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### **Question-1:**

**Write a python code for blinking LED for Raspberry pi.**

```
#!/usr/bin/env python
import RPi.GPIO as GPIO # RPi.GPIO can be referred as GPIO from now
import time
ledPin = 22 # pin22
def setup():
    GPIO.setmode(GPIO.BOARD) # GPIO Numbering of Pins
    GPIO.setup(ledPin, GPIO.OUT) # Set ledPin as output
    GPIO.output(ledPin, GPIO.LOW) # Set ledPin to LOW to turn Off
    the LED
def loop():
    while True:
        print 'LED on'
        GPIO.output(ledPin, GPIO.HIGH) # LED On
        time.sleep(1.0 ) # wait 1 sec
        print 'LED off'
        GPIO.output(ledPin, GPIO.LOW) # LED Off
        time.sleep(1.0) # wait 1 sec
def endprogram():
    GPIO.output(ledPin, GPIO.LOW) # LED Off
    GPIO.cleanup() # Release resources
if __name__ == '__main__': # Program starts from here
    setup()
    try:
        loop()
    except KeyboardInterrupt: # When 'Ctrl+C' is pressed, the destroy()
        will be executed.
    endprogram()
```

### **Question-2:**

**Write a python code for Traffic lights for Raspberry pi.**

```
#!/usr/bin/python3.4
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
GPIO.setup(4, GPIO.IN, pull_up_down = GPIO.PUD_DOWN) # Button
GPIO.setup(17, GPIO.OUT, initial = GPIO.HIGH) # RED
GPIO.setup(27, GPIO.OUT, initial = GPIO.HIGH) # YELLOW
GPIO.setup(18, GPIO.OUT, initial = GPIO.HIGH) # GREEN
GPIO.setup(22, GPIO.OUT, initial = GPIO.LOW) # Buzzer
x = 1 # Variable to control traffic light system
try:
```

```
while True:
    if(GPIO.input(4) == True):
        while(x == 1):
            GPIO.output(17, GPIO.LOW)
            GPIO.output(22, GPIO.HIGH)
            time.sleep(2)
            GPIO.output(22, GPIO.LOW)
            GPIO.output(27, GPIO.LOW)
            time.sleep(3)
            GPIO.output(17, GPIO.HIGH)
            GPIO.output(27,GPIO.HIGH)
            GPIO.output(18, GPIO.LOW)
            time.sleep(5)
            GPIO.output(18, GPIO.HIGH)
            time.sleep(2)
        except Exception as ex:
            print("error occured",ex)
        finally:
            GPIO.cleanup()
```