Deep Learning Fundus Image Analysis for Early Detection of Diabetic Retinopathy

Team ID:PNT2022TMID23190

Model Building

Now it's time to build our model. Let's use the pre-trained model which is Xception, one of the convolution neural net (CNN) architectures which is considered as a very good model for Image classification. Deep understanding on the Xception model – Link is referred to in the prior knowledge section. Kindly refer to it before starting the model-building part.

Pre-Trained CNN Model As A Feature Extractor

For one of the models, we will use it as a simple feature extractor by freezing all the five convolution blocks to make sure their weights don't get updated after each epoch as we train our own model. Here, we have considered images of dimension (229,229,3). Also, we have assigned include top = False because we are using convolution layer for features extraction and wants to train fully connected layer for our images classification(since it is not the part of Imagenet dataset) Flatten layer flattens the input. Does not affect the batch size.

Adding Dense Layers

A dense layer is a deeply connected neural network layer. It is the most common and frequently used layer.Let us create a model object named model with inputs as xception.input and output as dense layer.The number of neurons in the Dense layer is the same as the number of classes in the training set. The neurons in the last Dense layer, use softmax activation to convert their outputs into respective probabilities. Understanding the model is a very important phase to properly use it for training and prediction purposes. Keras provides a simple method, summary to get the full information about the model and its layers.

```
Adding Dense Layers
In [16]: prediction = Dense( 5,activation ='softmax')(x)
In [17]: model = Model(inputs=xception.input,outputs=prediction)
In [18]: model.summary()
Model: "model"
        Model: "model"
        Layer (type) Output Shape Param # Connected to
                                    [(None, 299, 299, 3 0
         input_1 (InputLayer)
                                                                []
         block1_conv1 (Conv2D)
                                    (None, 149, 149, 32 864
                                                            ['input_1[0][0]']
         block1_conv1_bn (BatchNormaliz (None, 149, 149, 32 128
                                                             ['block1_conv1[0][0]']
         block1_conv1_act (Activation) (None, 149, 149, 32 0
                                                              ['block1_conv1_bn[0][0]']
         block1_conv2 (Conv2D)
                                   (None, 147, 147, 64 18432
                                                                ['block1_conv1_act[0][0]']
         block1_conv2_bn (BatchNormaliz (None, 147, 147, 64 256
                                                                ['block1_conv2[0][0]']
         block1_conv2_act (Activation) (None, 147, 147, 64 0
                                                                ['block1_conv2_bn[0][0]']
          block13_pool (MaxPooling2D) (None, 10, 10, 1024 0
                                                                   ['block13_sepconv2_bn[0][0]']
          batch_normalization_3 (BatchNo (None, 10, 10, 1024 4096
                                                                   ['conv2d_3[0][0]']
          add_11 (Add)
                                      (None, 10, 10, 1024 0
                                                                   ['block13_pool[0][0]',
                                                                     batch_normalization_3[0][0]']
          block14_sepconv1 (SeparableCon (None, 10, 10, 1536 1582080 ['add_11[0][0]']
          block14_sepconv1_bn (BatchNorm (None, 10, 10, 1536 6144
                                                                   ['block14_sepconv1[0][0]']
          block14_sepconv1_act (Activati (None, 10, 10, 1536 0
                                                                   ['block14_sepconv1_bn[0][0]']
          block14_sepconv2 (SeparableCon (None, 10, 10, 2048 3159552
                                                                   ['block14_sepconv1_act[0][0]']
          block14_sepconv2_bn (BatchNorm (None, 10, 10, 2048 8192 alization)
                                                                   ['block14_sepconv2[0][0]']
          block14_sepconv2_act (Activati (None, 10, 10, 2048 0
                                                                   ['block14_sepconv2_bn[0][0]']
                                   (None, 204800) 0
          flatten (Flatten)
                                                                   ['block14_sepconv2_act[0][0]']
          dense (Dense)
                                   (None, 5)
                                                      1024005
                                                                  ['flatten[0][0]']
         ______
          Trainable params: 1,024,005
         Non-trainable params: 20,861,480
```

Configure The Learning Process

The compilation is the final step in creating a model. Once the compilation is done, we can move on to the training phase. The loss function is used to find errors or deviations in the learning process. Keras requires a loss function during the model compilation process. Optimization is an important process that optimizes the input weights by comparing the prediction and the loss function. Here we are using adam optimizerMetrics are used to evaluate the performance of your model. It is similar to the loss function, but not used in the training process

Configuring The Learning Process

```
In [19]: model.compile(
    loss = 'categorical_crossentropy',
    optimizer = 'adam',
    metrics =['accuracy']
)
```

Train The Model

Now, let us train our model with our image dataset. The model is trained for 30 epochs and after every epoch, the current model state is saved if the model has the least loss encountered till that time. We can see that the training loss decreases in almost every epoch till 10 epochs and probably there is further scope to improve the model.

fit_generator functions used to train a deep learning neural network

Arguments:

steps_per_epoch: it specifies the total number of steps taken from the generator as soon as one epoch is finished and the next epoch has started. We can calculate the value of steps_per_epoch as the total number of samples in your dataset divided by the batch size.

Epochs: an integer and number of epochs we want to train our model for.

validation data can be either:

- an inputs and targets - a generator- an inputs, targets, and sample_weights list which can be used to evaluate the loss and metrics for any model after any epoch has ended.validation_steps: only if the validation_data is a generator then only this argumentcan be used. It specifies the total number of steps taken from the generator before it is stopped at every epoch and its value is calculated as the total number of validation data pointsin your dataset divided by the validation batch size.

```
Training The Model
In [20]: # fit the model
    r = model.fit_generator(
     training_set,
validation_data=test_set,
epochs=50,
     steps_per_epoch=len (training_set)//32,
validation_steps=len(test_set)//32
    /usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:8: UserWarning: `Model.fit_generator` is deprecated and will be removed in a future ver sion. Please use `Model.fit`, which supports generators.
    Epoch 2/50
    Epoch 3/50
    3/3 [=====
Epoch 4/50
        Epoch 8/50 - 10ss: 2.8408 - accuracy: 0.6667
    Epoch 10/50
```

Save The Model

The model is saved with .h5 extension as follows An H5 file is a data file saved in the Hierarchical Data Format (HDF). It contains multidimensional arrays of scientific data.

Saving the Model In [21]: model.save("Updated-xception-diabetic-retinopathy.h5")