## **ASSIGNMENT 4**

| Assignment Date     | 15 October 2022 |
|---------------------|-----------------|
| Student Name        | Velmurugan P    |
| Student Roll Number | 190128          |
| Maximum Marks       | 2 Marks         |

Write Code and connections in wok Wi for ultrasonic sensor. Whatever distance is less than 100 cms send "Alert" to ibm cloud a and display in device recent events.

```
Solution:
//Pins
const int TRIG_PIN =
7:
const int ECHO_PIN
= 8;
//Anything over 400 cm (23200 us pulse) is "out of
range" const unsigned int MAX_DIST = 23200;
void setup () {
// The Trigger pin will tell the sensor to range
find Pin Mode (TRIG_PIN, OUTPUT);
digital Write (TRIG_PIN, LOW);
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance
sensor pinMode(ECHO_PIN, INPUT);
// We'll use the serial monitor to view the sensor
```

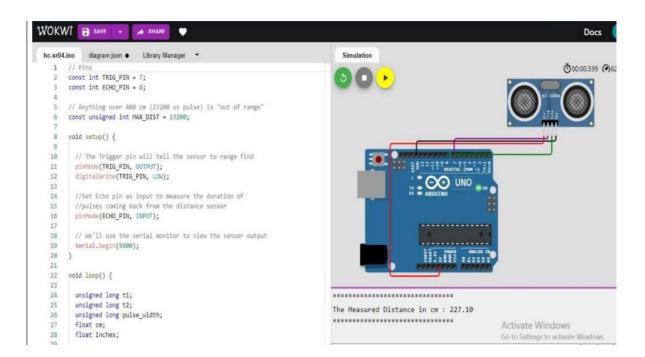
```
output Serial.begin(9600);
}
void loop () {
unsigned long
t1;
unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;
// Hold the trigger pin high for at least 10
us digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN) ==0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros () counter will overflow after-70
min t1= micros ();
while (digitalRead(ECHO_PIN)
 == 1); t2= micros ();
 pulse_width = t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (-
340m/s) cm=pulse_Width / 58;
inches = pulse_width/148.0;
```

```
// Print out results
if (pulse_width >MAX _
DIST){ Serial.println("Out of
range");
} else { Serial.println("******************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if (cm < 100) {
   //while(true){
   Serial.println("Alert!!");
   //}
}
Serial.print("****************************);
//wait at least 1000ms before next
measurement Delay (1000);
}
```

## **Output:**

1.If the distance is less than 100 cms ,it alerts.

## 2.If the distance is more than 100 cms, it won't alert



## 3. Simulation and code execution

