

Gesture Based Tool for Sterile Browsing of Radiology Images

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1.INTRODUCTION

1.1 Overview

In this project we use gestures to browse radiology images. Gestures refer to non-verbal form of communication.

A major challenge involved in this process is to provide doctors with efficient, intuitive, accurate and safe means of interaction without affecting the quality of their work. Keyboards and pointing devices, such as a mouse, are today's common method of human—computer interaction.

However, the use of computer keyboards and mouse by doctors and nurses in intensive care units (ICUs) is a common method for spreading infections.

Humans can recognize body and sign language easily. This is possible due to the combination of vision and synaptic interactions that were formed along brain development.

In order to replicate this skill in computers, some problems need to be solved: how to separate objects of interest in images and which image capture technology and classification technique are more appropriate, among others. In this project Gesture based Desktop automation, First the model is trained pre trained on the images of different hand gestures, such as a showing numbers with fingers as 1,2,3,4. This model uses the integrated webcam to capture the video frame. The image of the gesture captured in the video frame is compared with the Pre-trained model and the gesture is identified. If the gesture predicts is 0 - then images is converted into rectangle, 1 - image is Resized , 2 - image is rotated, 3 - image is blurred.

1.2 PURPOSE

It is used to browse through the images obtained using radiology using hand gestures rather than using mouse,keyboard,etc thereby maintaining sterility.

2. LITERATURE SURVEY

2.1 A Gesture-based Tool for Sterile Browsing of Radiology Images - research paper by national library of medicine

The hand gesture control system “*Gestix*” developed by the authors helped the doctor to remain in place during the entire operation, without any need to move to the main control wall since all the commands were performed using hand gestures. The sterile gesture interface consists of a Canon VC-C4 camera, whose pan/tilt/zoom can be initially set using an infrared (IR) remote.

This camera is placed just over a large flat screen monitor .

Additionally, an Intel Pentium IV, (600MHz, OS: Windows XP) with a Matrox Standard II video-capturing device is used.

The “*Gibson*” image browser is a 3D visualization medical tool that enables examination of images, such as: MRIs, CT scans and X-rays. The images are arranged over a multiple layer 3D cylinder. The image of interest is found through rotating the cylinder in the four cardinal directions. To interface the gesture recognition routines with the “*Gibson*” system, information such as the centroid of the hand, its size, and orientation are used to enable screen operations in the “*Gibson*” graphical user interface.

