#### **ASSIGNMENT 4**

DATE	12 November 2022
TEAM ID	PNT2022TMID36752
NAME	HARI.N
Maximum Marks	2 Marks

## **Question 1:**

Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100cmssend"alert"toibmcloudanddisplayindevicerecentevents.

# CODE:

#include <WiFi.h> #include < PubSubClient.h > void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength); //----credentials of IBM Accounts-----#define ORG "910vsj"//IBM ORGANITION ID #define DEVICE\_TYPE "Assignment4"//Device type mentioned in ibm watson IOT Platform #define DEVICE\_ID "d2327"//Device ID mentioned in ibm watson IOT Platform #define TOKEN "ibm12345" //Token String data3; float dist; //----- Customise the above values -----char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING char authMethod[] = "use-token-auth";// authentication method

```
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by passing
parameter like server id, portand wificredential
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
{
digitalWrite(trig,LOW);
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
 digitalWrite(trig,LOW);
 float dur = pulseIn(echo,HIGH);
```

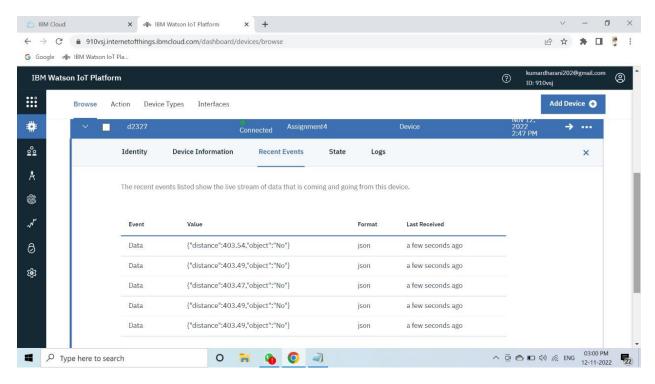
```
float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
Serial.println(dist);
 PublishData(dist);
delay(1000);
if (!client.loop()) {
  mqttconnect();
}
/.....retrieving to Cloud....../
void PublishData(float dist) {
mqttconnect();//function call for connecting to ibm
  creating the String in in form JSon to update the data to ibm cloud
 */
String object;
if (dist <100)
  digitalWrite(LED,HIGH);
  Serial.println("object is near");
  object = "Near";
}
else
  digitalWrite(LED,LOW);
```

```
Serial.println("no object found");
  object = "No";
 }
 String payload = "{\"distance\":";
 payload += dist;
 payload += "," "\"object\":\"";
 payload += object;
 payload += "\"}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in
Serial monitor or else it will print publish failed
 } else {
  Serial.println("Publish failed");
 }
}
void mqttconnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
```

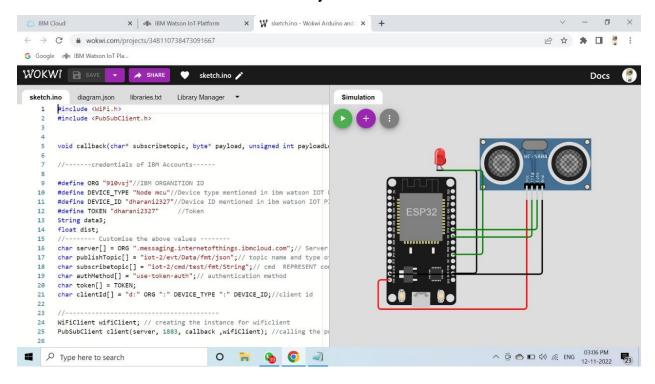
```
while (!!!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  initManagedDevice();
  Serial.println();
 }
void wificonnect() //function defination for wificonnect
{
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 }
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
  Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
```

```
} else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
  //Serial.print((char)payload[i]);
  data3 += (char)payload[i];
 }
 // Serial.println("data: "+ data3);
// if(data3=="Near")
// {
// Serial.println(data3);
// digitalWrite(LED,HIGH);
// }
// else
// {
// Serial.println(data3);
// digitalWrite(LED,LOW);
// }
data3="";
```

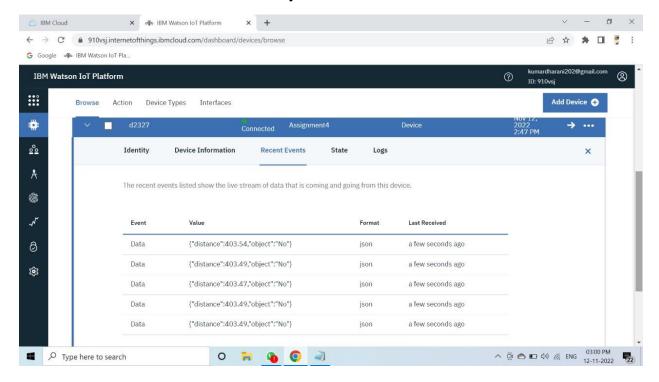
### **OUTPUT:**



## Data send to the IBM cloud device when the objecticsfar



## ${\bf Datas ent to the IBMC loud Device when the object is near}$



# Whenobjecticsneartotheultrasonicsensor

