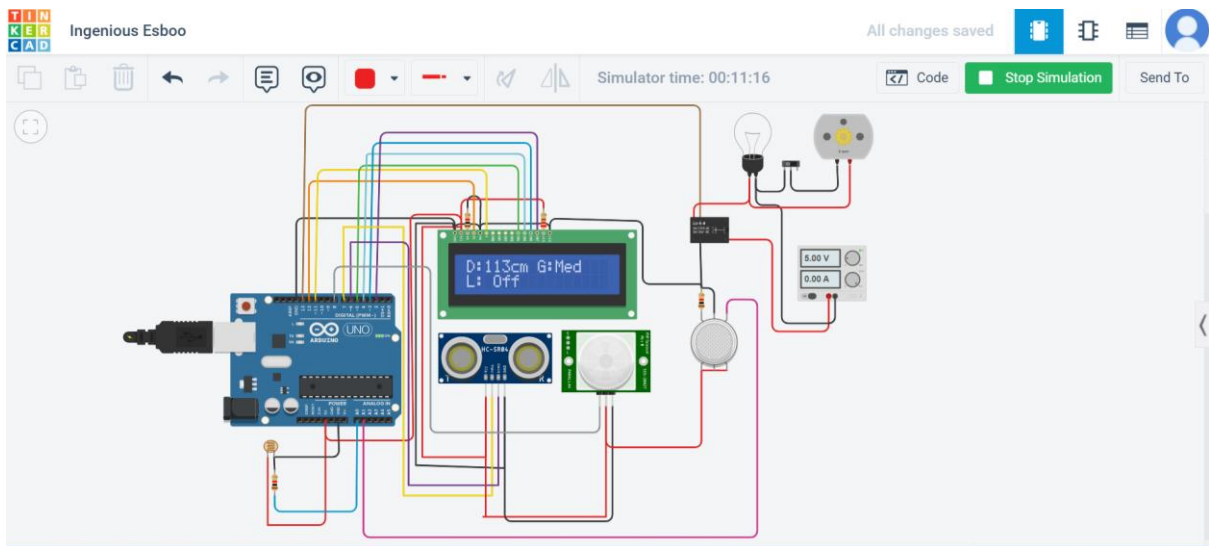


SMART HOME AUTOMATION



// include the library code:

```
#include <LiquidCrystal.h>
```

// initialize the library with the numbers of the interface pins

```
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
```

//For ultrasound sensor

```
int distanceThreshold = 0;
```

```
int cm = 0;
```

```
int inches = 0;
```

//for Relay Control

```
int releNO = 13;
```

```
int inputPir = 8;
```

```
int val = 0;
```

```
int resuldoSensorLDR;
```

```
int sensorLDR = A0;
```

```
//For Gas sensor
```

```
int const PINO_SGAS = A1;
```

```
long readUltrasonicDistance(int triggerPin, int echoPin)
```

```
{
```

```
  pinMode(triggerPin, OUTPUT); // Clear the trigger
```

```
  digitalWrite(triggerPin, LOW);
```

```
  delayMicroseconds(2);
```

```
  // Sets the trigger pin to HIGH state for 10 microseconds
```

```
  digitalWrite(triggerPin, HIGH);
```

```
  delayMicroseconds(10);
```

```
  digitalWrite(triggerPin, LOW);
```

```
  pinMode(echoPin, INPUT);
```

```
  // Reads the echo pin, and returns the sound wave travel time in microseconds
```

```
  return pulseIn(echoPin, HIGH);
```

```
}
```

```
void setup() {
```

```
  // set up the LCD's number of columns and rows:
```

```
  lcd.begin(16, 2);
```

```
  pinMode(releNO, OUTPUT);
```

```
  pinMode(inputPir, INPUT);
```

```
  pinMode(sensorLDR, INPUT);
```

```
  Serial.begin(9600);
```

```
}
```

```
void loop() {
```

```
  // set threshold distance to activate LEDs
```

```
  distanceThreshold = 350;
```

```
// measure the ping time in cm
```

```
cm = 0.01723 * readUltrasonicDistance(7, 6);
```

```
// convert to inches by dividing by 2.54
```

```
inches = (cm / 2.54);
```

```
lcd.setCursor(0,0); // Sets the location at which subsequent text written to the LCD will be displayed
```

```
lcd.print("D:"); // Prints string "Distance" on the LCD
```

```
lcd.print(cm); // Prints the distance value from the sensor
```

```
lcd.print("cm");
```

```
delay(10);
```

```
val = digitalRead(inputPir);
```

```
resuldoSensorLDR = analogRead(sensorLDR);
```

```
if(resuldoSensorLDR<600)
```

```
{
```

```
  if(val == HIGH)
```

```
  {
```

```
    digitalWrite(releNO, HIGH);
```

```
    lcd.setCursor(0,1);
```

```
    lcd.print("L: On ");
```

```
    delay(5000);
```

```
  }
```

```
  else{
```

```
    digitalWrite(releNO, LOW);lcd.setCursor(0,1);
```

```
    lcd.print("L: Off");
```

```
    delay(300);
```

```
  }
```

```
}
```

```
else{ digitalWrite (releNO, LOW);
```

```
Serial.println(resuldoSensorLDR);
```

```
delay(500);
```

```
}
```

```
int color = analogRead(PINO_SGAS);
```

```
lcd.setCursor(8,0);
```

```
//lcd.print("");
```

```
if(color <= 85){
```

```
    lcd.print("G:Low ");
```

```
} else if(color <= 120){
```

```
    lcd.print("G:Med ");
```

```
} else if(color <= 200){
```

```
    lcd.print("G:High");
```

```
} else if(color <= 300){
```

```
    lcd.print("G:Ext ");
```

```
}
```

```
delay(250);
```

```
}
```