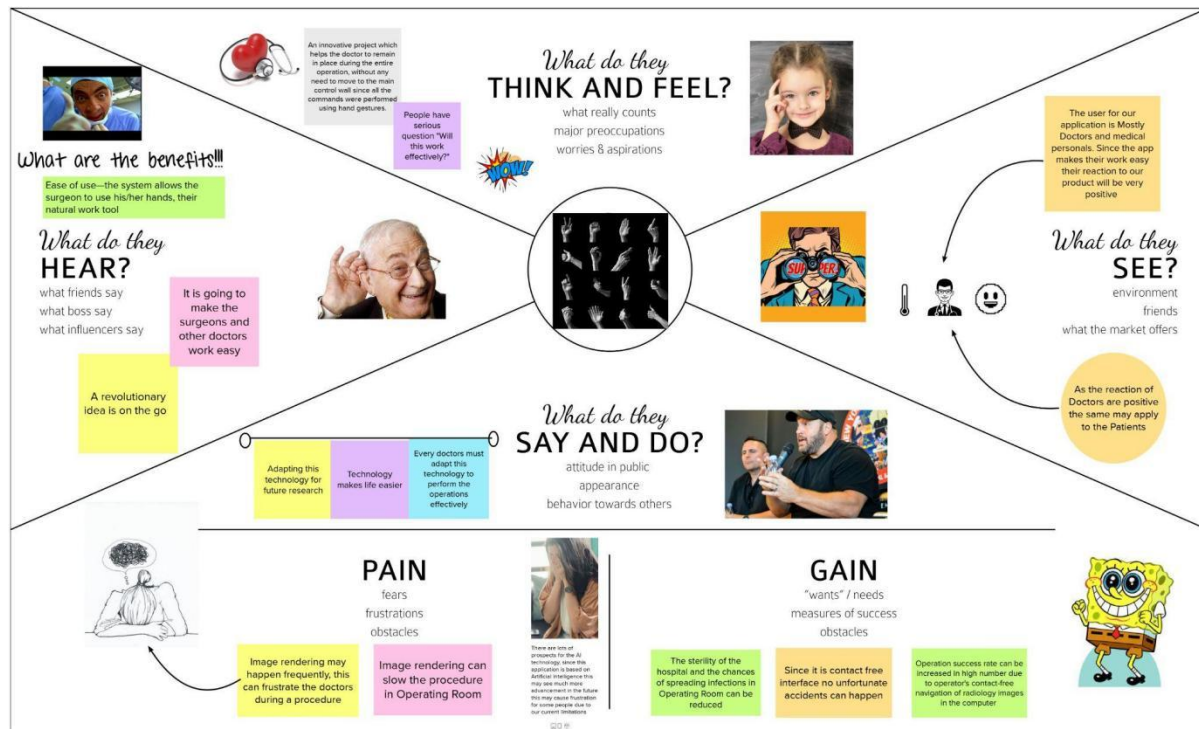


Fig 2. Radiology image browsing using hand gesture in hospital

3.IDEATION & PROPOSED SOLUTION

3.1 EMPATHY MAP CANVAS

It is a useful tool to helps teams better understand their users. Creating an effective solution requires understanding the true problem and the person who is experiencing it. The exercise of creating the map helps participants consider things from the user's perspective along with his or her goals and challenges.



3.2 IDEATION AND BRAINSTROM

Brainstorming provides a free and open environment that encourages everyone within a team to participate in the creative thinking process that leads to problem solving. Prioritizing volume over value, out-of-the-box ideas are welcome and built upon, and all participants are encouraged to collaborate, helping each other develop a rich amount of creative solutions.

Brainstorm, Idea Listing and Grouping

2

Brainstorm

Write down any ideas that come to mind that address your problem statement.

10 minutes

TIP
You can select a sticky note and hit the pencil (click to select) icon to start drawing!

S T SHARAN

Contactless

Fast and efficient

Gloves should not affect the gestures

There is no need for verbal communication

Use of high resolution camera enhance the recognition of gesture

It should be a generalized model

K SANTHOSH

It avoids infections

It should be able to capture the gesture fast

There is no need for frequent sterility

The model does not get distracted

The model should work at any kind of locations

The model could also be integrated with a robot

S SANJAY KUMAR

There is less possibility for misunderstanding of Hand Gestures

The model should be accurate

It is the future of medical domain

The model might be biased

The model should adapt to new gestures in future

The model could be used in Industries too

M SANJITH

Less possibilities of new infections

Doctor Computer interaction based on non verbal communication

A better UI

The model should be stable at any kind of situation

The future gestures should not impact model

Large training data for generalization

3

Group ideas

Take turns sharing your ideas while clustering similar or related notes as you go. In the last 10 minutes, give each cluster a sentence-like label. If a cluster is bigger than six sticky notes, try and see if you can break it up into smaller sub-groups.

20 minutes

Gloves and Infections:

It avoids infections

Contactless

Gloves should not affect the gestures

Less possibilities of new infections

Communication:

The future gestures should not impact model

The model should work at any kind of locations

Model Complexities:

The model might be biased

The model should adapt to new gestures in future

It should be a generalized model

Sensors and cameras:

Doctor Computer interaction based on non verbal communication

There is less possibility for misunderstanding of Hand Gestures

It should be able to capture the gesture fast

Use of high resolution camera enhance the recognition of gesture

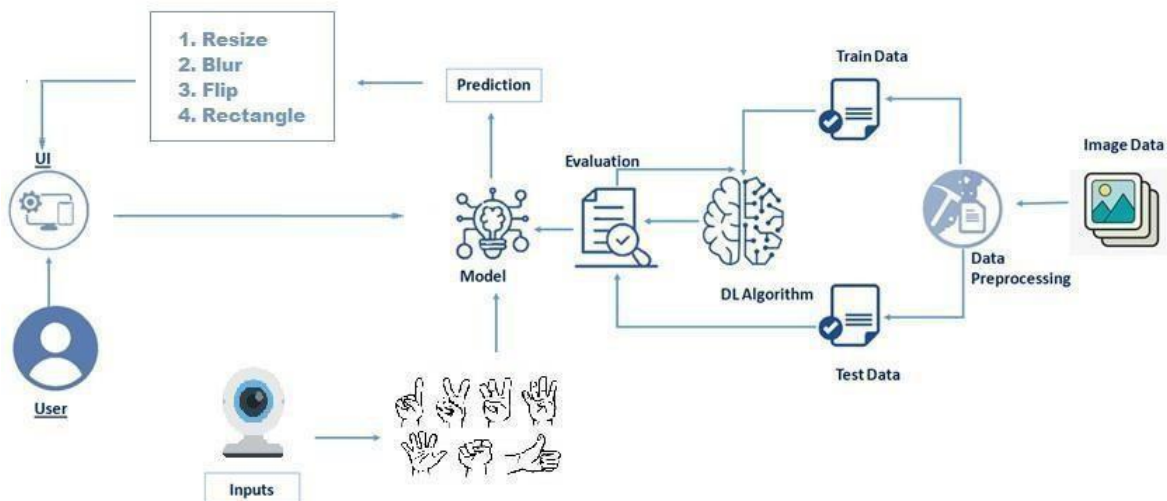


3.3 PROBLEM SOLUTION FIT

A well-articulated customer problem statement allows you and your team to find the ideal solution for the challenges your customers face. Throughout the process, you'll also be able to empathize with your customers, which helps you better understand how they perceive your product or service.

