

SPRINT 4

CODE FOR ARDUINO

TEAM ID	PNT2022TMID36752
PROJECT NAME	REAL-TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM
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```
#include <OneWire.h>
#include <DallasTemperature.h>
#define ONE_WIRE_BUS 5
OneWire oneWire(ONE_WIRE_BUS);
DallasTemperature sensors(&oneWire);
float Celcius=0;
float Fahrenheit=0;
float voltage=0;
const int analogInPin = A0;
int sensorValue = 0;
unsigned long int avgValue;
float b;
int buf[10],temp;
void setup(void)
{
  Serial.begin(9600);

  sensors.begin();
  int sensorValue = analogRead(A1);
  voltage = sensorValue * (5.0 / 1024.0);
}
void loop(void)
{
  sensors.requestTemperatures();
  Celcius=sensors.getTempCByIndex(0);
  Fahrenheit=sensors.toFahrenheit(Celcius);
  for(int i=0;i<10;i++)
  {
    buf[i]=analogRead(analogInPin);
    delay(10);
  }
  for(int i=0;i<9;i++)
  {
```

```

for(int j=i+1;j<10;j++)
{
if(buf[i]>buf[j])
{
temp=buf[i];
buf[i]=buf[j];
buf[j]=temp;
}
}
}
for(int i=2;i<8;i++)
avgValue+=buf[i];
float pHVol=(float)avgValue*5.0/1024/6;

float pHValue = -5.70 * pHVol + 21.34;
Serial.println(pHValue);
Serial.print("pH");
Serial.print(" C ");
Serial.print(Celcius);
Serial.print(voltage);
Serial.print("V");
delay(10000);
}

```

CODE IMPLEMENTATION:

```

import serial
import time
import csv
import numpy as np
import matplotlib.pyplot as plt
ser = serial.Serial('/COM6',9600)
ser_bytes = ser.readline(10)
print (ser_bytes)
ser.flushInput()
while True:
try:
ser_bytes = ser.readline()
decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
print(decoded_bytes)

temp = float(decoded_bytes(1:3))
turb = float(decoded_bytes(4:6))
pH = float(decoded_bytes(6:8))
with open("test_data.csv","a") as f:
writer = csv.writer(f,delimiter=",")
writer.writerow([time.time(),decoded_bytes])

```

```

except:
print("Keyboard Interrupt")
ser.close()
break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
plt.xlabel('time (s)')
plt.ylabel('Celsius (C)')
plt.title('Temperature')
plt.grid(True)
plt.savefig("Temperature.png")
plt.show()
Serial.begin(9600);
sensors.begin();
int sensorValue = analogRead(A1);
voltage = sensorValue * (5.0 / 1024.0);
}
void loop(void)

{
sensors.requestTemperatures();
Celcius=sensors.getTempCByIndex(0);
Fahrenheit=sensors.toFahrenheit(Celcius);
for(int i=0;i<10;i++)
{
buf[i]=analogRead(analogInPin);
delay(10);
}
for(int i=0;i<9;i++)
{
for(int j=i+1;j<10;j++)
{
if(buf[i]>buf[j])
{
temp=buf[i];
buf[i]=buf[j];
buf[j]=temp;
}
}
}
n = 256
X = np.linspace(-np.pi, np.pi, 256, endpoint=True)
C,S = np.cos(X), np.sin(X)
plt.plot(X, C)
plt.plot(X,S)
plt.show()

print ("Visualization of real time sensor Data.")

```

```
print("\n")
while True:
    try:
        ser_bytes = ser.readline()
        decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
        print(decoded_bytes)
        temp = float(decoded_bytes(1:3))
        turb = float(decoded_bytes(4:6))
        pH = float(decoded_bytes(6:8))
        with open("test_data.csv","a") as f:
            writer = csv.writer(f,delimiter=",")
            writer.writerow([time.time(),decoded_bytes])
    except:
        print("Keyboard Interrupt")
        ser.close()
        break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
```

OUTPUT:

