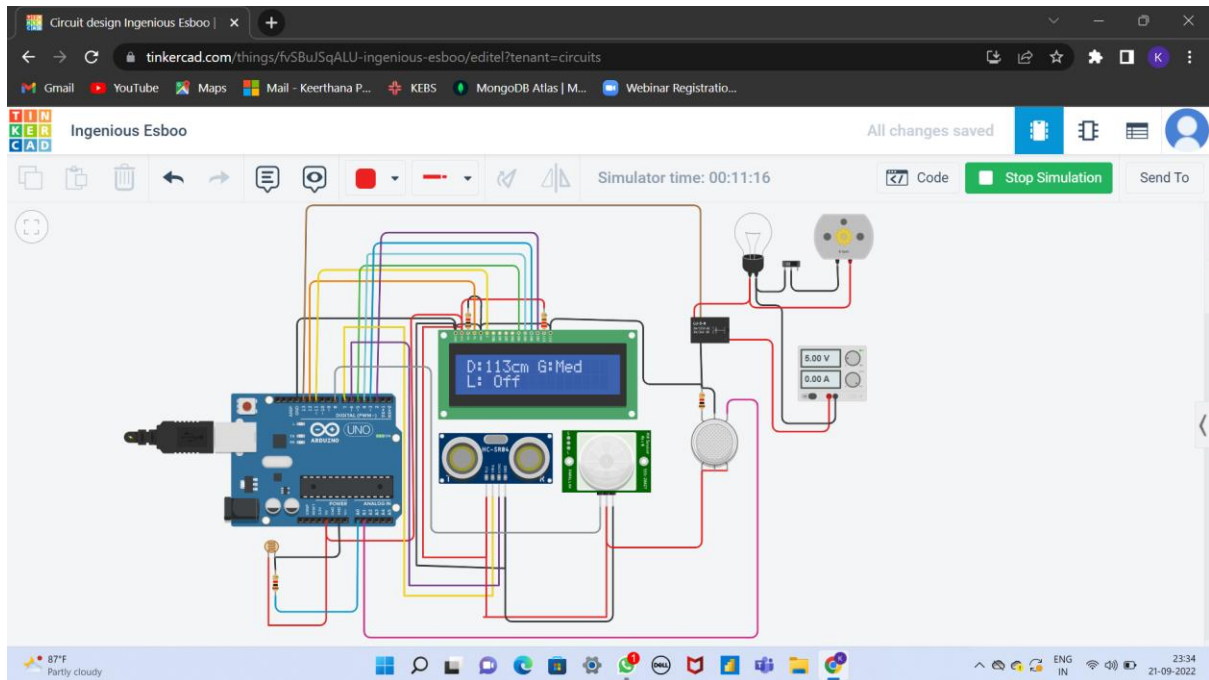


# SMART HOME AUTOMATION



```
// include the library code:
```

```
#include <LiquidCrystal.h>
```

```
// initialize the library with the numbers of the interface pins
```

```
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
```

```
//For ultrasound sensor
```

```
int distanceThreshold = 0;
```

```
int cm = 0;
```

```
int inches = 0;
```

```
//for Relay Control
```

```
int releNO = 13;
```

```
int inputPir = 8;
```

```
int val = 0;
```

```
int resuldoSensorLDR;
```

```
int sensorLDR = A0;
```

```
//For Gas sensor
```

```
int const PINO_SGAS = A1;
```

```
long readUltrasonicDistance(int triggerPin, int echoPin)
```

```
{
```

```
  pinMode(triggerPin, OUTPUT); // Clear the trigger
```

```
  digitalWrite(triggerPin, LOW);
```

```
  delayMicroseconds(2);
```

```
  // Sets the trigger pin to HIGH state for 10 microseconds
```

```
  digitalWrite(triggerPin, HIGH);
```

```
  delayMicroseconds(10);
```

```
  digitalWrite(triggerPin, LOW);
```

```
  pinMode(echoPin, INPUT);
```

```
  // Reads the echo pin, and returns the sound wave travel time in microseconds
```

```
  return pulseIn(echoPin, HIGH);
```

```
}
```

```
void setup() {
```

```
  // set up the LCD's number of columns and rows:
```

```
  lcd.begin(16, 2);
```

```
  pinMode(releNO, OUTPUT);
```

```
  pinMode(inputPir, INPUT);
```

```
  pinMode(sensorLDR, INPUT);
```

```
  Serial.begin(9600);
```

```
}
```

```
void loop() {
```

```
// set threshold distance to activate LEDs
distanceThreshold = 350;

// measure the ping time in cm
cm = 0.01723 * readUltrasonicDistance(7, 6);

// convert to inches by dividing by 2.54
inches = (cm / 2.54);
```

```
lcd.setCursor(0,0); // Sets the location at which subsequent text written to the LCD will be
displayed
```

```
lcd.print("D:"); // Prints string "Distance" on the LCD
lcd.print(cm); // Prints the distance value from the sensor
lcd.print("cm");
delay(10);
```

```
val = digitalRead(inputPir);
resuldoSensorLDR = analogRead(sensorLDR);
if(resuldoSensorLDR<600)
{
    if(val == HIGH)
    {
        digitalWrite(releNO, HIGH);
        lcd.setCursor(0,1);
        lcd.print("L: On ");
        delay(5000);
    }
    else{
        digitalWrite(releNO, LOW);lcd.setCursor(0,1);
        lcd.print("L: Off");
        delay(300);
    }
}
```

```
else{ digitalWrite (releNO, LOW);  
Serial.println(resuldoSensorLDR);  
delay(500);  
}
```

```
int color = analogRead(PINO_SGAS);
```

```
lcd.setCursor(8,0);  
//lcd.print("");  
if(color <= 85){  
    lcd.print("G:Low ");  
} else if(color <= 120){  
    lcd.print("G:Med ");  
} else if(color <= 200){  
    lcd.print("G:High");  
} else if(color <= 300){  
    lcd.print("G:Ext ");  
}
```

```
delay(250);  
}
```