Problem Statement	I am	I'm trying to	But	Because	Which makes me feel
PS-1	a student	build a web application that helps medical professionals to do their work with more sterility	repeated feed has to be provided for an expected output	our system couldn't handle quick hand gestures	motivated to learn similar technologies and to improve the efficiency of our model
PS-2	a student	make a sterile environment in medical fields	the ways to achieve it are not clear	there are lots of technologies	overwhelming
PS-3	a student	make a user friendly gesture based tools	there is an issue in making user friendly GUI	there is very limited source of styling in python based GUI libraries	anxious

4.REQUIREMENT ANALYSIS



We found that many hospitals rely on mouse and keyboard to browse the images that are obtained during different surgeries, scans, etc. This can contaminate the environment with various infections thus compromising the sterility.

Various technologies have been developed to overcome this issue and one such technology was called ‘Gestix’.

This hand gesture system for MRI manipulation in an EMR image database called “*Gestix*” was tested during a brain biopsy surgery. This system is a real-time hand-tracking recognition technique based on color and motion fusion. In an in vivo experiment, this type of interface prevented the surgeon's focus shift and change of location while achieving rapid intuitive interaction with an EMR image database. In addition to allowing sterile interaction with EMRs, the “*Gestix*” hand gesture interface provides:

1. ease of use—the system allows the surgeon to use his/her hands, their natural work tool;
2. rapid reaction—nonverbal instructions by hand gesture commands are intuitive and fast
3. an unencumbered interface—the proposed system does not require the surgeon to attach a microphone, use head-mounted (body-contact) sensing devices or to use foot pedals
4. distance control—the hand gestures can be performed up to 5 meters from the camera and still be recognized accurately.

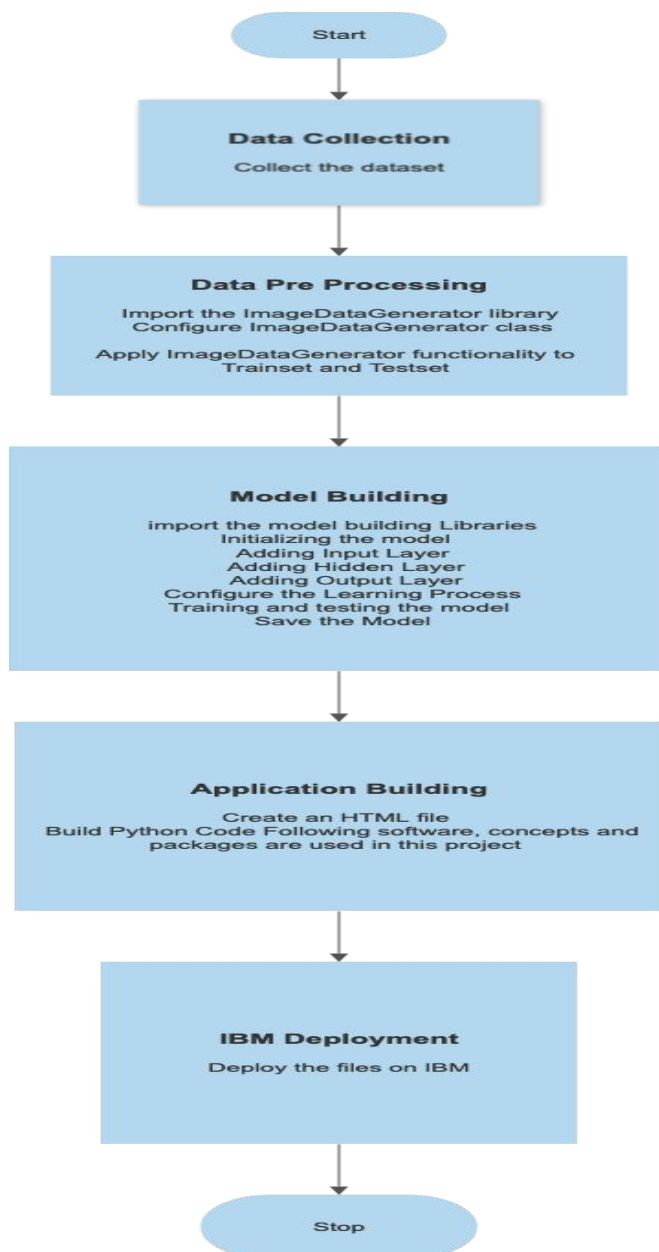
5.PROJECT DESIGN

SOLUTION AND TECHNICAL ARCHITECTURE

User interacts with the UI (User Interface) to upload the image as input.

- Depending on the different gesture inputs different operations are applied to the input image.
- Once model analyses the gesture, the prediction with operation applied on image is showcased on the UI. To accomplish this, we have to complete all the activities and tasks listed below:
- Data Collection.
 - Collect the dataset or Create the dataset
- Data Pre processing
 - Import the ImageDataGenerator library
 - Configure ImageDataGenerator class
 - Apply ImageDataGenerator functionality to Trainset and Testset
- Model Building
 - Import the model building Libraries
 - Initializing the model
 - Adding Input Layer
 - Adding Hidden Layer
 - Adding Output Layer
 - Configure the Learning Process
 - Training and testing the model

- Save the Model
- Application Building
 - Create an HTML file
 - Build Python Code Following software, concepts and packages are used in this project
- Anaconda navigator
- Python packages:
 - open anaconda prompt as administrator
 - Type “pip install TensorFlow” (make sure you are working on python 64bit)
 - Type “pip install opencv-python”
 - Type “pip install flask”



6.PROJECT PLANNING AND SCHEDULING

Product Backlog, Sprint Schedule, and Estimation

Sprint	Functional Requirement (Epic)	User Story Number	User Story / Task	Story Points	Priority	Team Members
Sprint-1	Data collection, Model Building (Training and Testing the model)	USN-1	Collect the hand gesture data set. Import the required libraries. Compile the model, train and save the model and test the model.	2	High	S T Sharan, Sanjay kumar S, Santhosh K
Sprint-1	Downloading Flask	USN-2	Download flask to develop a web application	1	High	S T Sharan, Sanjay kumar S, Santhosh K, Sanjith M
Sprint-1	Registration	USN-3	To register for the application by entering the email, password, and confirming my password.	2	High	S T Sharan, Sanjay kumar S Sanjith M
Sprint-1	Login	USN-4	To create a login for the application by entering email & password	2	High	S T Sharan, Sanjay kumar S Sanjith M
Sprint-2	About	USN-5	I can click on the "About" to get the idea on Gesture based tool for sterile browsing of radiology images	2	Low	S T Sharan, Sanjith M, Santhosh K
Sprint-2	Launch	USN-6	To create launch function which allows us to upload our images	3	High	Sanjay kumar S, S T Sharan, Santhosh K
Sprint-3	Predict	USN-7	Create functions to predict the images	3	High	S T Sharan, Sanjith M, Santhosh K
Sprint-4	Deployment	USN-8	To deploy the project in IBM cloud	3	High	Sanjay kumar S, S T Sharan, Santhosh K

Project Tracker, Velocity & Burndown Chart:

Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date (Planned)	Story Points Completed (as on Planned End Date)	Sprint Release Date (Actual)
Sprint-1	7	6 Days	24 Oct 2022	29 Oct 2022	7	29 Oct 2022
Sprint-2	5	6 Days	31 Oct 2022	05 Nov 2022	5	31 Oct 2022
Sprint-3	3	6 Days	07 Nov 2022	12 Nov 2022	3	07 Nov 2022
Sprint-4	3	6 Days	14 Nov 2022	19 Nov 2022	3	14 Nov 2022

7. CODING AND SOLUTION

```
1 import os
2 import pandas as pd
3 import tensorflow as tf
4 from werkzeug.utils import secure_filename
5 from flask import Flask, render_template, url_for, redirect, request
6 from flask_sqlalchemy import SQLAlchemy #ORM
7 from flask_login import UserMixin, login_user, LoginManager, login_required, logout_user, current_user
8 from flask_wtf import FlaskForm #flask form
9 from wtforms import StringField, PasswordField, SubmitField, IntegerField
10 from wtforms.validators import InputRequired, Length, ValidationError
11 from flask_bcrypt import Bcrypt
12 from werkzeug.utils import secure_filename
13 from werkzeug.datastructures import FileStorage
14 import operator
15 import cv2 # opencv library
16 import matplotlib.pyplot as plt #image processing
17 import matplotlib.image as mpimg #image processing
18 import numpy as np
19 from tensorflow.keras.models import load_model
20 import mediapipe as mp
21 from flask_bootstrap import Bootstrap
22
23 app = Flask(__name__, template_folder="templates")
24 db = SQLAlchemy(app)
25 bcrypt = Bcrypt(app)
26 app.config['SQLALCHEMY_DATABASE_URI'] = 'sqlite:///database.db'
27 app.config['SECRET_KEY'] = 'thisisasecretkey'
28 model=load_model('gesture.h5')
29 print("Loaded model from disk")
30
31 login_manager = LoginManager()
32 login_manager.init_app(app)
33 login_manager.login_view = 'login'
34
35 @login_manager.user_loader
36 def load_user(user_id):
37     return User.query.get(int(user_id))
38
39
40 class User(db.Model, UserMixin):
41     id = db.Column(db.Integer, primary_key=True)
42     username = db.Column(db.String(20), nullable=False, unique=True)
43     password = db.Column(db.String(80), nullable=False)
44
45 class RegisterForm(FlaskForm):
46     username = StringField("Username : ",validators=[
47         InputRequired(), Length(min=4, max=20)], render_kw={"placeholder": "Enter your username"})
48
49     password = PasswordField("Password : ",validators=[
50         InputRequired(), Length(min=8, max=20)], render_kw={"placeholder": "Enter your password"})
51
52     submit = SubmitField('Signup')
53
54 def validate_username(self, username):
55     existing_user_username = User.query.filter_by(username=username.data).first()
56     if existing_user_username:
57         raise ValidationError('That username already exists. Please choose a different one.')
```

```

64
65     password = PasswordField(validators=[
66         InputRequired(), Length(min=8, max=20)], render_kw={"placeholder": "Password"})
67
68     submit = SubmitField('Login')
69
70
71 @app.route('/')
72 def home():
73     return render_template('home.html')
74
75 @app.route('/about')
76 def about():
77     return render_template('about.html')
78
79 @app.route('/login', methods=['GET', 'POST'])
80 def login():
81     form = LoginForm()
82     if form.validate_on_submit():
83         user = User.query.filter_by(username=form.username.data).first()
84         if user:
85             if bcrypt.check_password_hash(user.password, form.password.data):
86                 login_user(user)
87                 return redirect(url_for('dashboard'))
88     return render_template('login.html', form=form)
89
90
91 @app.route('/dashboard', methods=['GET', 'POST'])
92 @login_required
93 def dashboard():
94     return render_template('dashboard.html')
95
96
97 @app.route('/logout', methods=['GET', 'POST'])
98 @login_required

```

```

97 @app.route('/logout', methods=['GET', 'POST'])
98 @login_required
99 def logout():
100     logout_user()
101     return redirect(url_for('home'))
102
103
104 @app.route('/register', methods=['GET', 'POST'])
105 def register():
106     form = RegisterForm()
107
108     if form.validate_on_submit():
109         hashed_password = bcrypt.generate_password_hash(form.password.data)
110         new_user = User(username=form.username.data, password=hashed_password)
111         db.session.add(new_user)
112         db.session.commit()
113         return redirect(url_for('login'))
114
115     return render_template('register.html', form=form)
116
117
118 @app.route('/predict', methods=['GET', 'POST'])# route to show the predictions in a web UI
119 @login_required
120 def launch():
121     if request.method == 'POST':
122         print("inside image")
123         f = request.files['image']
124
125         basepath = os.path.dirname(__file__)
126         file_path = os.path.join(basepath, 'uploads', secure_filename(f.filename))
127         f.save(file_path)
128         print(file_path)
129         cap = cv2.VideoCapture(0)
130         while True:
131             , frame = cap.read() #capturing the video frame values

```

```

126 file_path = os.path.join(basepath, 'uploads', secure_filename(f.filename))
127 f.save(file_path)
128 print(file_path)
129 cap = cv2.VideoCapture(0)
130 while True:
131     _, frame = cap.read() #capturing the video frame values
132     # Simulating mirror image
133     frame = cv2.flip(frame, 1)
134
135     # Got this from collect-data.py
136     # Coordinates of the ROI
137     x1 = int(0.5*frame.shape[1])
138     y1 = 10
139     x2 = frame.shape[1]-10
140     y2 = int(0.5*frame.shape[1])
141     # Drawing the ROI
142     # The increment/decrement by 1 is to compensate for the bounding box
143     cv2.rectangle(frame, (x1-1, y1-1), (x2+1, y2+1), (255,0,0), 1)
144     # Extracting the ROI
145     roi = frame[y1:y2, x1:x2]
146
147     # Resizing the ROI so it can be fed to the model for prediction
148     roi = cv2.resize(roi, (64, 64))
149     roi = cv2.cvtColor(roi, cv2.COLOR_BGR2GRAY)
150     _, test_image = cv2.threshold(roi, 120, 255, cv2.THRESH_BINARY)
151     cv2.imshow("test", test_image)
152     # Batch of 1
153     result = model.predict(test_image.reshape(1, 64, 64, 1))
154     prediction = {'ZERO': result[0][0],
155                  'ONE': result[0][1],
156                  'TWO': result[0][2],
157                  'THREE': result[0][3],
158                  'FOUR': result[0][4],
159                  'FIVE': result[0][5]}
160     # Sorting based on top prediction
161
162     'FOUR': result[0][4],
163     'FIVE': result[0][5]}
164     # Sorting based on top prediction
165     prediction = sorted(prediction.items(), key=operator.itemgetter(1), reverse=True)
166
167     # Displaying the predictions
168     cv2.putText(frame, prediction[0][0], (10, 120), cv2.FONT_HERSHEY_PLAIN, 1, (0,255,255), 1)
169     cv2.imshow("Frame", frame)
170
171     #loading an image
172     image1=cv2.imread(file_path)
173     if prediction[0][0]=='TWO':
174         print("Flip : 2 - gesture")
175         img = cv2.flip(image1, -1)
176         cv2.imshow('Flipped image',img)
177         key=cv2.waitKey(3000)
178         if (key & 0xFF) == ord("2"):
179             cv2.destroyAllWindows("Rectangle")
180
181     elif prediction[0][0]=='FIVE':
182         print("Rectangle: 5 - gesture")
183         cv2.rectangle(image1, (480, 170), (650, 420), 4444)
184         cv2.imshow("Rectangle", image1)
185
186         key=cv2.waitKey(3000)
187         if (key & 0xFF) == ord("5"):
188             cv2.destroyAllWindows("Rectangle")
189
190     elif prediction[0][0]=='THREE':
191         print("Blurred : 3 - gesture")
192         blurred = cv2.GaussianBlur(image1, (21, 21), 0)
193         cv2.imshow("Blurred", blurred)
194         key=cv2.waitKey(3000)
195         if (key & 0xFF) == ord("3"):
196             cv2.destroyAllWindows("Blurred")

