ASSIGNMENT - 1

BUILD A SMART HOME IN TINKERCAD

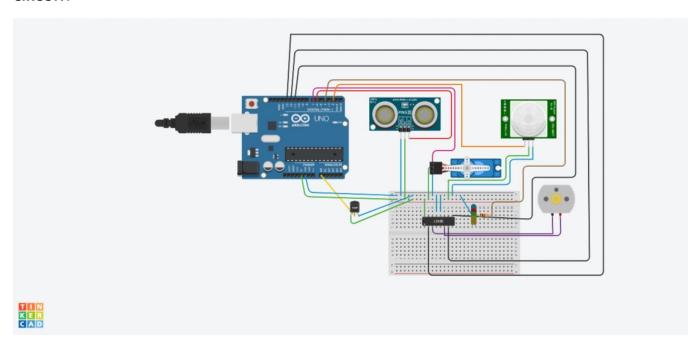
Assignment date	26 September 2022
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Maximum marks	2Marks

QUESTION -1:

Build a smart home in tinkercad Use atleast 2 sensor, led, buzzer in a circuit. Stimulate in a single code.

Solution:

CIRCUIT:



CODE:

#include<Servo.h>

int us = 6;

int servo = 7;

Servo servo1;

void setup() {

Serial.begin(9600);

```
servo1.attach(servo);
 pinMode(2,INPUT);
 pinMode(4,OUTPUT);
 pinMode(11,OUTPUT);
 pinMode(12,OUTPUT);
 pinMode(13,OUTPUT);
 pinMode(A0,INPUT);
 digitalWrite(2,LOW);
 digitalWrite(11,HIGH);
}
void loop() {
 long duration, inches, cm;
 pinMode(us, OUTPUT);
 digitalWrite(us, LOW);
 delayMicroseconds(2);
 digitalWrite(us, HIGH);
 delayMicroseconds(5);
 digitalWrite(us, LOW);
 pinMode(us, INPUT);
 duration = pulseIn(us, HIGH);
 inches = microsecondsToInches(duration);
 cm = microsecondsToCentimeters(duration);
 servo1.write(0);
 if(cm < 30)
  servo1.write(120);
  Serial.println("A Person Arrived, Door is Opening.....");
  delay(2000);
 }
```

```
Else
 {
  servo1.write(0);
  Serial.println("Door is Closed.....");
 }
 int pir = digitalRead(2);
 if(pir == HIGH)
 {
  digitalWrite(4,HIGH);
  delay(3000);
 }
 else if(pir == LOW)
 {
  digitalWrite(4,LOW);
 float value=analogRead(A0);
 float temp=(((value/1024)*5.0199)-0.5)*100;
 Serial.print("temp is ");
 Serial.println(temp);
 delay(3000);
 if(temp > 20)
 {
  digitalWrite(12,HIGH);
  digitalWrite(13,LOW);
 }
 Else
```

```
{
    digitalWrite(12,LOW);
    digitalWrite(13,LOW);
}
long microsecondsToInches(long microseconds) {
    return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
    return microseconds / 29 / 2;
}
```