```

```

182     key=cv2.waitKey(3000)
183     if (key & 0xFF) == ord("5"):
184         cv2.destroyAllWindows("Rectangle")
185
186     elif prediction[0][0]=='THREE':
187         print("Blurred : 3 - gesture")
188         blurred = cv2.GaussianBlur(image1, (21, 21), 0)
189         cv2.imshow("Blurred", blurred)
190         key=cv2.waitKey(3000)
191         if (key & 0xFF) == ord("3"):
192             cv2.destroyAllWindows("Blurred")
193
194     elif prediction[0][0]=='FOUR':
195         print("400x400 : 4 - gesture")
196         resized = cv2.resize(image1, (400, 400))
197         cv2.imshow("Fixed Resizing", resized)
198         key=cv2.waitKey(3000)
199         if (key & 0xFF) == ord("4"):
200             cv2.destroyAllWindows("Fixed Resizing")
201
202
203     interrupt = cv2.waitKey(10)
204     if interrupt & 0xFF == 27: # esc key
205         break
206
207
208     cap.release()
209     cv2.destroyAllWindows()
210     return render_template("home.html")
211
212
213 if __name__ == '__main__':
214     app.run(debug=True, port = 5000)

```

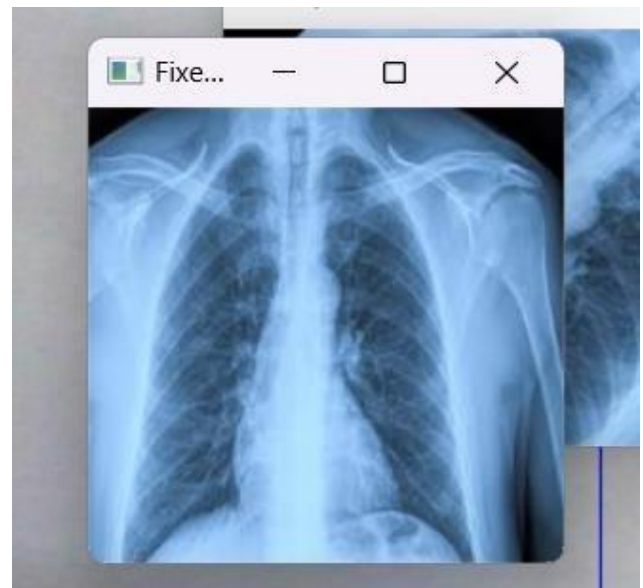
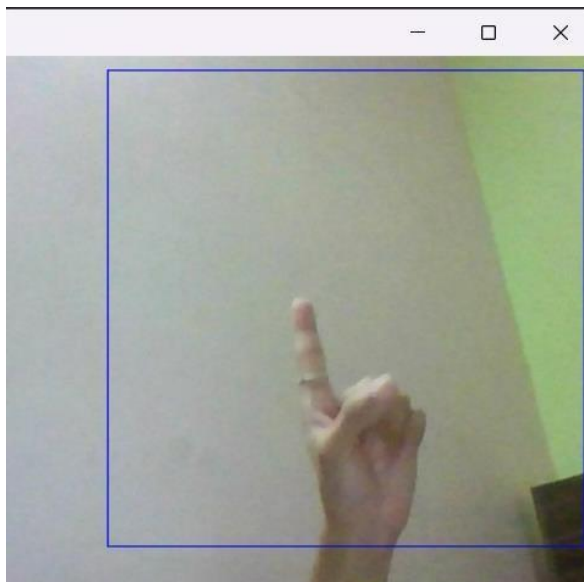
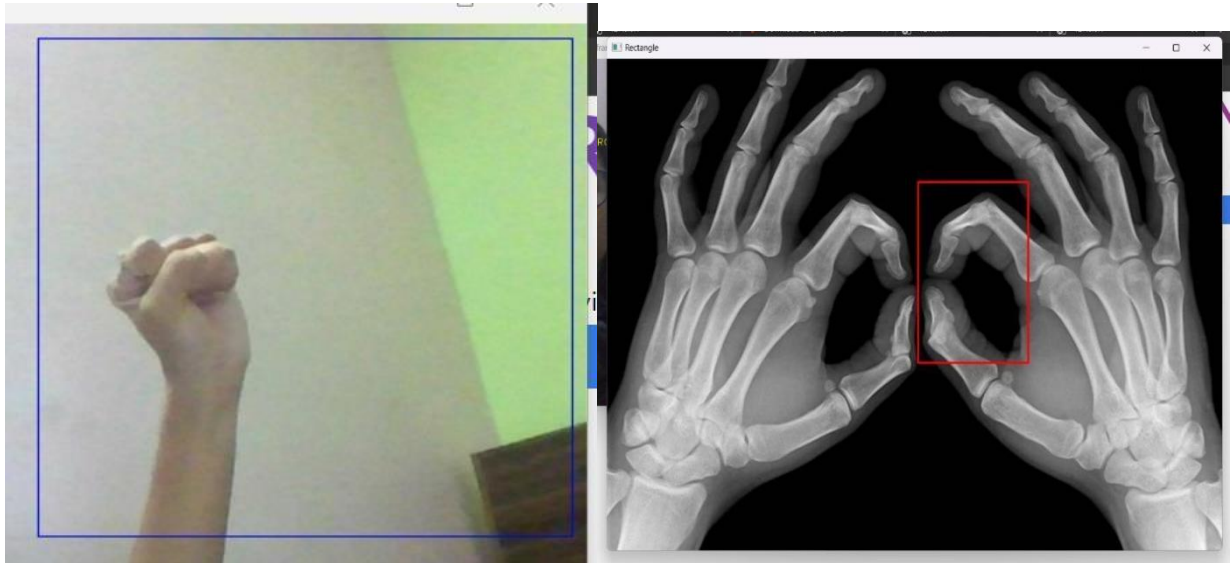
8.TESTING

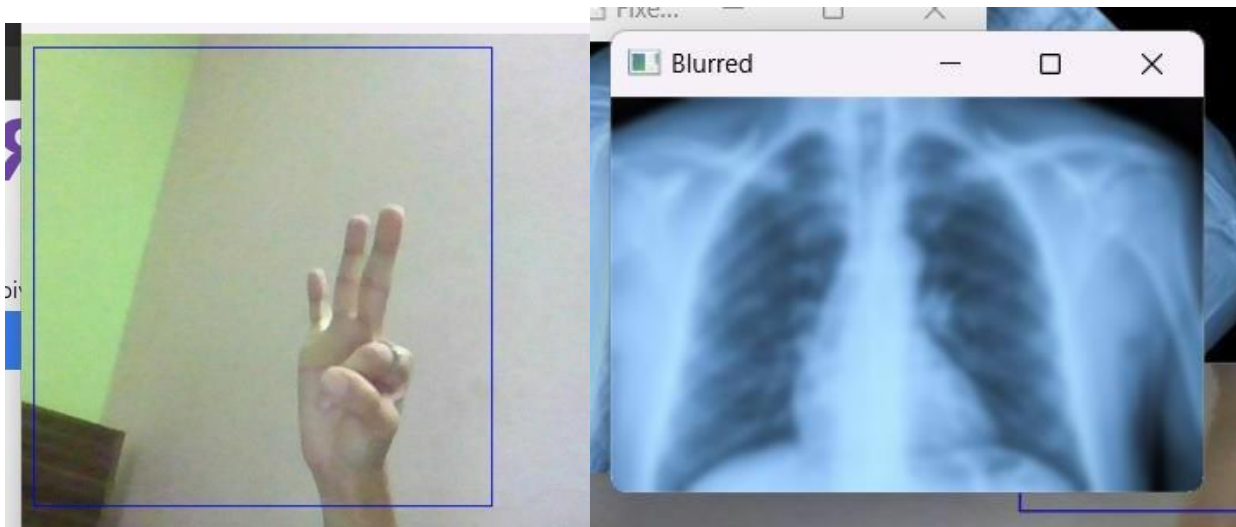
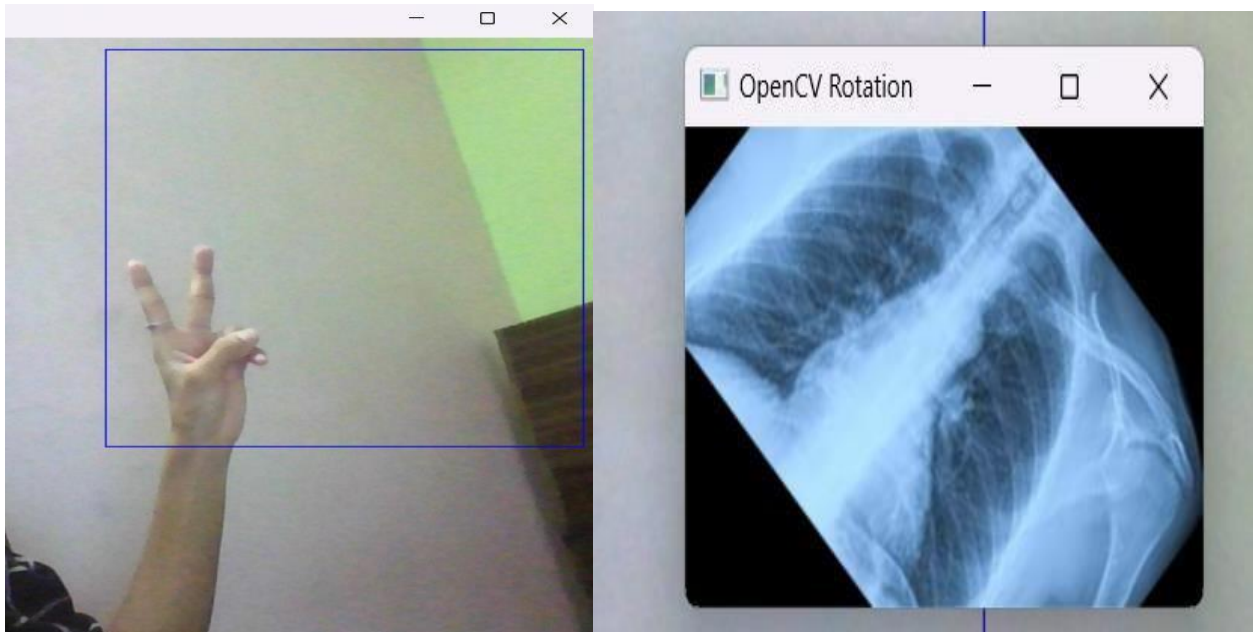
Model Performance Testing:

S.No.	Parameter	Values	Screenshot
1.	Model Summary	-	<pre> In [28]: model.summary() Model: "sequential" _____ Layer (type) Output Shape Param # ----- conv2d (Conv2D) (None, 62, 62, 32) 320 max_pooling2d (MaxPooling2D) (None, 31, 31, 32) 0 conv2d_1 (Conv2D) (None, 29, 29, 32) 9248 max_pooling2d_1 (MaxPooling2D) (None, 14, 14, 32) 0 flatten (Flatten) (None, 6272) 0 dense (Dense) (None, 512) 3211776 dense_1 (Dense) (None, 6) 3078 Total params: 3,224,422 Trainable params: 3,224,422 Non-trainable params: 0 </pre>
2.	Accuracy	Training Accuracy – 0.9882 Validation Accuracy – 0.9333	<pre> Epoch 25/25 196/198 [*****] - 13s 67ms/step - loss: 0.0271 - accuracy: 0.9882 - val_loss: 0.4289 - val_accuracy: 0.9333 </pre>

9.RESULT

Final findings (Output) of the project along with screenshots.





Through this project we found that we can maintain the sterility of an operation theater, etc by using hand based gesture tools to browse the images obtained.

10.ADVANTAGES & DISADVANTAGES

Advantages:

- Major advantage of this tool is that it helps to maintain the sterility of the environment.
- It is also easy to use and is quicker than the existing methods to browse images.
- It can also be performed even if the surgeon is a bit far away from the system, this helps to save time.
- The tool does not need the person using it to have an apparatus or any devices on them to use it. They can simply move their hands to browse through the images.

Disadvantages:

- The tool can be quite expensive as it requires cameras and other expensive devices to capture images and process it.

APPLICATIONS

- This hand based gesture tool developed can be mainly used in the medical industry to browse images without compromising the sterility.
- However it can also be used in different industries while presenting certain ideas, during meetings, and can be used by teachers while teaching.

11.CONCLUSION

In this project we developed a tool which recognises hand gestures and enables doctors to browse through radiology images using these gestures. This enables doctors and surgeons to maintain the sterility as they would not have to touch any mouse or keyboard to go through the images.

This tool is also easy to use and is quicker than the regular method of using mouse/keyboard.

It can be used regardless of the users location since they don't have to be in contact with any device.

It also does not require the user to have any device on them to use it.

Further this technology can be extended to other industries like it can be used by presenters, by teachers for show images in the classroom, etc.

12.FUTURE SCOPE

- The tool can be made quicker by increasing the recognition speed.
- More number of gestures can be added thereby increasing this tool's functionality and useability for different purposes.
- Tracking of both hands can be added to increase the set of commands. Voice commands can also be added to further increase the functionality.

REFERENCE

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4. S. Ioffe and C. Szegedy, "Batch normalization: Accelerating deep network training by reducing internal covariate shift," in International Conference on Machine Learning, 2015, pp. 448–456.
- 5.Juan Wachs, Helman Stern, Yael Edan, Michael Gillam, Jon Handler, Craig Feied, Mark Smith
- 6.Professor. Juan P. Wachs,
- 7.Professor. Benjamin Fritsch

13.Appendix

source code

<https://github.com/IBM-EPBL/IBM-Project-31294-1660198703>